

Longitech Camera Controller

Anette Weisbecker, Michael Burmester, Albrecht Schmidt

Take Control of Home Security Cameras Glenn Fleishman, 2023-04-28 Make your home safer! Version 1.4.1, updated April 28, 2023 Are you thinking about installing a home security camera—or several? This book guides you through the many decisions about quality, features, privacy, and security that will help you find just what you want. Or do you own an existing system and want to swap out parts, expand it, or upgrade it? You'll learn options for cameras you own and what interoperates. The book explains the role of Apple's HomeKit Secure Video, and how to make its highest-level security work for you. In *Take Control of Home Security Cameras*, networking and security expert Glenn Fleishman shows you how to make smart choices about buying and configuring cameras that take into account technical details, video quality, system integration, your own privacy and that of others, and internet security. As you read this book, you'll:

- Figure out which features are right for you
- Configure your system securely to ensure that you and people you authorize are the only ones with access to live and stored video
- Understand the different kinds of cloud-based storage of video, and which you might be comfortable with
- Learn about Apple HomeKit Secure Video, an option available for the Apple ecosystem that lets you access video and control cameras from several manufacturers in a highly secure way from your iPhone, iPad, or Mac, including Logitech's Circle View
- Get to know features found in home security cameras, and how they affect the quality and nature of video you capture
- Set your system so that alerts only appear for the kinds of motion, sound, or other triggers that meet your threshold
- Avoid becoming part of the surveillance state—or opt into a limited and controlled part of it with a fuller understanding of what that means
- Learn about the legal aspects and limits of recording audio and video, and how they might (or might not) help catch criminals

Take Control of Home Security Cameras Glenn Fleishman, 2020 Are you thinking about installing a home security camera (or several!) or a smart-home security and sensor system that includes cameras? This book guides you through the many decisions about quality, features, privacy, and security that will help you find just what you want. If you own one or more home security cameras already, you'll learn much more about options, configuration, and changes you can make—and how you might expand your system or replace parts of it. (This book could even convince you that the time isn't right to purchase a home security camera given tradeoffs you don't want to make, especially on privacy and security!) In *Take Control of Home Security Cameras*, networking and security expert Glenn Fleishman shows you how to make smart choices about buying and configuring cameras that take into account technical details, video quality, system integration, your own privacy and that of others, and internet security. As you read this book, you'll:

- Figure out which features are right for you
- Configure your system securely to ensure that you and people you authorize are the only ones with access to live and stored video
- Find out how to build a system entirely offline, in which no video or live streams make their way to the internet at all
- Understand the different kinds of cloud-based storage of video, and which you might be comfortable with
- Learn about Apple HomeKit Secure Video, a new option available for iPhone and iPad users and certain camera systems (including Logitech Circle 2) that provides the highest level of privacy currently available in cloud storage
- Get

to know features found in home security cameras, and how they affect the quality and nature of video you capture Set your system so that alerts only appear for the kinds of motion, sound, or other triggers that meet your threshold Avoid becoming part of the surveillance state-or opt into a limited and controlled part of it with a fuller understanding of what that means Learn about the legal aspects and limits of recording audio and video, and how they might (or might not) help catch criminals Get in-depth insight into over 10 of the most popular home security video cameras and systems, including Amazon Blink and Ring, Google Nest, NETGEAR Arlo, Logitech Circle, and several others Figure out whether you want a multi-camera system that records video on your network or smart cameras that stream events or continuous video to the internet.

