

Sliding

Giorgio Bartolini, Leonid Fridman, Alessandro Pisano, Elio Usai

Sliding Mode Control Andrzej Bartoszewicz, 2011-04-11 The main objective of this monograph is to present a broad range of well worked out, recent application studies as well as theoretical contributions in the field of sliding mode control system analysis and design. The contributions presented here include new theoretical developments as well as successful applications of variable structure controllers primarily in the field of power electronics, electric drives and motion steering systems. They enrich the current state of the art, and motivate and encourage new ideas and solutions in the sliding mode control area.

Sliding Patricia Whitehouse, 2004 Presents simple hands-on experiments that demonstrate the properties that make sliding easier or more difficult.

Sliding Mode Control in Electro-mechanical Systems Vadim Utkin, Juergen Guldner, Ma Shijun, 1999-04-22 Sliding Mode Control (SMC) is gaining increasing importance as a universal design tool for the robust control of linear and nonlinear systems. The strengths of sliding mode controllers result from the ease and flexibility of the methodology for their design and implementation. They provide inherent order reduction, direct incorporation of robustness against system uncertainties and disturbances, and an implicit stability proof. They also allow for the design of high performance control systems at low costs. SMC is particularly useful for electro-mechanical systems because of its discontinuous structure. In fact, since the hardware of many electro-mechanical systems (such as electric motors) prescribes discontinuous inputs, SMC has become the natural choice for direct implementation. The book is intended primarily for engineers and establishes an

interdisciplinary bridge between control science, electrical and mechanical engineering.

Discrete-time Sliding Mode Control B. Bandyopadhyay, S. Janardhanan, 2005-10-17

Sliding mode control is a simple and yet robust control technique, where the system states are made to confine to a selected subset. With the increasing use of computers and discrete-time samplers in controller implementation in the recent past, discrete-time systems and computer based control have become important topics. This monograph presents an output feedback sliding mode control philosophy which can be applied to almost all controllable and observable systems, while at the same time being simple enough as not to tax the computer too much. It is shown that the solution can be found in the synergy of the multirate output sampling concept and the concept of discrete-time sliding mode control.

Sliding Mode Control In Engineering Wilfrid Perruquetti, Jean-Pierre

Barbot, 2002-01-29 Provides comprehensive coverage of the most recent developments in the theory of non-Archimedean pseudo-differential equations and its application to stochastics and mathematical physics--offering current methods of construction for stochastic processes in the field of p-adic numbers and related structures. Develops a new theory for parabolic equations

Sliding in the Snow Melissa Dymock, 2015-07-14 Grab your gloves and snow boots, it's time for an adventure in a frozen wonderland—right in your own backyard! Here are fun twists on classic winter pastimes, like sledding and making snowmen. Learn how to design your own backyard winter Olympics. Things to make and do include: • Saving a Snowflake Forever • Wacky Snow Creations • Making Your Own Snowshoes • Making a Snowball

Launcher • Sidewalk Curling • Skijoring • And more! MELISSA DYMOCK is a ski instructor for children ages 3 to 12 and has mastered getting six 5-year-olds dressed and on skis before any of them have to go the bathroom again (most days). For more outdoor adventures, find her at weekendwomanwarrior.com. She lives in Utah. FRAN LEE has a MFA from the School of the Art Institute of Chicago in Printmaking and a freelance graphic designer and illustrator (www.coatimundistudios.com). She has designed and illustrated many children's activity books and has been the Art Director for Chicago Review Press and Creative Director for Hello Kitty (Sanrio Inc.). She lives in Portland, Oregon, with her husband.

Modern Sliding Mode Control Theory Giorgio Bartolini, Leonid Fridman, Alessandro Pisano, Elio Usai, 2008-04-24 This concise book covers modern sliding mode control theory. The authors identify key contributions defining the theoretical and applicative state-of-the-art of the sliding mode control theory and the most promising trends of the ongoing research activities.

Who's Hatching? Charles Reasoner, 1994 Readers slide open the pages to discover the surprise baby hiding inside each egg.

Sliding Base Structures Hong-Song Hu, 2023-08-11 This open access book is an efficient and economic approach for mitigating the seismic damage of low-rise buildings. This book presents various aspects of SB structures, including their fundamentals, dynamic analysis procedures, seismic response characteristics, design methods, and practical applications. It contains a comprehensive study on the influence of various structural and ground motion characteristics on the responses of SB structures, which is

particularly helpful for the readers to fully understand the behavior of SB structures. Researchers and engineers in the field of structural engineering and earthquake engineering will benefit from this book.

