

Multi Xl

Dongsheng Xu, XiaolanWei, Hui Ding, Hongqiong Bin

Designing Multi-target Drugs J. Richard Morphy, C. John Harris, 2012 This is the first book to pull together studies and reviews from cutting edge authors who work in the emerging and exciting field of multi-targeted drug discovery.

Recent Advances in Evolutionary Multi-objective Optimization Slim Bechikh, Rituparna Datta, Abhishek Gupta, 2016-08-09 This book covers the most recent advances in the field of evolutionary multiobjective optimization. With the aim of drawing the attention of up-and coming scientists towards exciting prospects at the forefront of computational intelligence, the authors have made an effort to ensure that the ideas conveyed herein are accessible to the widest audience. The book begins with a summary of the basic concepts in multi-objective optimization. This is followed by brief discussions on various algorithms that have been proposed over the years for solving such problems, ranging from classical (mathematical) approaches to sophisticated evolutionary ones that are capable of seamlessly tackling practical challenges such as non-convexity, multi-modality, the presence of multiple constraints, etc. Thereafter, some of the key emerging aspects that are likely to shape future research directions in the field are presented. These include: optimization in dynamic environments, multi-objective bilevel programming, handling high dimensionality under many objectives, and evolutionary multitasking. In addition to theory and methodology, this book describes several real-world applications from various domains, which will expose the readers to the versatility of evolutionary multi-objective optimization.

Distributed Coordination of Multi-agent Networks Wei Ren, Yongcan Cao, 2010-11-30 Distributed Coordination of Multi-agent Networks introduces

problems, models, and issues such as collective periodic motion coordination, collective tracking with a dynamic leader, and containment control with multiple leaders, and explores ideas for their solution. Solving these problems extends the existing application domains of multi-agent networks; for example, collective periodic motion coordination is appropriate for applications involving repetitive movements, collective tracking guarantees tracking of a dynamic leader by multiple followers in the presence of reduced interaction and partial measurements, and containment control enables maneuvering of multiple followers by multiple leaders.

Fuzzy and Multi-Level Decision Making: Soft Computing Approaches Chi-Bin Cheng, Hsu-Shih Shih, E. Stanley Lee, 2018-12-14 This book offers a comprehensive overview of cutting-edge approaches for decision-making in hierarchical organizations. It presents soft-computing-based techniques, including fuzzy sets, neural networks, genetic algorithms and particle swarm optimization, and shows how these approaches can be effectively used to deal with problems typical of this kind of organization. After introducing the main classical approaches applied to multiple-level programming, the book describes a set of soft-computing techniques, demonstrating their advantages in providing more efficient solutions to hierarchical decision-making problems compared to the classical methods. Based on the book *Fuzzy and Multi-Level Decision Making* (Springer, 2001) by Lee E.S and Shih, H., this second edition has been expanded to include the most recent findings and methods and a broader spectrum of soft computing approaches. All the algorithms are presented in detail, together with a wealth of practical examples and solutions to real-world problems, providing students, researchers and professionals with a timely, practice-oriented reference

guide to the area of interactive fuzzy decision making, multi-level programming and hierarchical optimization.

Learning Representation for Multi-View Data Analysis Zhengming Ding, Handong Zhao, Yun Fu, 2018-12-06 This book equips readers to handle complex multi-view data representation, centered around several major visual applications, sharing many tips and insights through a unified learning framework. This framework is able to model most existing multi-view learning and domain adaptation, enriching readers' understanding from their similarity, and differences based on data organization and problem settings, as well as the research goal. A comprehensive review exhaustively provides the key recent research on multi-view data analysis, i.e., multi-view clustering, multi-view classification, zero-shot learning, and domain adaption. More practical challenges in multi-view data analysis are discussed including incomplete, unbalanced and large-scale multi-view learning. Learning Representation for Multi-View Data Analysis covers a wide range of applications in the research fields of big data, human-centered computing, pattern recognition, digital marketing, web mining, and computer vision.