Control Engineering in Robotics and Industrial Automation Muralindran Mariappan,Mohd Rizal Arshad,Rini Akmeliawati,Chong Shin Chong,2021-08-12 This book is the first research collection by the Malaysian Society for Automatic Control Engineers (MACE). Numerous applications of control engineering, sensor, and instrumentation technology in robotics, industrial automation, and other mechatronic systems are presented in this book. The book begins by introducing control engineering in robotics and industrial automation. It progresses through a series of chapters, discussing the application of control engineering in various areas such as: brake-by-wire technology; web scrubber systems; robot localization; and, autonomous navigation systems. Coverage of swarm robotics behaviors and applications of sensor technology in the field of music, biomedical technology, and structural analysis takes the book beyond its core of mechatronic systems and demonstrates a more diverse application of the ideas it presents. Each chapter provides comprehensive and detailed coverage of the main ideas, design methods, and practical needs of its chosen topic, making this book accessible and useful to researchers, engineers, postgraduates, and undergraduate students.

ODROID Magazine ,2015-12-01 Table of Contents 6 Logical Volume Management: Beyond Barriers with LVM 8 New Hardkernel Offices: A Mini Tour of the Headquarters 10 Linux Containers: Quickly Prepare a Fully Configured Isolated System for Testing 18 Faro: The Humanoid Goalkeeper Robot 20 Using Android NDK in Android Studio and Gradle: Working with WiringPi in Android 23 Frets on Fire: Release Your Inner Rock Star 24 ODR0ID-XU4 Multi-boot Scripts: Do It the Easy Way 26 Linux Gaming: Fallout - A Post-Nuclear Role Playing Game 30 Reading Temperature and Humidity From an SHT15 Sensor: An Introduction to the GPIO Interface 33 Android Gaming: Five Nights at Freddy's - Jump Scares and Creepy Toys 34 Fan-Made Zelda Games: Your Favorite Fantasy World Expands 37 ODR0ID-C1+ OTG Jumper: Solderless USB Power 38 Android Development: Inside the System Server 40 Meet an ODR0IDian: Saleem Almajed (@Xeosal), Emerging Technology Expert and Avid Musician 41 Community Wiki: Contribute to the Expanding ODR0ID Knowledge Base

Windows 10 All-In-One For Dummies Woody Leonhard,2016-10-03 The most comprehensive guide to Windows 10, updated with the latest enhancements If you're new to Windows 10 and want an authoritative and accessible guide to the basics of the widely used operating system, Windows 10 All-in-One For Dummies is the book for you. Written by trusted Windows expert Woody Leonhard, this freshly updated guide cuts through the jargon and covers everything

you need to know, including navigating the start menu, personalizing your Windows experience, maximizing Windows apps, and managing security. Windows 10 All-in-One For Dummies includes all the guidance you need to make the most of this latest update of Windows. It shows you how to set up multiple user accounts, create a Homegroup for easy sharing between devices, backup your files, and troubleshoot common problems. Covers all the new features and latest enhancements to Windows 10 Makes upgrading to the latest version easier than ever Lets you work with apps like a pro Includes tons of tips on protecting your computer, data, privacy, and identity Whether you use Windows 10 for business, fun and games, or staying in touch with family and friends, Windows 10 All-in-One For Dummies makes it easy.

5G and Beyond Parag Chatterjee,Robin Singh Bhadoria,Yadunath Pathak,2022-05-11 The Internet of Things (IoT) has seen the eventual shift to the Internet of Everything in the recent years, unveiling its ubiquitous presence spanning from smart transports to smart healthcare, from smart education to smart shopping. With the 5G rollouts across the different countries of the world, it raises newer perspectives toward the integration of 5G in IoT. For IoT-based smart devices, 5G not only means speed, but also better stability, efficiency, and more secure connectivity. The reach of 5G in IoT is extending in multifarious areas like self-driving vehicles, smart grids for renewable energy, AI-enabled robots on factory floors, intelligent healthcare services . . . The endless list is the real future of 5G in IoT. Features: Fundamental and applied perspectives to 5G integration in IoT Transdisciplinary vision with aspects of Artificial Intelligence, Industry 4.0, and hands-on practice tools Discussion of trending research issues in 5G and IoT As 5G technologies catalyze a paradigm shift in the domain of IoT, this book serves as a reference for the researchers in the field of IoT and 5G, proffering the landscape to the trending aspects as well as the key topics of discussion in the years to come.

