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Fausto Pedro García Márquez,Akhtar Jamil,Süleyman Eken,Alaa Ali Hameed

Artificial Intelligence for Robotics and Autonomous Systems Applications Ahmad Taher Azar, Anis Koubaa, 2023-05-15 This book addresses many applications of artificial intelligence in robotics, namely AI using visual and motional input. Robotic technology has made significant contributions to daily living, industrial uses, and medicinal applications. Machine learning, in particular, is critical for intelligent robots or unmanned/autonomous systems such as UAVs, UGVs, UUVs, cooperative robots, and so on. Humans are distinguished from animals by capacities such as receiving visual information, adjusting to uncertain circumstances, and making decisions to take action in a complex system. Significant progress has been made in robotics toward human-like intelligence; yet, there are still numerous unresolved issues. Deep learning, reinforcement learning, real-time learning, swarm intelligence, and other developing approaches such as tiny-ML have been developed in recent decades and used in robotics. Artificial intelligence is being integrated into robots in order to develop advanced robotics capable of performing multiple tasks and learning new things with a better perception of the environment, allowing robots to perform critical tasks with human-like vision to detect or recognize various objects. Intelligent robots have been successfully constructed using machine learning and deep learning AI technology. Robotics performance is improving as higher quality, and more precise machine learning processes are used to train computer vision models to recognize different things and carry out operations correctly with the desired outcome. We believe that the increasing demands and challenges offered by real-world robotic applications encourage academic research in both artificial intelligence and robotics. The goal of this book is to bring together scientists, specialists, and engineers from around the world to present and share their most recent research findings and new ideas on artificial intelligence in robotics.

Computational Science and Its Applications - ICCSA 2006 Osvaldo Gervasi, Vipin Kumar, C.J. Kenneth Tan, David Taniar, Antonio Laganà, Youngsong Mun, Hyunseung Choo, 2006-05-11 The five-volume set LNCS 3980-3984 constitutes the refereed proceedings of the International Conference on Computational Science and Its Applications, ICCSA 2006. The volumes present a total of 664 papers organized according to the five major conference themes: computational methods, algorithms and applications high performance technical computing and networks advanced and emerging applications geometric modelling, graphics and visualization information systems and information technologies. This is Part I.

Computational Intelligence, Data Analytics and Applications Fausto Pedro García Márquez, Akhtar Jamil, Süleyman Eken, Alaa Ali Hameed, 2023-03-14 This book is a compilation of accepted papers presented at the International Conference on Computing, Intelligence and Data Analytics (ICCIDA) in 2022 organized by Information Systems Engineering of the Kocaeli University, Turkey on September 16-17, 2022. The book highlights some of the latest research advances and cutting-edge analyses of real-world problems related to Computing, Intelligence and Data Analytics and their applications in various domains. This includes state of the art models and methods used on benchmark datasets.

Molecular Physical Chemistry for Engineering Applications Florin Emilian Daneş, Silvia Daneş, Valeria Petrescu, Eleonora-Mihaela Ungureanu, 2021-07-06 This textbook introduces the molecular side of physical chemistry. It offers students and practitioners a new approach to the subject by presenting numerous applications and solved problems that illustrate the concepts introduced for varied and complex technical situations. The book offers a balance between theory, tools, and practical applications. The text aims to be a practical manual for solving engineering problems in industries where processes depend on the chemical composition and physical properties of matter. The book is organized into three main topics: (I) the molecular structure of matter, (II) molecular models in thermodynamics, and (III) transport phenomena and mechanisms. Part I presents methods of analysis of the molecular behavior in a given system, while the following parts use these methods to study the equilibrium states of a material system and to analyze the processes that can take place when the system is in a state of non-equilibrium, in particular the transport phenomena. Molecular Physical Chemistry for Engineering Applications is designed for upper-level undergraduate and graduate courses in physical chemistry for engineers, applied physical chemistry, transport phenomena, colloidal chemistry, and transport/transfer processes. The book will also be a valuable reference guide for engineers, technicians, and scientists working in industry. Offers modeling techniques and tools for solving exercises and practical cases; Provides solutions and conclusions so students can follow results more closely; Step-by-step problem solving enables students to understand how to approach complex issues.

Advances in Engineering Research and Application Duy Cuong Nguyen, Ngoc Pi Vu, Binh Tien Long, Horst Puta, Kai-Uwe Sattler, 2022-01-12 This book covers the International Conference on Engineering Research and Applications (ICERA 2021), which took place at Thai Nguyen University of Technology, Thai Nguyen, Vietnam on December 1–2, 2021, and provided an international forum to disseminate information on latest theories and practices in engineering research and applications. The conference focused on original research work in areas including mechanical engineering, materials and mechanics of materials, mechatronics and micromechatronics, automotive engineering, electrical and electronics engineering, information and communication technology. By disseminating the latest advances in the field, the Proceedings of ICERA 2021, Advances in Engineering Research and Application, helps academics and professionals alike to reshape their thinking on sustainable development.