Multi-Layer Potentials and Boundary Problems Irina Mitrea, Marius Mitrea, 2013-01-05 Many phenomena in engineering and mathematical physics can be modeled by means of boundary value problems for a certain elliptic differential operator in a given domain. When the differential operator under discussion is of second order a variety of tools are available for dealing with such problems, including boundary integral methods, variational methods, harmonic measure techniques, and methods based on classical harmonic analysis. When the differential operator is of higher-order (as is the case, e.g., with anisotropic plate bending when one deals with a fourth order

operator) only a few options could be successfully implemented. In the 1970s Alberto Calderón, one of the founders of the modern theory of Singular Integral Operators, advocated the use of layer potentials for the treatment of higher-order elliptic boundary value problems. The present monograph represents the first systematic treatment based on this approach. This research monograph lays, for the first time, the mathematical foundation aimed at solving boundary value problems for higher-order elliptic operators in non-smooth domains using the layer potential method and addresses a comprehensive range of topics, dealing with elliptic boundary value problems in non-smooth domains including layer potentials, jump relations, non-tangential maximal function estimates, multi-traces and extensions, boundary value problems with data in Whitney-Lebesgue spaces, Whitney-Besov spaces, Whitney-Sobolev-based Lebesgue spaces, Whitney-Triebel-Lizorkin spaces, Whitney-Sobolev-based Hardy spaces, Whitney-BMO and Whitney-VMO spaces.

Uniform Tire Quality Grading ,1986

Microsoft SQL Server 2012 Analysis Services Alberto Ferrari,Marco Russo,Chris Webb,2012-07-15 Build agile and responsive Business Intelligence solutions Analyze tabular data using the BI Semantic Model (BISM) in Microsoft SQL Server 2012 Analysis Services—and discover a simpler method for creating corporate-level BI solutions. Led by three BI experts, you'll learn how to build, deploy, and query a BISM tabular model with step-by-step guides, examples, and best practices. This hands-on book shows you how the tabular model's in-memory database enables you to perform rapid analytics—whether you're a professional BI developer new to Analysis Services or familiar with its multidimensional model. Discover how to: Determine when

a tabular or multidimensional model is right for your project Build a tabular model using SQL Server Data Tools in Microsoft Visual Studio 2010 Integrate data from multiple sources into a single, coherent view of company information Use the Data Analysis eXpressions (DAX) language to create calculated columns, measures, and queries Choose a data modeling technique that meets your organization's performance and usability requirements Optimize your data model for better performance with xVelocity storage engine Manage complex data relationships, such as multicolumn, banding, and many-to-many Implement security by establishing administrative and data user roles

Fuzzy Information and Engineering-2019 Bing-yuan Cao, 2020-05-16 This book includes 70 selected papers from the Ninth International Conference on Fuzzy Information and Engineering (ICFIE) Satellite, which was held on December 26-30, 2018; and from the 9th International Conference on Fuzzy Information and Engineering (ICFIAE), which was held on February 13-15, 2019. The two conferences presented the latest research in the areas of fuzzy information and engineering, operational research and management, and their applications.

Cooperative Control of Multi-Agent Systems Zhongkui Li, Zhisheng Duan, 2017-12-19 Distributed controller design is generally a challenging task, especially for multi-agent systems with complex dynamics, due to the interconnected effect of the agent dynamics, the interaction graph among agents, and the cooperative control laws. Cooperative Control of Multi-Agent Systems: A Consensus Region Approach offers a systematic framework for designing distributed controllers for multi-agent systems with general linear agent dynamics, linear agent dynamics with uncertainties, and Lipschitz nonlinear agent dynamics. Beginning with an introduction to cooperative control and graph theory, this monograph: Explores the consensus control

problem for continuous-time and discrete-time linear multi-agent systems
 Studies the H^∞ and H_2 consensus problems for linear multi-agent systems
 subject to external disturbances Designs distributed adaptive consensus
 protocols for continuous-time linear multi-agent systems Considers the
 distributed tracking control problem for linear multi-agent systems with a
 leader of nonzero control input Examines the distributed containment control
 problem for the case with multiple leaders Covers the robust cooperative
 control problem for multi-agent systems with linear nominal agent dynamics
 subject to heterogeneous matching uncertainties Discusses the global
 consensus problem for Lipschitz nonlinear multi-agent systems Cooperative
 Control of Multi-Agent Systems: A Consensus Region Approach provides a novel
 approach to designing distributed cooperative protocols for multi-agent
 systems with complex dynamics. The proposed consensus region decouples the
 design of the feedback gain matrices of the cooperative protocols from the
 communication graph and serves as a measure for the robustness of the
 protocols to variations of the communication graph. By exploiting the
 decoupling feature, adaptive cooperative protocols are presented that can be
 designed and implemented in a fully distributed fashion.