Mensch und Computer 2015 – Workshopband Anette Weisbecker,Michael Burmester,Albrecht Schmidt,2015-09-14 The Workshop Volume from the Humans and Computers Conference documents the advanced tutorials that were presented to deepen the understanding gained from the conference lectures. It presents case studies along with accompanying exercises.

Advanced Concepts for Intelligent Vision Systems Wilfried Philips,Dan Popescu,Paul Scheunders,2006-10-04 This book constitutes the refereed proceedings of the 8th International Conference on Advanced Concepts for Intelligent Vision Systems, ACIVS 2006. The book presents 45 revised full papers and 65 revised poster papers. Topical sections include noise reduction and restoration, segmentation, motion estimation and tracking, video processing and coding, camera calibration, image registration and stereo matching, biometrics and security, medical imaging, image retrieval and image understanding, and more.

Advanced, Contemporary Control Andrzej Bartoszewicz,Jacek Kabziński,Janusz Kacprzyk,2020-06-24 This book presents the proceedings of the 20th Polish Control Conference. A triennial event that was first held in 1958, the conference successfully combines its long tradition with a modern approach to shed light on problems in control engineering, automation, robotics and a wide range of applications in these disciplines. The book presents new

theoretical results concerning the steering of dynamical systems, as well as industrial case studies and worked solutions to real-world problems in contemporary engineering. It particularly focuses on the modelling, identification, analysis and design of automation systems; however, it also addresses the evaluation of their performance, efficiency and reliability. Other topics include fault-tolerant control in robotics, automated manufacturing, mechatronics and industrial systems. Moreover, it discusses data processing and transfer issues, covering a variety of methodologies, including model predictive, robust and adaptive techniques, as well as algebraic and geometric methods, and fractional order calculus approaches. The book also examines essential application areas, such as transportation and autonomous intelligent vehicle systems, robotic arms, mobile manipulators, cyber-physical systems, electric drives and both surface and underwater marine vessels. Lastly, it explores biological and medical applications of the control-theory-inspired methods.

Bio-inspired Information and Communication Technologies Yifan Chen, Tadashi Nakano, Lin Lin, Mohammad Upal Mahfuz, Weisi Guo, 2020-08-10 This book constitutes the refereed conference proceedings of the 12th International Conference on Bio-inspired Information and Communications Technologies, held in Shanghai, China, in July 2020. Due to the safety concerns and travel restrictions caused by COVID-19, BICT 2020 took place online in a live stream. BICT 2020 aims to provide a world-leading and multidisciplinary venue for researchers and practitioners in diverse disciplines that seek the understanding of key principles, processes and mechanisms in biological systems and leverage those understandings to develop novel information and communications technologies (ICT). The 20 full and 8 short papers were carefully reviewed and selected from 56 submissions. In addition to the main track targeting broad and mainstream research topics, BICT 2020 includes four special tracks with focused research topics on internet of everything, intelligent internet of things and network applications, intelligent sensor network, and data-driven intelligent modeling, application and optimization.

Cyber Security of Industrial Control Systems in the Future Internet Environment Stojanović, Mirjana D., Boštjan Rakas, Slavica V., 2020-02-21 In today's modernized market, many fields are utilizing internet technologies in their everyday methods of operation. The industrial sector is no different as these technological solutions have provided several benefits including reduction of costs, scalability, and efficiency improvements. Despite this, cyber security remains a crucial risk factor in industrial control systems. The same public and corporate solutions do not apply to this specific district because these security issues are more complex and intensive. Research is needed that explores new risk assessment methods and security mechanisms that professionals can apply to their modern technological procedures. Cyber Security of Industrial Control Systems in the Future Internet Environment is a pivotal reference source that provides vital research on current security risks in critical infrastructure schemes with the implementation of information and communication technologies. While highlighting topics such as intrusion detection systems, forensic challenges, and smart grids, this publication explores specific security solutions within industrial sectors that have begun applying internet technologies to their current methods of operation. This book is ideally designed for researchers, system engineers, managers,

networkers, IT professionals, analysts, academicians, and students seeking a better understanding of the key issues within securing industrial control systems that utilize internet technologies.