Dealing with the Data Flood Jeroen Meij, 2002

Game Theory and Applications L. A. Petrosjan, 2005 This book brings together papers of well-known specialists in game theory and adjacent problems. It presents the basic results in dynamic games, stochastic games, applications of game theoretical methods in ecology and economics and methodological aspects of game theory.

Molecular Imaging: Basic Principles And Applications In Biomedical Research (2nd Edition) Rudin Markus, 2013-07-04 The area of molecular imaging has matured over the past decade and is still growing rapidly. Many concepts developed for molecular biology and cellular imaging have been successfully translated to in vivo imaging of intact organisms. Molecular imaging enables the study of processes at a molecular level in their full biological context. Due to the high specificity of the molecular readouts the approach bears a high potential for diagnostics. It is fair to say that molecular imaging has become an indispensable tool for biomedical research and drug discovery and development today. This volume familiarizes the reader with the concepts of imaging and molecular imaging in particular. Basic principles of imaging technologies, reporter moieties for the various imaging modalities, and the design of targeted probes are described in the first part. The second part illustrates how these tools can be used to visualize relevant molecular events in the living organism. Topics covered include the studies of the biodistribution of reporter probes

and drugs, visualization of the expression of biomolecules such as receptors and enzymes, and how imaging can be used for analyzing consequences of the interaction of a ligand or a drug with its molecular target by visualizing signal transduction, or assessing the metabolic, physiological, or structural response of the organism studied. The final chapter deals with visualization of cell migration, for example in the context of cell therapies. The second edition covers novel developments over recent years, in particular regarding imaging technologies (hybrid techniques) and novel reporter concepts. Novel biomedical applications have been included, where appropriate. All the chapters have been thoroughly reworked and the artwork updated.

Complex Networks and Their Applications VIII Hocine Cherifi, Sabrina Gaito, José Fernando Mendes, Esteban Moro, Luis Mateus Rocha, 2019-11-25 This book highlights cutting-edge research in the field of network science, offering scientists, researchers, students, and practitioners a unique update on the latest advances in theory and a multitude of applications. It presents the peer-reviewed proceedings of the Eighth International Conference on Complex Networks and their Applications (COMPLEX NETWORKS 2019), which took place in Lisbon, Portugal, on December 10–12, 2019. The carefully selected papers cover a wide range of theoretical topics such as network models and measures; community structure, and network dynamics; diffusion, epidemics, and spreading processes; resilience and control as well as all the main network applications, including social and political networks; networks in finance and economics; biological and neuroscience networks; and technological networks.

Singularities and Foliations. Geometry, Topology and Applications Raimundo Nonato Araújo dos Santos, Aurélio Menegon Neto, David Mond, Marcelo J. Saia, Jawad Snoussi, 2018-03-21 This proceedings book brings selected works from two conferences, the 2nd Brazil-Mexico Meeting on Singularity and the 3rd Northeastern Brazilian Meeting on Singularities, that were held in Salvador, in July 2015. All contributions were carefully peer-reviewed and revised, and cover topics like Equisingularity, Topology and Geometry of Singularities, Topological Classification of Singularities of Mappings, and more. They were written by mathematicians from several countries, including Brazil, Spain, Mexico, Japan and the USA, on relevant topics on Theory of Singularity, such as studies on deformations, Milnor fibration, foliations, Catastrophe theory, and myriad applications. Open problems are also introduced, making this volume a must-read both for graduate students and active researchers in this field.

MECHANISMS AND VIBRATION ANALYSIS WITH SOLIDWORKS AND MATLAB /SIMSCAPE Cyrus Raoufi PhD PEng, 2021-09-15 This textbook is intended to cover the fundamentals of Design of Mechanisms using the SolidWorks Motion Analysis® and MATLAB™/Simulink™/Simscape™. It is written primarily for the engineering students, engineers, technologists and practitioners who have no or a little work experience with SolidWorks and MATLAB™/Simulink™/Simscape™. It is assumed that the readers are familiar with the fundamentals of the Statics and Dynamics offered at introductory level courses in a typical undergraduate mechanical engineering program. However, the basic theories and formulas are included within this text as well. The textbook can be also used as a reference text for an introductory level course in the motion system design and design of mechanisms areas, offered to the students in mechatronics and robotics programs. Chapter 1 of this textbook deals mostly with the fundamental terms and concepts used in the process of the design of mechanism. Several examples of commonly used planar mechanisms are offered, including: slider-crank, four bar, Scotch-Yoke, quick return, ratchet, indexing, and cam-follower mechanisms. The concept of the mass moment of inertia is reviewed and the application of SolidWorks to find the area and mass properties of a rigid body, relative to a desired coordinate frame, is shown. The rigid bodies' transformation and kinematics of a rigid body are presented and the governing equations are obtained. Chapter 2 includes the graphical and analytical kinematic approaches for a planar mechanism, alongside an introduction to the concept of velocity and acceleration images. Several examples are solved using MATLAB/Simulink to demonstrate how a computational software is used to solve the equations obtained by the analytical kinematic approach. Chapter 3 of this textbook introduces SolidWorks Motion Analysis with all available motion elements such as motors, force, contact, gravity, spring, and dampers. Further, both motion study properties and SolidWorks motion analysis post processing tools are presented. Chapter 4 of this textbook presents both the static and dynamic force analysis using the graphical approach. A systematic approach is introduced to learn how to use a CAD software, in particular SolidWorks, to perform both static and dynamic force analysis. The main parameters to size and select an actuator based on required loading and inertia are discussed. The load and inertia calculation for commonly used transmission systems such as gearboxes, lead screws, racks and pinions, pulleys, belt-driven, and conveyor systems are also presented. In chapter 5, Simscape software and several Simscape libraries are introduced to simulate mechanical motion systems such as robots and mechanisms. Chapter 6 of this textbook shows a systematic approach is to define the position and orientation of various frames in space using MATLAB/Simulink/ Robotic System Toolbox. The Forward kinematic of serial robots is covered. This chapter ends with an introduction to the inverse kinematic of a serial robot. Chapter 7 of this book presents the applications of some tools available in MATLAB and Simulink/Simscape to analyze the mechanical vibrations of the discrete systems. Besides, SolidWorks Simulations is used to perform modal frequency analysis for continuous systems such as beams, plates, sheet metals, and assemblies.