Papers and Monographs of the American Academy in Rome American Academy in
 Rome, 1928

**Statistical Atlases and Computational Models of the Heart. Multi-Sequence
 CMR Segmentation, CRT-EPiggy and LV Full Quantification Challenges** Mihaela
 Pop, Maxime Sermesant, Oscar Camara, Xiaohai Zhuang, Shuo Li, Alistair
 Young, Tommaso Mansi, Avan Suinesiaputra, 2020-01-22 This book constitutes the
 thoroughly refereed post-workshop proceedings of the 10th International
 Workshop on Statistical Atlases and Computational Models of the Heart: Atrial

Segmentation and LV Quantification Challenges, STACOM 2019, held in conjunction with MICCAI 2019, in Shenzhen, China, in October 2019. The 42 revised full workshop papers were carefully reviewed and selected from 76 submissions. The topics of the workshop included: cardiac imaging and image processing, machine learning applied to cardiac imaging and image analysis, atlas construction, statistical modelling of cardiac function across different patient populations, cardiac computational physiology, model customization, atlas based functional analysis, ontological schemata for data and results, integrated functional and structural analyses, as well as the pre-clinical and clinical applicability of these methods.

Autonomous and Connected Vehicles Dominique Paret, Hassina Rebaine, 2022-03-15 AUTONOMOUS AND CONNECTED VEHICLES Discover the latest developments in autonomous vehicles and what the future holds for this exciting technology In Autonomous and Connected Vehicles, networking experts Dominique Paret and Hassina Rebaine deliver a robust exploration of the major technological changes taking place in the field, and describe the different levels of autonomy possible with current technologies and the legal and regulatory contexts in which new autonomous vehicles will circulate. The book also includes discussions of the sensors, including infrared, ultrasound, cameras, lidar, and radar, used by modern autonomous vehicles. Readers will enjoy the intuitive descriptions of Advanced Driver Assistance Systems (ADAS), network architectures (CAN-FD, FlexRay, and Backbone Ethernet), and software that power current and future autonomous vehicles. The authors also discuss how ADAS can be fused with data flowing over newer and faster network architectures and artificial intelligence to create greater levels of autonomy. The book also includes: A thorough introduction to the buzz and

hype surrounding autonomous and connected vehicles, including a brief history of the autonomous vehicle Comprehensive explorations of common issues affecting autonomous and connected vehicles, including regulatory guidelines, legislation, relevant norms and standards, and insurance issues Practical discussions of autonomous vehicle sensors, from DAS to ADAS and HADAS, and VA L3 to L5 In-depth examinations of networks and architecture, including discussions of data fusion, artificial intelligence, and hardware architecture in vehicles Perfect for graduate and undergraduate students in programs dealing with the intersection of wireless communication technologies and vehicles, Autonomous and Connected Vehicles is also a must-read reference for industry professionals and researchers seeking a one-stop reference for the latest developments in vehicle communications technology.

A New Method Based on PROMETHEE and TODIM for Multi-Attribute Decision-Making with Single-Valued Neutrosophic Sets Dongsheng Xu, Xiaolan Wei, Hui Ding, Hongqiong Bin, In this paper, a new method based on PROMETHEE and TODIM is proposed to solve the MADM problem under the single-valued neutrosophic environment. Based on the calculation formula of inflow and outflow in PROMETHEE method, and the calculation formula of overall dominance in the TODIM method, a new integrated formula is obtained.

