

Encoder

Barry G. Haskell, Atul Puri, Arun N. Netravali

Nonlinear Digital Encoders for Data Communications Calin Vladeanu, Safwan El Assad, 2014-03-06 This book presents digital encoders for data communications. After an introduction on data communications and different sequences, the authors present the trellis-coded modulation schemes using nonlinear digital encoders. The book contains many numerical examples that complete the description of the analyzed schemes. Also, some performance simulation results are provided. Appendixes include demonstrations for the mathematical apparatus used throughout the book and some Matlab/Simulink source files used to run the simulations. Therefore, students can easily understand the concepts presented in the book and to simulate the schemes.

Introduction to Convolutional Codes with Applications Ajay Dholakia, 2012-12-06 Introduction to Convolutional Codes with Applications is an introduction to the basic concepts of convolutional codes, their structure and classification, various error correction and decoding techniques for convolutionally encoded data, and some of the most common applications. The definition and representations, distance properties, and important classes of convolutional codes are also discussed in detail. The book provides the first comprehensive description of table-driven correction and decoding of convolutionally encoded data. Complete examples of Viterbi, sequential, and majority-logic decoding technique are also included, allowing a quick comparison among the different decoding approaches. Introduction to Convolutional Codes with Applications summarizes the research of the last two decades on applications of convolutional codes in hybrid ARQ protocols. A new classification allows a natural way of studying the underlying concepts of hybrid schemes and accommodates all of the new research. A novel application of fast decodable invertible convolutional codes for lost packet recovery in high speed networks is described. This opens the door for using convolutional coding for error recovery in high speed networks. Practicing communications, electronics, and networking engineers who want to get a better grasp of the underlying concepts of convolutional coding and its applications will greatly benefit by the simple and concise style of explanation. An up-to-date bibliography of over 300 papers is included. Also suitable for use as a textbook or a reference text in an advanced course on coding theory with emphasis on convolutional codes.

VLSI Design for Video Coding Youn-Long Steve Lin, Chao-Yang Kao, Hung-Chih Kuo, Jian-Wen Chen, 2009-12-29 High definition video requires substantial compression in order to be transmitted or stored economically. Advances in video coding standards from MPEG-1, MPEG-2, MPEG-4 to H.264/AVC have provided ever increasing coding efficiency, at the expense of great computational complexity which can only be delivered through massively parallel processing. This book will present VLSI architectural design and chip implementation for high definition H.264/AVC video encoding, using a state-of-the-art video application, with complete VLSI prototype, via FPGA/ASIC. It will serve as an invaluable reference for anyone interested in VLSI design and high-level (EDA) synthesis for video.

Medical Coding in the Real World and VLab Encoder Bundle 3e, AC234021VB Roberts, 2021-12-31

A Logarithmic Encoder for Binary Word Compression Joseph A. Sciulli, United States. National Aeronautics and Space Administration, 1967

The Performance of 31 and 127 Bit Elastic Surface Wave Encoders and Decoders Peter A. DeVito, Paul H. Carr, Thomas L. Szabo, 1972

Design of a Parallel Encoder/decoder for the Hamming Code, Using ROM. Stanford University Stanford Electronics Laboratories. Digital Systems Laboratory, 1972 ROM implementation of logic circuits which have a large number of inputs is generally considered unwise. However, in the design of an encoder/decoder for the Hamming code, ROM implementation is found to yield many advantages over SSI and MSI implementation. There is a one-to-one correspondence between the partition of H matrix into submatrices and the partition of the set of the inputs to the encoder into subsets of the inputs to the ROM modules. Hence, several methods of partitioning the H matrix for the Hamming code are devised. The resulting

ROM implementation is shown to save package count compared with other implementations. However, at the present state of technology, there is a trade-off between speed and package count. In the applications where speed is of the utmost importance, the SSI implementation using ECL logic is the most attractive. The disadvantage of ROM in speed should diminish in the near future when semiconductor memory technology will progress to the point where the slow DTL/TTL gates in the input buffer, the address decoder, and the output buffer of ROM, can be replaced by faster gates.

The Encoder Raymond Khoury, Miguel Lalor, 2016-06 A thrilling quest to discover the fabled treasure of the Templars!

Artificial Intelligence and Digitalization for Sustainable Development Bereket H. Woldegiorgis, Kibret Mequanint, Mekuanint A.