Sliding-Mode Fuzzy Controllers Mojtaba Ahmadiéh Khanesar, Okyay Kaynak, Erdal Kayacan, 2021-07-21 This book addresses some of the challenges suffered by the well-known and robust sliding-mode control paradigm. The authors show how the fusion of fuzzy systems with sliding-mode controllers can alleviate some of these problems and promote applicability. Fuzzy systems used as soft switches eliminate high-frequency signal oscillations and can substantially lower the noise sensitivity of sliding-mode controllers. The amount of a priori knowledge required concerning the nominal structure and parameters of a nonlinear system is also shown to be much reduced by exploiting the general function-approximation property of fuzzy systems so as to use them as identifiers. The main features of this book include: • a review of various existing structures of sliding-mode fuzzy control; • a guide to the fundamental mathematics of sliding-mode fuzzy controllers and their stability analysis; • state-of-the-art procedures for the design of a sliding-mode fuzzy controller; • source codes including MATLAB® and Simulink® codes illustrating the simulation of these controllers, particularly the adaptive controllers; • a short bibliography for each chapter for readers interested in learning more on a particular subject; and • illustrative examples and simulation results to support the main claims made in the text. Academic researchers and graduate students interested in the control of nonlinear systems and particularly those working in sliding-mode controller design will find this book a valuable source of comparative information on existing controllers and

ideas for the development of new ones.

Recent Advances in Sliding Modes: From Control to Intelligent Mechatronics Xinghuo Yu, Mehmet Önder Efe, 2015-04-10 This volume is dedicated to Professor Okay Kaynak to commemorate his life time impactful research and scholarly achievements and outstanding services to profession. The 21 invited chapters have been written by leading researchers who, in the past, have had association with Professor Kaynak as either his students and associates or colleagues and collaborators. The focal theme of the volume is the Sliding Modes covering a broad scope of topics from theoretical investigations to their significant applications from Control to Intelligent Mechatronics.

Sliding Mode Control Using Novel Sliding Surfaces B. Bandyopadhyay, Fulwani Deepak, Kyung-Soo Kim, 2009-10-14

After a survey paper by Utkin in the late 1970s, sliding mode control methodologies emerged as an effective tool to tackle uncertainty and disturbances which are inevitable in most of the practical systems. Sliding mode control is a particular class of variable structure control which was introduced by Emel'yanov and his colleagues. The design paradigms of sliding mode control has now become a mature design technique for the design of robust controller of uncertain system. In sliding mode technique, the state trajectory of the system is constrained on a chosen manifold (or within some neighborhood thereof) by an appropriate control action. This manifold is also called a switching surface or a sliding surface. During sliding mode, system dynamics is governed by the chosen manifold which results in a well celebrated invariance property towards certain classes of disturbance and model mismatches. The purpose of this monograph is to give a different dimension to sl-

ing surface design to achieve high performance of the system. Design of the switching surface is vital because the closed loop dynamics is governed by the parameters of the sliding surface. Therefore sliding surface should be - signed to meet the closed loop specifications. Many systems demand high performance with robustness. To address this issue of achieving high performance with robustness, we propose nonlinear surfaces for different classes of systems. The nonlinear surface is designed such that it changes the system's closed-loop damping ratio from its initial low value to a final high value.

Applications of Sliding Mode Control Nabil Derbel, Jawhar Ghommam, Quanmin Zhu, 2016-10-14 This book presents essential studies and applications in the context of sliding mode control, highlighting the latest findings from interdisciplinary theoretical studies, ranging from computational algorithm development to representative applications. Readers will learn how to easily tailor the techniques to accommodate their ad hoc applications. To make the content as accessible as possible, the book employs a clear route in each paper, moving from background to motivation, to quantitative development (equations), and lastly to case studies/illustrations/tutorials (simulations, experiences, curves, tables, etc.). Though primarily intended for graduate students, professors and researchers from related fields, the book will also benefit engineers and scientists from industry.

Variable-Structure Systems and Sliding-Mode Control Martin Steinberger, Martin Horn, Leonid Fridman, 2020-02-10 The book covers the latest theoretical results and sophisticated applications in the field of variable-structure systems and sliding-mode control. This book is divided into four parts. Part I discusses new higher-order sliding-

mode algorithms, including new homogeneous controllers and differentiators. Part II then explores properties of continuous sliding-mode algorithms, such as saturated feedback control, reaching time, and orbital stability. Part III is focused on the usage of variable-structure systems (VSS) controllers for solving other control problems, for example unmatched disturbances. Finally, Part IV discusses applications of VSS; these include applications within power electronics and vehicle platooning. Variable-structure Systems and Sliding-Mode Control will be of interest to academic researchers, students and practising engineers.

Sliding Modes after the first Decade of the 21st Century Leonid Fridman, Jaime Moreno, Rafael Iriarte, 2011-09-28 The book presents the newest results of the major world research groups working in the area of Variable Structure Systems and Sliding Mode Control (VSS/SMC). The research activity of these groups is coordinated by the IEEE Technical Committee on Variable Structure Systems (VSS) and Sliding Modes (SM). The presented results include the reports of the research groups collaborating in a framework of the Unión European Union – México project of Fondo de Cooperación Internacional en Ciencia y Tecnología (FONCICyT) 93302 titled Automatization and Monitoring of Energy Production Processes via Sliding Mode Control. The book starts with the overview of the sliding mode control concepts and algorithms that were developed and discussed in the last two decades The research papers are combined in three sections: Part I: VSS and SM Algorithms and their Analysis Part II: SMC Design Part III: Applications of VSS and SMC The book will be of interests of engineers, researchers and graduate students working in the area of the control systems design. Novel mathematical theories and engineering

concepts of control systems are rigorously discussed and supported by numerous applications to practical tasks.

