Virtual Driver

JL Elias

Adaptive Cooperation between Driver and Assistant System Frédéric Holzmann,2007-12-03 One of the next challenges in vehicular technology field is to improve drastically the road safety. Current developments are focusing on both vehicle platform and diverse assistance systems. This book presents a new engineering approach based on lean vehicle architecture ready for the drive-by-wire technology. Based on a cognitive functionality split, execution and command levels are detailed. The execution level centralized over the stability control performs the motion vector coming from the command level. At this level the driver generates a motion vector which is continuously monitored by a virtual co-pilot. The integration of assistance systems in a safety relevant multi-agent system is presented here to provide first an adequate feedback to the driver to let him recover a dangerous situation. Robust strategies are also presented for the intervention phase once the command vehicle has to be optimized to stay within the safety envelope.

Driving in Virtual Reality Björn Blissing,2020-09-02 In the last decades, there has been a substantial increase in the development of complex active safety systems for automotive vehicles. These systems need to be tested for verification and validation to ensure that the system intervenes in the correct situations using the correct measures. There are multiple methods available to perform such testing. Software-in-the-loop and hardware-in-the-loop testing offer effective driverless testing. Other methods increase the fidelity by including human drivers, such as driving simulators and experiments performed at test tracks. This thesis examines vehicle-in-the-loop testing, an innovative method where the driver of a real vehicle wears a head-mounted display that displays virtual targets. This method combines the benefits of driving simulators with the benefits of using a real vehicle on a test track. Driving simulators offer repeatability, safety, and the possibility of complex interactions

between actors. In contrast, the real vehicle provides the correct vehicle dynamics and motion feedback. There is a need to know how the technology behind the method might influence the results from vehicle-in-the-loop testing. Two techniques for vehicle-in-the-loop systems are studied. The first involves video-see through head-mounted displays, where the focus of the research is on the effects of visual latency on driving behavior. The results show that lateral driving behavior changes with added latency, but longitudinal behavior appears unaffected. The second system uses an opaque head-mounted display in an entirely virtual world. The research shows that this solution changes speed perception and results in a significant degradation in performance of tasks dependent on visual acuity. This research presents results that are relevant to consider when developing vehicle-in-the-loop platforms. The results are also applicable when choosing scenarios for this test method. Dagens fordon innehåller fler och fler säkerhetssystem. Vissa av dessa system ger varningar i potentiellt kritiska trafiksituationer. Det finns också mer komplexa system som tillfälligt kan ta kontroll över fordonet för att förhindra en olycka eller åtminstone mildra effekterna. Komplexiteten hos dessa system innebär att man måste genomföra omfattande tester. Både för att se att systemen reagerar vid rätt tidpunkt, men också för att se att valet av åtgärd är korrekt. Det finns många olika sätt att testa dessa system. Man börjar vanligtvis med simuleringar av programvara och hårdvara. Därefter kan systemet introduceras i ett fordon för att se vilka effekter systemet har när det interagerar med en riktig förare. Att utföra tester med förare ställer dock höga säkerhetskrav, och det är ofta svårt att samordna komplexa trafiksituationer på en testbana. Traditionellt har körsimulatorer varit ett naturligt alternativ eftersom de kan utföra komplexa scenarier i en säker miljö. Denna avhandling undersöker en testmetod där man utrustar föraren med en virtual reality-display. Genom att presentera omvärlden med hjälp av virtual reality, så kan man

genomföra scenarion som tidigare varit omöjliga på en testbana. Det kan dock finnas inbyggda begränsningar i virtual reality tekniken som kan påverka körbeteendet. Det är därför viktigt att hitta och kvantifiera dessa effekter för att kunna lita på resultaten från testmetoden. Att känna till dessa effekter på körbeteendet dessutom kan hjälpa till att avgöra vilka typer av scenarier som är lämpade för denna testmetod. Det är också viktig information för att avgöra var man bör fokusera den tekniska utvecklingen av testutrustningen.

Advanced Driver Intention Inference Yang Xing,Chen Lv,Dongpu Cao,2020-03-15 Advanced Driver Intention Inference: Theory and Design describes one of the most important function for future ADAS, namely, the driver intention inference. The book contains the state-of-art knowledge on the construction of driver intention inference system, providing a better understanding on how the human driver intention mechanism will contribute to a more naturalistic on-board decision system for automated vehicles. Features examples of using machine learning/deep learning to build industry products Depicts future trends for driver behavior detection and driver intention inference Discuss traffic context perception techniques that predict driver intentions such as Lidar and GPS

Cybersickness in Virtual Reality Versus Augmented Reality Kay Marie Stanney,Ben D. Lawson,Charles McMaster Oman,2021-12-06

Visual Perception Modelling for Intelligent Virtual Driver Agents in Synthetic Driving Simulation Abdulai Don Dumbuya,2003

Smart Driver Training Simulation Wolf Dieter Käppler,2008-07-02 As technology improves, so does the sophistication of driving simulators. Meanwhile, as the volume of traffic increases, simulators are being seen as a real addition to the driving trainer's armory. This book explains the basics of education and training using simulators and their ability to

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improve safety on our streets. Käppler shows that they can be used for documentation, data acquisition, data analysis, evaluation, and modeling as well as for simple training.