Bitew, Teketay B. Beza, Abdulkerim M. Yibre, 2023-03-18 This proceedings, ICAST 2022, constitutes the refereed post-conference proceedings of the 10th International Conference on Advancement of Science and Technology, ICAST 2022, which took place in Bahir Dar, Ethiopia, in November 2022. The 17 revised full papers and one short paper were carefully reviewed and selected from 174 submissions. The papers present economic and technologic developments in modern societies related to important issues such as digitization, energy transformation, impact on national economy, and its recent advancements.

Digital Video: An Introduction to MPEG-2 Barry G. Haskell, Atul Puri, Arun N. Netravali, 2007-05-08 Digital Video offers comprehensive coverage of the MPEG-2 audio/visual digital compression standard. The treatment includes the specifics needed to implement an MPEG-2 Decoder, including the syntax and semantics of the coded bitstreams. Since the MPEG-2 Encoders are not specified by the standard, and are actually closely held secrets of many vendors, the book only outlines the fundamentals of encoder design and algorithm optimization.

Joint Source Channel Coding Using Arithmetic Codes Dongsheng Bi, Michael Ward Hoffman, Khalid Sayood, 2010 Proposes a new way of looking at arithmetic codes with forbidden symbols. If a limit is imposed on the maximum value of a key parameter in the encoder, this modified arithmetic encoder can also be modelled as a finite state machine and the code generated can be treated as a variable-length trellis code. The number of states used can be reduced and techniques used for decoding convolutional codes can be applied directly on the trellis.

Encoderpro.com Expert Ingenix, 2004-01-01

Computer Controlled Systems G. Perdikaris, 1991-09-30 The primary objective of the book is to provide advanced undergraduate or first-year graduate engineering students with a self-contained presentation of the principles fundamental to the analysis, design and implementation of computer controlled systems. The material is also suitable for self-study by practicing engineers and is intended to follow a first course in either linear systems analysis or control systems. A secondary objective of the book is to provide engineering and/or computer science audiences with the material for a junior/senior-level course in modern systems analysis. Chapters 2, 3, 4, and 5 have been designed with this purpose in mind. The emphasis in such a course is to develop the mathematical tools and methods suitable for the analysis and design of real-time systems such as digital filters. Thus, engineers and/or computer scientists who know how to program computers can understand the mathematics relevant to the issue of what it is they are programming. This is especially important for those who may work in engineering and scientific environments where, for instance, programming difference equations for real-time applications is becoming increasingly common. A background in linear algebra should be an adequate prerequisite for the systems analysis course. Chapter 1 of the book presents a brief introduction to computer controlled systems. It describes the general issues and terminology relevant to the analysis, design, and implementation of such systems.

Passive Encoder for Range Knobs William H. Schiffbauer, 1983

Entropy Coders of the H.264/AVC Standard Xiaohua Tian, Thinh M. Le, Yong Lian, 2010-10-17 This book presents a collection of algorithms and VLSI architectures of entropy (or statistical) codecs of recent video compression standards, with focus on the H.264/AVC standard. For any visual

data compression scheme, there exists a combination of two, or all of the following three stages: spatial, temporal, and statistical compression. General readers are first introduced with the various algorithms of the statistical coders. The VLSI implementations are also reviewed and discussed. Readers with limited hardware design background are also introduced with a design methodology starting from performance-complexity analyses to software/hardware co-simulation. A typical design of the Contextbased Adaptive Binary Arithmetic Coding (CABAC) encoder is also presented in details. To support System-on-Chip design environment, the CABAC design is wrapped with a SoC-based Wishbone system bus interface.

