Parameter 14

Thomas Roeper,Edwin Williams

An Introduction to the Lie Theory of One-parameter Groups Abraham Cohen, 1911

Optimal Input Signals for Parameter Estimation Ewaryst Rafajłowicz, 2022-03-07 The aim of this book is to provide methods and algorithms for the optimization of input signals so as to estimate parameters in systems described by PDE's as accurate as possible under given constraints. The optimality conditions have their background in the optimal experiment design theory for regression functions and in simple but useful results on the dependence of eigenvalues of partial differential operators on their parameters. Examples are provided that reveal sometimes intriguing geometry of spatiotemporal input signals and responses to them. An introduction to optimal experimental design for parameter estimation of regression functions is provided. The emphasis is on functions having a tensor product (Kronecker) structure that is compatible with eigenfunctions of many partial differential operators. New optimality conditions in the time domain and computational algorithms are derived for D-optimal input signals when parameters of ordinary differential equations are estimated. They are used as building blocks for constructing D-optimal spatio-temporal inputs for systems described by linear partial differential equations of the parabolic and hyperbolic types with constant parameters. Optimality conditions for spatially distributed signals are also obtained for equations of elliptic type in those cases where their eigenfunctions do not depend on unknown constant parameters. These conditions and the resulting algorithms are interesting in their own right and, moreover, they are second building blocks for optimality of spatio-temporal signals. A discussion of the generalizability and possible applications of the results obtained is presented.

One-Parameter Semigroups for Linear Evolution Equations Klaus-Jochen Engel, Rainer Nagel, 2006-04-06 This book explores the theory of strongly continuous one-parameter semigroups of linear operators. A special feature of the text is an unusually wide range of applications such as to ordinary and partial differential operators, to delay and Volterra equations, and to control theory. Also, the book places an emphasis on philosophical motivation and the historical background.

The Polysynthesis Parameter Mark C. Baker,1996-01-04 This book investigates in detail the grammar of polysynthetic languages--those with very complex verbal morphology. Baker argues that polysynthesis is more than an accidental collection of morphological processes; rather, it is a systematic way of representing predicate-argument relationships that is parallel to but distinct from the system used in languages like English. Having repercussions for many areas of syntax and related aspects of morphology and semantics, this argument results in a comprehensive picture of the grammar of polysynthetic languages. Baker draws on examples from Mohawk and certain languages of the American Southwest, Mesoamerica, Australia, and Siberia.

Control and Estimation of Distributed Parameter Systems Wolfgang Desch, F. Kappel, Karl Kunisch, 1994 A semigroup formulation of a nonlinear size-structured distributed rate population model.- Damage detection and characterization in smart material structures.- Optimality conditions for non-gualified parabolic control problems.- Convergence of trajectories for a controlled viscous Burgers' equation.- Optimality conditions for boundary control problems of parabolic type.-Pontryagin's principle for optimal control problems governed by semilinear elliptic equations.-Invariance of the Hamiltonian in control problems for semilinear parabolic distributed parameter systems.- Rate distribution modeling for structured heterogeneous populations.- A model for a twolayered plate with interfacial slip.- Numerical solution of a constrained control problem for a phase field model.- Uniform stabilizability of nonlinearly coupled Kirchhoff plate equations.- Boundary temperature control for thermally coupled Navier-Stokes equations.- Adaptive estimation of nonlinear distributed parameter systems.- Decay estimates for the wave equation with internal damping.- On the controllability of the rotation of a flexible arm.- Modeling and controllability of interconnected elastic membranes.- On feedback controls for dynamic networks of strings and beams and their numerical simulation.- Various relaxations in optimal control of distributed parameter systems.- Convergence of an SQP-method for a class of nonlinear parabolic boundary control problems.- Conditional stability in determination of densities of heat sources in a bounded domain.- Boundary stabilization of the Korteweg-de Vries equation.- Controllability of the linear

system of thermoelasticity: Dirichlet-Neumann boundary conditions.

Sliding Mode Control of Uncertain Parameter-Switching Hybrid Systems Ligang Wu, Peng Shi,Xiaojie Su,2014-07-14 In control theory, sliding mode control (SMC) is a nonlinear control method that alters the dynamics of a nonlinear system by application of a discontinuous control signal that forces the system to slide along a cross-section of the system's normal behaviour. In recent years, SMC has been successfully applied to a wide variety of practical engineering systems including robot manipulators, aircraft, underwater vehicles, spacecraft, flexible space structures, electrical motors, power systems, and automotive engines. Sliding Mode Control of Uncertain Parameter-Switching Hybrid Systems addresses the increasing demand for developing SMC technologies and comprehensively presents the new, state-of-the-art sliding mode control methodologies for uncertain parameter-switching hybrid systems. It establishes a unified framework for SMC of Markovian jump singular systems and proposes new SMC methodologies based on the analysis results. A series of problems are solved with new approaches for analysis and synthesis of switched hybrid systems, including stability analysis and stabilization, dynamic output feedback control, and SMC. A set of newly developed techniques (e.g. average dwell time, piecewise Lyapunov function, parameter-dependent Lyapunov function, cone complementary linearization) are exploited to handle the emerging mathematical/computational challenges. Key features: Covers new concepts, new models and new methodologies with theoretical significance in system analysis and control synthesis Includes recent advances in Markovian jump systems, switched hybrid systems, singular systems, stochastic systems and time-delay systems Includes solved problems Introduces advanced techniques Sliding Mode Control of Uncertain Parameter-Switching Hybrid Systems is a comprehensive reference for researchers and practitioners working in control engineering, system sciences and applied mathematics, and is also a useful source of information for senior undergraduate and graduates studying in these areas.