Explainable AI and Other Applications of Fuzzy Techniques Julia Rayz, Victor Raskin, Scott Dick, Vladik Kreinovich, 2021-07-27 This book focuses on an overview of the AI techniques, their foundations, their applications, and remaining challenges and open problems. Many artificial intelligence (AI) techniques do not explain their recommendations. Providing natural-language explanations for numerical AI recommendations is one of the main challenges of modern AI. To provide such explanations, a natural idea is to use

techniques specifically designed to relate numerical recommendations and natural-language descriptions, namely fuzzy techniques. This book is of interest to practitioners who want to use fuzzy techniques to make AI applications explainable, to researchers who may want to extend the ideas from these papers to new application areas, and to graduate students who are interested in the state-of-the-art of fuzzy techniques and of explainable AI—in short, to anyone who is interested in problems involving fuzziness and AI in general.

Consumer Guide to Uniform Tire Quality Grading ,1993

Cutting-Edge Research Topics on Multiple Criteria Decision Making Yong Shi, Shouyang Wang, Yi Peng, Jianping Li, Yong Zeng, 2009-07-09 MCDM 2009, the 20th International Conference on Multiple-Criteria Decision Making, emerged as a global forum dedicated to the sharing of original research results and practical development experiences among researchers and application developers from different multiple-criteria decision making-related areas such as multiple-criteria decision aiding, multiple criteria classification, ranking, and sorting, multiple objective continuous and combinatorial optimization, multiple objective metaheuristics, multiple-criteria decision making and preference modeling, and fuzzy multiple-criteria decision making. The theme for MCDM 2009 was “New State of MCDM in the 21st Century.” The conference seeks solutions to challenging problems facing the development of multiple-criteria decision making, and shapes future directions of research by promoting high-quality, novel and daring research findings. With the MCDM conference, these new challenges and tools can easily be shared with the multiple-criteria decision making community. The workshop program included nine workshops which focused on different topics in new research challenges

and initiatives of MCDM. We received more than 350 submissions for all the workshops, out of which 121 were accepted. This includes 72 regular papers and 49 short papers. We would like to thank all workshop organizers and the Program Committee for the excellent work in maintaining the conference's standing for high-quality papers.

Data Fusion: Concepts and Ideas H B Mitchell, 2012-02-09 This textbook provides a comprehensive introduction to the concepts and idea of multisensor data fusion. It is an extensively revised second edition of the author's successful book: Multi-Sensor Data Fusion: An Introduction which was originally published by Springer-Verlag in 2007. The main changes in the new book are: New Material: Apart from one new chapter there are approximately 30 new sections, 50 new examples and 100 new references. At the same time, material which is out-of-date has been eliminated and the remaining text has been rewritten for added clarity. Altogether, the new book is nearly 70 pages longer than the original book. Matlab code: Where appropriate we have given details of Matlab code which may be downloaded from the worldwide web. In a few places, where such code is not readily available, we have included Matlab code in the body of the text. Layout. The layout and typography has been revised. Examples and Matlab code now appear on a gray background for easy identification and advanced material is marked with an asterisk. The book is intended to be self-contained. No previous knowledge of multi-sensor data fusion is assumed, although some familiarity with the basic tools of linear algebra, calculus and simple probability is recommended. Although conceptually simple, the study of multi-sensor data fusion presents challenges that are unique within the education of the electrical engineer or computer scientist. To become competent in the field the student must become familiar

with tools taken from a wide range of diverse subjects including: neural networks, signal processing, statistical estimation, tracking algorithms, computer vision and control theory. All too often, the student views multi-sensor data fusion as a miscellaneous assortment of different processes which bear no relationship to each other. In contrast, in this book the processes are unified by using a common statistical framework. As a consequence, the underlying pattern of relationships that exists between the different methodologies is made evident. The book is illustrated with many real-life examples taken from a diverse range of applications and contains an extensive list of modern references.

Artificial Intelligence and MRI: Boosting Clinical Diagnosis Antonio Napolitano, Natalie Julie Serkova, Daniel Rodriguez Gutierrez, Oliver Diaz, 2022-08-05

The Doctrine of Fluxions, Founded on Sir Isaac Newton's Method, James Hodgson, 1736

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