Sliding-Mode Control of PEM Fuel Cells Cristian Kunusch, Paul Puleston, Miguel Mayosky, 2012-01-14 Sliding-mode Control of PEM Fuel Cells demonstrates the application of higher-order sliding-mode control to PEMFC dynamics showing the advantages of sliding modes. The book introduces the theory of fuel cells and sliding-mode control. It contextualises PEMFCs both in terms of their development and within the hydrogen economy and today's energy production situation as a whole. It then discusses fuel-cell operation principles, the mathematical background of high-order sliding-mode control and to a feasibility study for the use of sliding modes in the control of an automotive fuel stack. Part II presents experimental results of sliding-mode-control application to laboratory fuel cells and deals with subsystem-based modelling, detailed design, and observability and controllability. Simulation results are contrasted with empirical data and performance, robustness and implementation issues are treated in depth. Possibilities for future research are also laid out.

Sliding Mode Control Using MATLAB Jinkun Liu, 2017-05-25 Sliding Mode Control Using MATLAB provides many sliding mode controller design examples, along with simulation examples and MATLAB® programs. Following the review of sliding mode control, the book includes sliding mode control for continuous systems, robust adaptive sliding mode control, sliding mode control for underactuated systems, backstepping, and dynamic surface sliding mode control, sliding mode control based on filter and observer, sliding mode control for discrete systems, fuzzy sliding mode control, neural network

sliding mode control, and sliding mode control for robot manipulators. The contents of each chapter are independent, providing readers with information they can use for their own needs. It is suitable for the readers who work on mechanical and electronic engineering, electrical automation engineering, etc., and can also be used as a teaching reference for universities. Provides many sliding mode controller design examples to help readers solve their research and design problems Includes various, implementable, robust sliding mode control design solutions from engineering applications Provides the simulation examples and MATLAB programs for each sliding mode control algorithm

Sliding Mode Controllers for Power Electronic Converters Axaykumar Mehta, Brijesh Naik, 2018-12-13 This book proposes a proportional integral type sliding function, which does not facilitate the finite reaching and hence the responses of the load voltage results in an exponential steady state. To facilitate finite time reaching, it also presents the new Integral Sliding Mode Control with Finite Time Reaching (ISMCFTR). The book also extends the application of the proposed controller to another type of PEC, the DC-DC Boost converter, and also proposes the PI type sliding surface for the Zeta converter, which is non-inverting type Buck Boost converter. An important source of practical implementations, it presents practical implementations as simulation and experimental results to demonstrate the efficacy of the converter.

Sliding Mode Control of Switching Power Converters Siew-Chong Tan, Yuk-Ming Lai, Chi-Kong Tse, 2018-09-03 Sliding Mode Control of Switching Power Converters: Techniques and Implementation is perhaps the first in-depth account of how sliding mode controllers can be practically engineered to optimize control of power converters. A

complete understanding of this process is timely and necessary, as the electronics industry moves toward the use of renewable energy sources and widely varying loads that can be adequately supported only by power converters using nonlinear controllers. Of the various advanced control methods used to handle the complex requirements of power conversion systems, sliding mode control (SMC) has been most widely investigated and proved to be a more feasible alternative than fuzzy and adaptive control for existing and future power converters. Bridging the gap between power electronics and control theory, this book employs a top-down instructional approach to discuss traditional and modern SMC techniques. Covering everything from equations to analog implantation, it: Provides a comprehensive general overview of SMC principles and methods Offers advanced readers a systematic exposition of the mathematical machineries and design principles relevant to construction of SMC, then introduces newer approaches Demonstrates the practical implementation and supporting design rules of SMC, based on analog circuits Promotes an appreciation of general nonlinear control by presenting it from a practical perspective and using familiar engineering terminology With specialized coverage of modeling and implementation that is useful to students and professionals in electrical and electronic engineering, this book clarifies SMC principles and their application to power converters. Making the material equally accessible to all readers, whether their background is in analog circuit design, power electronics, or control engineering, the authors—experienced researchers in their own right—elegantly and practically relate theory, application, and mathematical concepts and models to corresponding industrial targets.

Sliding Mode Control Methodology in the Applications of Industrial Power

Systems Jianxing Liu, Yabin Gao, Yunfei Yin, Jiahui Wang, Wensheng Luo, Guanghui Sun, 2019-10-23 This book presents recent advanced techniques in sliding mode control and observer design for industrial power systems, focusing on their applications in polymer electrolyte membrane fuel cells and power converters. Readers will find not only valuable new fault detection and isolation techniques based on sliding mode control and observers, but also a number of robust control and estimation methodologies combined with fuzzy neural networks and extended state observer methods. The book also provides necessary experimental and simulation examples for proton exchange membrane fuel cell systems and power converter systems. Given its scope, it offers a valuable resource for undergraduate and graduate students, academics, scientists and engineers who are working in the field.

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