Parameter Theory and Linguistic Change Charlotte Galves, Sonia Cyrino, Ruth Lopes, Filomena Sandalo, Juanito Avelar, 2012-11-01 This book focuses on some of the most important issues in historical syntax. In a series of close examinations of languages from old Egyptian to modern Afrikaans, leading scholars present new work on Afro-Asiatic, Latin and Romance, Germanic, Albanian, Celtic, Indo-Iranian, and Japanese. The book revolves around the linked themes of parametric theory and the dynamics of language change. The former is a key element in the search for explanatory adequacy in historical syntax: if the notion of imperfect learning, for example, explains a large element of grammatical change, it is vital to understand how parameters are set in language acquisition and how they might have been set differently in previous generations. The authors test particular hypotheses against data from different times and places with the aim of understanding the relationship between language variation and the dynamics of change. Is it possible, for example, to reconcile the unidirectionality of change predominantly expressed in the phenomenon of grammaticalization, with the multidirectionality predicted by generativist approaches? In terms of the richness of the data it examines, the broad range of languages it discusses, and the use it makes of linguistic theory this is an outstanding book, not least in the contribution it makes to the understanding of language change.

Inverse Problem Theory and Methods for Model Parameter Estimation Albert Tarantola,2005-01-01 This book proposes a general approach to the basic difficulties appearing in the resolution of inverse problems.

Parameter Setting Thomas Roeper,Edwin Williams,2012-12-06 In May 1985 the University of Massachusetts held the first conference on the parameter setting model of grammar and acquisition. The conference was conceived in the belief that there is a new possibility of tightly connecting grammatical studies and language acquisition studies, and that this new possibility has grown out of the new generation of ideas about the relation of Universal Grammar to the grammar of particular languages. The papers in this volume are all concerned in one way or another with the 'parametric' model of grammar, and with its role in explaining the acquisition of language. Before summarizing the accompanying papers, I would like to sketch the intellectual background of these new ideas. It

has long been the acknowledged goal of grammatical theorists to explicate the relation between the experience of the child and the knowledge of the adult. Somehow, the child selects a unique grammar (by assumption) compatible with a random partially unreliable sample of some language. In the earliest work in generative grammar, starting with Chomsky's Aspects, and extending to such works as Jackendoffs Lexicalist Syntax (1977), the model of this account was the formal evaluation metric, accompanied by a general rule writing system. The model of acquisition was the following: the child composed a grammar by writing rules in the rule writing system, under the constraint that the rules must be compatible with the data, and that the grammar must be the one most highly valued by the evaluation metric.

Identification and System Parameter Estimation 1982 G. A. Bekey, G. N. Saridis, 2016-06-06 Identification and System Parameter Estimation 1982 covers the proceedings of the Sixth International Federation of Automatic Control (IFAC) Symposium. The book also serves as a tribute to Dr. Naum S. Rajbman. The text covers issues concerning identification and estimation, such as increasing interrelationships between identification/estimation and other aspects of system theory, including control theory, signal processing, experimental design, numerical mathematics, pattern recognition, and information theory. The book also provides coverage regarding the application and problems faced by several engineering and scientific fields that use identification and estimation, such as biological systems, traffic control, geophysics, aeronautics, robotics, economics, and power systems. Researchers from all scientific fields will find this book a great reference material, since it presents topics that concern various disciplines.

<u>Parameter Study of Insertion Conditions for Lunar Missions Including Various Trajectory</u> <u>Considerations</u> Carl R. Huss, Harold A. Hamer, John P. Mayer, 1961 A parameter study of lunar ballistic trajectories was made by using the restricted two-body orbit equations and assuming that a sphere of influence exists about the earth and about the moon such that the attraction of each body on the vehicle can be treated separately. The results of the study are summarized in the form of charts from which approximate insertion conditions (velocity, radius vector or altitude, flight-path angle, and lead angle or firing time) can be selected for specific lunar missions. Data are included on conditions at perilune, requirements for return to earth, and trip times.