Maximum PC ,2006-12 Maximum PC is the magazine that every computer fanatic, PC gamer or content creator must read. Each and every issue is packed with punishing product reviews, insightful and innovative how-to stories and the illuminating technical articles that enthusiasts crave.

Robust Cooperative Control of Multi-Agent Systems Chunyan Wang,Zongyu Zuo,Jianan Wang,Zhengtao Ding,2021-05-18 This book presents a concise introduction to the latest advances in robust cooperative control design for multi-agent systems with input delay and external disturbances, especially from a prediction and observation perspective. The volume covers a wide range of applications, such as the trajectory tracking of quadrotors, formation flying of multiple unmanned aerial vehicles (UAVs) and fixed-time formation of ground vehicles. Robust cooperative control means that multi-agent systems are able to achieve specified control tasks while remaining robust in the face of both parametric and nonparametric model uncertainties. In addition, the authors cover a wide range of key issues in cooperative control, such as communication and input delays, parametric model uncertainties and external disturbances. Moving beyond the scope of existing works, a systematic prediction and observation approach to designing robust cooperative control laws is presented. About the Authors Chunyan Wang is an Associate Professor in the School of Aerospace Engineering at Beijing Institute of Technology, China. Zongyu Zuo is a full Professor with the School of Automation Science and Electrical Engineering, Beihang University, China. Jianan Wang is an Associate Professor in the School of Aerospace Engineering at Beijing Institute of Technology, China. Zhengtao Ding is a Professor in the Department of Electrical and Electronic Engineering at University of Manchester, U.K.

ICRRM 2019 – System Reliability, Quality Control, Safety, Maintenance and Management Vinit Kumar Gunjan,Sri Niwas Singh,Tran Duc-Tan,Gloria Jeanette Rincon Aponte,Amit Kumar,2019-06-13 Content of this proceedings discusses emerging trends in structural reliability, safety and disaster management, covering topics like total quality management, risk maintenance and design for reliability. Some papers also address chemical process reliability, reliability analysis and engineering applications in chemical process equipment systems and includes a chapter on reliability evaluation models of chemical systems. Accepted papers from 2019 International Conference on Reliability, Risk Maintenance and Engineering Management (ICRRM 2019) are part of this conference proceeding. It offers useful insights to road safety engineers, disaster management professionals involved in product design and probabilistic methods in manufacturing systems.

Aerial Vehicles T. M. Lam,2009-01-01 This book contains 35 chapters written by experts in developing techniques for making aerial vehicles more intelligent, more reliable, more flexible in use, and safer in operation.It will also serve as an inspiration for further improvement of the design and application of aeral vehicles. The advanced techniques and research described here may also be applicable to other high-tech areas such as robotics, avionics, vetronics, and space.

Visual Control of Wheeled Mobile Robots Héctor . M Becerra, Carlos Sagüés, 2014-03-26 Vision-based control of wheeled mobile robots is an interesting field of research from a scientific and even social point of view due to its potential applicability. This book presents a formal treatment of some aspects of control theory applied to the problem of vision-based pose regulation of wheeled mobile robots. In this problem, the robot has to reach a desired position and orientation, which are specified by a target image. It is faced in such a way that vision and control are unified to achieve stability of the closed loop, a large region of convergence, without local minima and good robustness against parametric uncertainty. Three different control schemes that rely on monocular vision as unique sensor are presented and evaluated experimentally. A common benefit of these approaches is that they are valid for imaging systems obeying approximately a central projection model, e.g., conventional cameras, catadioptric systems and some fisheye cameras. Thus, the presented control schemes are generic approaches. A minimum set of visual measurements, integrated in adequate task functions, are taken from a geometric constraint imposed between corresponding image features. Particularly, the epipolar geometry and the trifocal tensor are exploited since they can be used for generic scenes. A detailed experimental evaluation is presented for each control scheme.