Machine Learning and Embedded Computing in Advanced Driver Assistance Systems (ADAS) John Ball ,Bo Tang ,2019-10-01 This book contains the latest research on machine learning and embedded computing in advanced driver assistance systems (ADAS). It encompasses research in detection, tracking, LiDAR and camera processing, ethics, and communications. Several new datasets are also provided for future research work. Researchers and others interested in these topics will find important advances contained in this book.

Powertrain Instrumentation and Test Systems Michael Paulweber,Klaus Lebert,2016-06-17 The book deals with the increasingly complex test systems for powertrain components and systems giving an overview of the diverse types of test beds for all components of an advanced powertrain focusing on specific topics such as instrumentation, control, simulation, hardware-in-the-loop, automation or test facility management. This book is intended for powertrain (component) development engineers, test bed planners, test bed operators and beginners.

Virtual, Augmented and Mixed Reality: Interaction, Navigation, Visualization, Embodiment, and Simulation Jessie Y.C. Chen,Gino Fragomeni,2018-07-10 This two-volume set LNCS 10909 and 10910 constitutes the refereed proceedings of the 10th International Conference on Virtual, Augmented and Mixed Reality, VAMR 2018, held as part of HCI International 2018 in Las Vegas, NV, USA. HCII 2018 received a total of 4346 submissions, of which 1171 papers and 160 posters were accepted for publication after a careful reviewing process. The 65 papers presented in this volume were organized in topical sections named: interaction, navigation, and visualization in VAMR; embodiment, communication, and collaboration in VAMR; education, training, and simulation; VAMR in psychotherapy,

exercising, and health; virtual reality for cultural heritage, entertainment, and games; industrial and military applications.

Modelling Driver Behaviour in Automotive Environments Carlo Cacciabue,2010-04-28 This book presents a general overview of the various factors that contribute to modelling human behaviour in automotive environments. This long-awaited volume, written by world experts in the field, presents state-of-the-art research and case studies. It will be invaluable reading for professional practitioners graduate students, researchers and alike.

Driver Behaviour and Training: Dr. Lisa Dorn,2017-07-05 Research on driver behaviour over the past two decades has clearly demonstrated that the goals and motivations a driver brings to the driving task are important determinants for driver behaviour. The importance of this work is underlined by statistics: WHO figures show that road accidents are predicted to be the number three cause of death and injury by 2020 (currently more than 20 million deaths and injuries p.a.). The objective of this second edition, and of the conference on which it is based, is to describe and discuss recent advances in the study of driving behaviour and driver training. It bridges the gap between practitioners in road safety, and theoreticians investigating driving behaviour, from a number of different perspectives and related disciplines. A major focus is to consider how driver training needs to be adapted, to take into account driver characteristics, goals and motivations, in order to raise awareness of how these may contribute to unsafe driving behaviour, and to go on to promote the development of driver training courses that considers all the skills that are essential for road safety. As well as setting out new approaches to driver training methodology based on many years of empirical research on driver behaviour, the contributing road safety researchers and professionals consider the impact of human factors in the design of driver training as well as the traditional skills-based approach.

Readership includes road safety researchers from a variety of different academic backgrounds, senior practitioners in the field of driver training from regulatory authorities and professional driver training organizations such as the police service, and private and public sector personnel who are concerned with improving road safety.

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   Towards a Common Software/Hardware Methodology for Future Advanced Driver Assistance Systems Guillermo Payá-Vayá,Holger Blume,2022-09-01 The European research project DESERVE (DEvelopment platform for Safe and Efficient dRiVE, 2012-2015) had the aim of designing and developing a platform tool to cope with the continuously increasing complexity and the simultaneous need to reduce cost for future embedded Advanced Driver Assistance Systems (ADAS). For this purpose, the DESERVE platform profits from cross-domain software reuse, standardization of automotive software component interfaces, and easy but safety-compliant integration of heterogeneous modules. This enables the development of a new generation of ADAS applications, which challengingly combine different functions, sensors, actuators, hardware platforms, and Human Machine Interfaces (HMI). This book presents the different results of the DESERVE project concerning the ADAS development platform, test case functions, and validation and evaluation of different approaches. The reader is invited to substantiate the content of this book with the deliverables published during the DESERVE project. Technical topics discussed in this book include:Modern ADAS development platforms;Design space exploration;Driving modelling;Video-based and Radar-based ADAS functions;HMI for ADAS;Vehicle-hardware-in-the-loop validation systems