Punctured Convolutional Encoders David John Rowe,1997

Terrain Aided Localisation of Autonomous Vehicles in Unstructured Environments Rajmohan Madhavan,2003-03-08 This thesis is concerned with the theoretical and practical development of reliable and robust localisation algorithms for autonomous land vehicles operating at high speeds in unstructured, expansive and harsh environments. Localisation is the ability of a vehicle to determine its position and orientation within an operating environment. The need for such a localisation system is motivated by the requirement of developing autonomous vehicles in applications such as mining, agriculture and cargo handling. The main drivers in these applications are for safety, efficiency and productivity. The approach taken to the localisation problem in this thesis guarantees that the safety and reliability requirements imposed by such applications are achieved. The approach also aims to minimise the engineering or modification of the environment, such as adding artificial landmarks or other infrastructure. This is a key driver in the practical implementation of a localisation algorithm. In pursuit of these objectives, this thesis makes the following principal contributions: 1. The development of an Iterative Closest Point - Extended Kalman Filter (ICP-EKF) algorithm - a map-based iconic algorithm that utilises measurements from a scanning laser rangefinder to achieve localisation. The ICP-EKF algorithm entails the development of a map-building algorithm. The main attraction of the map-based localisation algorithm is that it works directly on sensed data and thus does not require extraction and matching of features. It also explicitly takes into account the uncertainty associated with measurements and has the ability to include measurements from a variety of different sensors. 2. The development and implementation of an entropy-based metric to evaluate the information content of measurements. This metric facilitates the augmentation of landmarks to the ICP-EKF algorithm thus guaranteeing reliable and robust localisation. 3. The development and adaptation of a view-invariant Curvature Scale Space (CSS) landmark extraction algorithm. The algorithm is sufficiently robust to sensor noise and is capable of reliably detecting and extracting landmarks that are naturally present in the environment from laser rangefinder scans. 4. The integration of the information metric and the CSS and ICP-EKF algorithms to arrive at a unified localisation framework that uses measurements from both artificial and natural landmarks, combined with dead-reckoning sensors, to deliver reliable vehicle position estimates. The localisation framework developed is sufficiently generic to be used on a variety of other autonomous land vehicle systems. This is demonstrated by its implementation using field data collected from three different trials on three different vehicles. The first trial was carried out on a four-wheel drive vehicle in an underground mine tunnel. The second trial was conducted on a Load-Haul-Dump (LHD) truck in a test tunnel constructed to emulate an underground mine. The estimates of the proposed localisation algorithms are compared to the ground truth provided by an artificial landmark-based localisation algorithm that uses bearing measurements from a laser. To demonstrate the feasibility and reliability of both the natural landmark extraction and localisation algorithms, these are also implemented on a utility vehicle in an outdoor area within the University's campus. The results demonstrate the robustness of the proposed localisation algorithms in producing reliable and accurate position estimates for autonomous vehicles operating in a variety of unstructured domains.

AI Embedded Assurance for Cyber Systems Cliff Wang,S.S. Iyengar,Kun Sun,2024-01-13 The rapid growth and reliance on cyber systems have permeated our society, government, and military which is demonstrated in this book. The authors discuss how AI-powered cyber systems are

designed to protect against cyber threats and ensure the security and reliability of digital systems using artificial intelligence (AI) technologies. As AI becomes more integrated into various aspects of our lives, the need for reliable and trustworthy AI systems becomes increasingly important. This book is an introduction to all of the above-mentioned areas in the context of AI Embedded Assurance for Cyber Systems. This book has three themes. First, the AI/ML for digital forensics theme focuses on developing AI and ML powered forensic tools, techniques, software, and hardware. Second, the AI/ML for cyber physical system theme describes that AI/ML plays an enabling role to boost the development of cyber physical systems (CPS), especially in strengthening the security and privacy of CPS. Third, the AI/ML for cyber analysis theme focuses on using AI/ML to analyze tons of data in a timely manner and identify many complex threat patterns. This book is designed for undergraduates, graduate students in computer science and researchers in an interdisciplinary area of cyber forensics and AI embedded security applications. It is also useful for practitioners who would like to adopt AIs to solve cyber security problems.

Trellis and Turbo Coding Christian B. Schlegel, Lance C. Perez, 2015-08-19 This new edition has been extensively revised to reflect the progress in error control coding over the past few years. Over 60% of the material has been completely reworked, and 30% of the material is original. Convolutional, turbo, and low density parity-check (LDPC) coding and polar codes in a unified framework Advanced research-related developments such as spatial coupling A focus on algorithmic and implementation aspects of error control coding

The Last Templar - Volume 1 - The Encoder Raymond Khoury, 2016-05-06T00:00:00+02:00 Acre, 1291. The last Crusader city in the Holy Land is about to fall. Two Knights Templar, obeying the grandmaster's orders, manage to escape the invading Muslim army on the order's last ship. New York City, nowadays. During the unveiling of an exhibition of some of the Vatican's treasures, four men disguised as Templars attack the Metropolitan Museum and steal several artefacts, including a centuries-old decoder - a loss that horrifies the Church.

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Encoder Introduction

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