Informatics in Control, Automation and Robotics Honghua Tan, 2012-02-01 Session 1 includes 109 papers selected from 2011 3rd International Asia Conference on Informatics in Control, Automation and Robotics (CAR 2011), held on December 24-25, 2011, Shenzhen, China. This session will act as an international forum for researchers and practitioners interested in the advances in and applications of Intelligent Control Systems. It is an opportunity to present and observe the latest research, results, and ideas in these areas. Intelligent control is a rapidly developing, complex, and challenging field of increasing practical importance and still greater potential. Its applications have a solid core in robotics and mechatronics but branch out into areas as diverse as process control, automotive industry, medical equipment, renewable energy and air conditioning. So, this session will aim to strengthen relationships between industry, research laboratories and universities. All papers published in session 1 will be peer evaluated by at least two conference reviewers. Acceptance will be based primarily on originality and contribution.

Modelling and Control of an Autonomous Two-Wheeled Vehicle Alen Turnwald, 2020-11-13 With respect to the future urban mobility, modern electrical bicycles, advanced motorcycles and innovative two-wheeled vehicles are arresting enormous amount of attention. Especially, model-based control and optimal trajectory planning for such vehicles are important to the research and development of the future. Therefore, a reliable and yet usable vehicle model as well as a systematic approach to motion control for two-wheeled vehicles are essential, to which this work makes a contribution. Currently available two-wheeled vehicle models are mostly either too complex to be used for a systematic control synthesis, or too simple such that the physical behaviour of the vehicle is no more represented. In this thesis, a unifying approach to modelling and control for autonomous two-wheeled vehicles is presented. The resulting model is generally valid and physically detailed enough to represent the characteristic

dynamical behaviour such as the self-stability. At the same time, it is suited to a systematic control synthesis. Furthermore, the systematic extendability, for instance by a rider, is demonstrated. The model is validated by simulations and by comparison to well-known models from the literature. The proposed vehicle model is derived in the Lagrangian and Hamiltonian framework and used for model-based optimal trajectory planning. Furthermore, a passivity-based trajectory tracking controller is designed based on the resulting port-Hamiltonian system using the so-called generalised canonical transformations. Such a controller is physically interpretable and robust against parameter uncertainties. To this end, existing approaches of passivity-based controller design are extended and adjusted for two-wheeled vehicles. Finally, a prototype two-wheeled vehicle is introduced which is used for experimental validation of the model and to demonstrate motion control algorithms for autonomous two-wheeled vehicles.

Intelligent Autonomous Systems 13 Emanuele Menegatti, Nathan Michael, Karsten Berns, Hiroaki Yamaguchi, 2015-09-03
This book describes the latest research accomplishments, innovations, and visions in the field of robotics as presented at the 13th International Conference on Intelligent Autonomous Systems (IAS), held in Padua in July 2014, by leading researchers, engineers, and practitioners from across the world. The contents amply confirm that robots, machines, and systems are rapidly achieving intelligence and autonomy, mastering more and more capabilities such as mobility and manipulation, sensing and perception, reasoning, and decision making. A wide range of research results and applications are covered, and particular attention is paid to the emerging role of autonomous robots and intelligent systems in industrial production, which reflects their maturity and robustness. The contributions have been selected through a rigorous peer-review process and contain many exciting and visionary ideas that will further galvanize the research community, spurring novel research directions. The series of biennial IAS conferences commenced in 1986 and represents a premiere event in robotics.

Photography Peter Laytin, 1993

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