Road Vehicle Automation 3 Gereon Meyer,Sven Beiker,2016-07-01 This edited book comprises papers about the impacts, benefits and challenges of connected and automated cars. It is the third volume of the LNMOB series dealing with Road Vehicle Automation. The book comprises contributions from researchers, industry practitioners and policy makers, covering perspectives from the U.S., Europe and Japan. It is based on the Automated Vehicles Symposium 2015 which was jointly organized by the Association of Unmanned Vehicle Systems International (AUVSI) and the Transportation Research Board (TRB) in Ann Arbor, Michigan, in July 2015. The topical spectrum includes, but is not limited to, public sector activities, human factors, ethical and business aspects, energy and technological perspectives, vehicle systems and transportation infrastructure. This book is an indispensable source of information for academic researchers, industrial engineers and policy makers interested in the topic of road vehicle automation.

Virtual Reality and Augmented Reality Jernej Barbic,Mirabelle D'Cruz,Marc Erich Latoschik,Mel Slater,Patrick Bourdot,2017-12-06 This book constitutes the refereed proceedings of the 14th International Conference on Virtual Reality and Augmented Reality, EuroVR 2017, held in Laval, France, in December 2017. The 10 full papers and 2 short papers presented were carefully reviewed and selected from 36 submissions. The papers are organized in four topical sections: interaction models and user studies, visual and haptic real-time rendering, perception and cognition, and rehabilitation and safety.

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Modern Development and Challenges in Virtual Reality

Mamata Rath,Tusharkanta Samal,2023-10-18 Virtual reality (VR) is one of the technologies with the highest expectations for future growth. By creating realistic images and objects, a VR environment gives the user the impression that they are completely engrossed in their surroundings. VR applications that go beyond leisure, tourism, and marketing are now in high demand and thus the technology must be user-friendly and economical. The major technology firms are already striving to create headsets that do not require cables and that allow for high-definition viewing. Artificial intelligence is being used to control VR headsets that have far more powerful CPUs. The new standard will also offer some intriguing capabilities, like the ability to connect huge user communities and additional gadgets. Customers will be able to get photos in real-time in corporate settings, almost as if they were seeing them with their own eyes. This book presents a comprehensive overview of VR applications in medicine, electric vehicles, aviation, architecture, and more.

Official Gazette of the United States Patent and Trademark Office ,2001

Determination of a characteristic driver modell Gerald Bonengel,2013-01-24 Scientific Study from the year 2012 in the subject Engineering - Automotive Engineering, , language: English, abstract: There are various concepts to reduce the noxious emission in the area of mobility. For example actually the expansion of the electro-mobility, via hybrid drive to the point of fuel made of biomass is explored. To assess these concepts the operating conditions and operating areas of the vehicles in day to day use are crucial, as the concepts differ explicitly with regard to the range, power and driving characteristics. To be able to select the proper concept a driver's model has to be defined, as the economical key data's are in a strong correlation of this model. Via an everyday operating behavior performance data's can be created, which can be used in "Hardware in the Loop" (HIL) engine test bench simulations. The analyzed rides will be

characterized with time-weighted and motor units as well as the allocations of the accessed engine torques and the engine rpm. driver's model; Keywords: Hardware in the Loop; driving characteristics

Virtual Reality Therapy for Anxiety Elizabeth McMahon,Debra Boeldt,2021-11-25 Practical, down to earth, clearly written, and easy for therapists to understand and apply, Virtual Reality Therapy for Anxiety is a useful guide for any clinician treating anxiety, regardless of setting (in-office or via telehealth), theoretical orientation, or level of training. Written by an experienced psychologist who has used multiple VR systems since 2010, it's the only up to date, clinically informed, evidence-based training manual available. Easy-to-understand concepts and diagrams explain anxiety and its treatment, and the book incorporates research findings and clinical expertise. VRT is described step by step with multiple case examples, and an extended case-vignette chapter presents a session-by-session treatment protocol of a complex case with transcript excerpts. Key findings and quotations from research are also presented. After completing the guide, therapists and other mental health professionals will understand the unique clinical benefits of VR, be prepared to use VR in therapy comfortably and effectively either in the office or remotely, and will have expertise in a new, needed, and empirically validated treatment for a common clinical problem.

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