Linear Parameter-Varying System Identification Paulo Lopes dos Santos,2012 This review volume reports the state-of-the-art in Linear Parameter Varying (LPV) system identification. Written by world renowned researchers, the book contains twelve chapters, focusing on the most recent LPV identification methods for both discrete-time and continuous-time models, using different approaches such as optimization methods for input/output LPV models Identification, set membership methods, optimization methods and subspace methods for state-space LPV models identification and orthonormal basis functions methods. Since there is a strong connection between LPV systems, hybrid switching systems and piecewise affine models, identification of hybrid switching systems and piecewise affine systems will be considered as well.

Robust Control and Linear Parameter Varying Approaches Olivier Sename, Peter Gaspar, József Bokor, 2013-02-01 Vehicles are complex systems (non-linear, multi-variable) where the abundance of embedded controllers should ensure better security. This book aims at emphasizing the interest and potential of Linear Parameter Varying methods within the framework of vehicle dynamics, e.g. proposed control-oriented model, complex enough to handle some system non linearities but still simple for control or observer design, take into account the adaptability of the vehicle's response to driving situations, to the driver request and/or to the road sollicitations, manage interactions between various actuators to optimize the dynamic behavior of vehicles. This book results from the 32th International Summer School in Automatic that held in Grenoble, France, in September 2011, where recent methods (based on robust control and LPV technics), then applied to the control of vehicle dynamics, have been presented. After some theoretical background and a view on some recent works on LPV approaches (for modelling, analysis, control, observation and diagnosis), the main emphasis is put on road vehicles but some illustrations are concerned with railway, aerospace and underwater vehicles. The main objective of the book is to demonstrate the value of this approach for controlling the dynamic behavior of vehicles. It presents, in a rm way, background and new results on LPV methods and their application to vehicle dynamics.

NASA Workshop on Distributed Parameter Modeling and Control of Flexible Aerospace Systems , 1994

Scientific and Technical Aerospace Reports ,1985

<u>Hydraulic Parameter Identification</u> Luc C. Lebbe, 2012-12-06 Hydraulic parameter identification is a crucial step in hydrogeological investigations. The book proposes a unique and generalized interpretation method for single and multiple pumping tests made in groundwater reservoirs with layered heterogeneity and with or without lateral anisotropy. This method eliminates the drawbacks of the numerous and frequently applied interpretation methods. The book also presents an introduction to inverse modeling, resulting in optimal parameter values with their joint confidence region and the corresponding residuals. Cross sections through this multidimensional region elucidate the relation between the shape of this region and some statistical parameters describing the reliability of the identified parameters. This method is demonstrated by means of five pumping or recharge tests.

Stabilized Adaptive Forgetting in Recursive Parameter Estimation J.T. Milek,1995 Civilian Power Reactor Program: Addendum. Core parameter studies for selected reactor types U.S. Atomic Energy Commission,1960

Parameter Extraction and Complex Nonlinear Transistor Models Gunter Kompa, 2019-12-31 All model parameters are fundamentally coupled together, so that directly measured individual parameters, although widely used and accepted, may initially only serve as good estimates. This comprehensive resource presents all aspects concerning the modeling of semiconductor field-effect device parameters based on gallium-arsenide (GaAs) and gallium nitride (GaN) technology. Metal-semiconductor field-effect transistors (MESFETs), high electron mobility transistors (HEMTs) and heterojunction bipolar transistors (HBTs), their structures and functions, and existing transistor models are also classified. The Shockley model is presented in order to give insight into semiconductor field-effect transistor (FET) device physics and explain the relationship between geometric and material parameters and device performance. Extraction of trapping and thermal time constants is discussed. A special section is devoted to standard nonlinear FET models applied to large-signal measurements, including static-/pulsed-DC and single-/two-tone stimulation. High power measurement setups for signal waveform measurement, wideband source-/load-pull measurement (including envelope source-/load pull) are also included, along with high-power intermodulation distortion (IMD) measurement setup (including envelope load-pull). Written by a world-renowned expert in the field, this book is the first to cover of all aspects of semiconductor FET device modeling in a single volume.

Parameter Estimation in Reliability and Life Span Models A Clifford Cohen,Betty Jones Whitten,2020-07-26 Offers an applications-oriented treatment of parameter estimation from both complete and censored samples; contains notations, simplified formats for estimates, graphical techniques, and numerous tables and charts allowing users to calculate estimates and analyze sample data quickly and easily. Anno

Decoding Parameter 14: Revealing the Captivating Potential of Verbal Expression

In an era characterized by interconnectedness and an insatiable thirst for knowledge, the captivating potential of verbal expression has emerged as a formidable force. Its power to evoke sentiments, stimulate introspection, and incite profound transformations is genuinely awe-inspiring. Within the pages of "**Parameter 14**," a mesmerizing literary creation penned with a celebrated wordsmith, readers set about an enlightening odyssey, unraveling the intricate significance of language and its enduring effect on our lives. In this appraisal, we shall explore the book is central themes, evaluate its distinctive writing style, and gauge its pervasive influence on the hearts and

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