Controlss 142

United States. Congress. House. Committee on the District of Columbia

Firearms Control Regulations Act of 1975 (Council Act No. 1-142) United States. Congress. House. Committee on the District of Columbia, 1976

Fault-Tolerant Attitude Control of Spacecraft Qinglei Hu,Bing Xiao,Bo Li,Youmin Zhang,2021-06-09 Fault-Tolerant Attitude Control of Spacecraft presents the fundamentals of spacecraft fault-tolerant attitude control systems, along with the most recent research and advanced, nonlinear control techniques. This book gives researchers a self-contained guide to the complex tasks of envisaging, designing, implementing and experimenting by presenting designs for integrated modeling, dynamics, fault-tolerant attitude control, and fault reconstruction for spacecraft. Specifically, the book gives a full literature review and presents preliminaries and mathematical models, robust fault-tolerant attitude control, fault-tolerant attitude control with actuator saturation, velocity-free fault tolerant attitude control, finite-time fault-tolerant attitude tracking control, and active fault-tolerant attitude contour. Finally, the book looks at the future of this interesting topic, offering readers a one-stop solution for those working on fault-tolerant attitude control for spacecraft. Presents the fundamentals of fault-tolerant attitude control systems for spacecraft in one practical solution Gives the latest research and thinking on nonlinear attitude control, fault tolerant control, and reliable attitude control Brings together concepts in fault control theory, fault diagnosis, and attitude control for spacecraft Covers advances in theory, technological aspects, and applications in spacecraft Presents detailed numerical and simulation results to assist engineers Offers a clear, systematic reference on fault-tolerant control and attitude control for spacecraft

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Industrial Electricity and Motor Controls, Second Edition Rex Miller, Mark Miller, 2013-08-24 The most complete, up-to-date guide to industrial electricity This practical resource offers comprehensive coverage of the entire electrical field and its equipment, including troubleshooting and repair. You'll learn how to read and interpret schematics and drawings and safely work with all electrical components and systems on the jobsite. The Second Edition features a new chapter on robotics, a new 16-page color insert, and information on the latest codes, regulations, and devices. Filled with more than 650 photos and diagrams, study questions, review problems, and detailed answers, this career-building tool helps you enhance your electrical and electronics expertise and apply it effectively in the workplace. Industrial Electricity and Motor Controls, Second Edition covers: Tools and

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Financial Systems at the Crossroads Wing Thye Woo, Yingli Pan, Jeffrey D Sachs, Junhui Qian, 2014-04-16 Financial Systems at the Crossroads: Lessons for China is written by leading financial experts to study the causes of financial disasters internationally. The research team is drawn from the global research networks of three leading universities: the Antai College of Economics and Management at Shanghai Jiao Tong University, the School of Economics at Fudan University, and the Earth Institute at Columbia University. This review volume identifies the regulatory framework to guide the emergence of efficient financial institutions that are prudent; and to specify the required institutional mechanisms to prevent and resolve systemic collapse. It examines the specific circumstances of China to come up with a comprehensive agenda to reform China's financial sector. It provides indepth analysis of China's financial industry to show its future evolution and offers lessons for developing a financial system that is efficient, innovative and resilient. Contents: Analytical Overview: Mobilizing China's Financial Sector Efficiently and Safely for Sustaining Economic Transformation and Strengthening Global Financial Stability (Yingli Pan, Jeffrey D Sachs, Wing Thye Woo and John Qi Zhu)Understanding the Important Lessons from the International Experience: Wall Street Lawlessness (Jeffrey D Sachs) Systemic Lack of Prudence in Wealthy Nations: Avoiding the Dark Side of Financial Development (Peter Boone and Simon Johnson)Lessons from the Financial Liberalization in the Nordic Countries in the 1980s (Seppo Honkapohja) Asian Financial Markets and Financial Internationalization in China (Kiyohiko G Nishimura) Tokyo's Ultimately Failed Bid for First Tier International Financial Centre Status: Why Did It Fall Short and What are the Lessons for Shanghai? (Huw McKay)Designing the Right Financial System for China: The Great Accommodation: Chinese Central Banking in the New Millennium (Junhui Qian and Wing Thye Woo) The Structural Friction in China's Banking System: Causes, Measurement and Solutions (Hongzhong Liu and Tai Qin)Credit Rationing, Bank Bailouts, and the Deleterious Impact of Credit: Evidence from China (Jean Louis Arcand) The Options for Reforming the Renminbi Exchange Rate Regime (Xinru Wu, Yingli Pan, Zhichao Zhang, Jing Nie and Si Zhou) The Internationalization of the Renminbi is in Accordance with China's National Interests and Global Responsibilities (Yingli Pan, Yingfeng Xu and Jun Wu)Reforming China's Rural Financial Market (Xi Zhu) Readership: Graduate students and researchers in financial industry, financial analysts and China-watchers. Keywords: Financial Systems; Chinese Economy; US Economy; Financial Development; Nordic Countries; China Central Banking; Renminbi Exchange RateKey Features: Written by leading financial experts from the global research networks of Shanghai Jiao Tong University, Fudan University and Columbia UniversityStudies the causes of financial disasters internationally Examines the specific circumstances of China to come up with a comprehensive agenda to reform China's financial sectorProvides in-depth analysis of China's financial industry to

show its future evolutionOffers lessons for developing a financial system that is efficient, innovative and resilient

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Lyapunov-Based Control of Robotic Systems Aman Behal, Warren Dixon, Darren M. Dawson, Bin Xian, 2009-12-17 Lyapunov-Based Control of Robotic Systems describes nonlinear control design solutions for problems that arise from robots required to interact with and manipulate their environments. Since most practical scenarios require the design of nonlinear controllers to work around uncertainty and measurement-related issues, the authors use Lyapunov's direc

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