Intelligent Systems and Applications Yaxin Bi, Rahul Bhatia, Supriya Kapoor, 2019-08-23 The book presents a remarkable collection of chapters covering a wide range of topics in the areas of intelligent systems and artificial intelligence, and their real-world applications. It gathers the proceedings of the Intelligent Systems Conference 2019, which attracted a total of 546 submissions from pioneering researchers, scientists, industrial engineers, and students from all around the world. These submissions underwent a double-blind peer-review process, after which 190 were selected for inclusion in these proceedings. As intelligent systems continue to replace and sometimes outperform human intelligence in decision-making processes, they have made it possible to tackle a host of problems more effectively. This branching out of computational intelligence in several directions and use of intelligent systems in everyday applications have created the need for an international conference as a venue for reporting on the latest innovations and trends. This book collects both theory and application based chapters on virtually all aspects of artificial intelligence; presenting state-of-the-art intelligent methods and techniques for solving real-world problems, along with a vision for future research, it represents a unique and valuable asset.

Open Government: Concepts, Methodologies, Tools, and Applications Management Association, Information Resources, 2019-09-06 Open government initiatives have become a defining goal for public administrators around the world. As technology and social media tools become more integrated into society, they provide important frameworks

for online government and community collaboration. However, progress is still necessary to create a method of evaluation for online governing systems for effective political management worldwide. *Open Government: Concepts, Methodologies, Tools, and Applications* is a vital reference source that explores the use of open government initiatives and systems in the executive, legislative, and judiciary sectors. It also examines the use of technology in creating a more affordable, participatory, and transparent public-sector management models for greater citizen and community involvement in public affairs. Highlighting a range of topics such as data transparency, collaborative governance, and bureaucratic secrecy, this multi-volume book is ideally designed for government officials, leaders, practitioners, policymakers, researchers, and academicians seeking current research on open government initiatives.

Intelligent Robotics and Applications Huayong Yang, Honghai Liu, Jun Zou, Zhouping Yin, Lianqing Liu, Geng Yang, Xiaoping Ouyang, Zhiyong Wang, 2023-10-20 The 9-volume set LNAI 14267-14275 constitutes the proceedings of the 16th International Conference on Intelligent Robotics and Applications, ICIRA 2023, which took place in Hangzhou, China, during July 5–7, 2023. The 413 papers included in these proceedings were carefully reviewed and selected from 630 submissions. They were organized in topical sections as follows: Part I: Human-Centric Technologies for Seamless Human-Robot Collaboration; Multimodal Collaborative Perception and Fusion; Intelligent Robot Perception in Unknown Environments; Vision-Based Human Robot Interaction and Application. Part II: Vision-Based Human Robot Interaction and Application; Reliable AI on Machine Human Reactions; Wearable Sensors and Robots; Wearable Robots for Assistance, Augmentation and Rehabilitation of Human Movements; Perception and Manipulation of Dexterous Hand for Humanoid Robot. Part III: Perception and Manipulation of Dexterous Hand for Humanoid Robot; Medical Imaging for Biomedical Robotics; Advanced Underwater Robot Technologies; Innovative Design and Performance Evaluation of Robot Mechanisms; Evaluation of Wearable Robots for Assistance and Rehabilitation; 3D Printing Soft Robots. Part IV: 3D Printing Soft Robots; Dielectric Elastomer Actuators for Soft Robotics; Human-like Locomotion and Manipulation; Pattern Recognition and Machine Learning for Smart Robots. Part V: Pattern Recognition and Machine Learning for Smart Robots; Robotic Tactile Sensation, Perception, and Applications; Advanced Sensing and Control Technology for Human-Robot Interaction; Knowledge-Based Robot Decision-Making and Manipulation; Design and Control of Legged Robots. Part VI: Design and Control of Legged Robots; Robots in Tunnelling and Underground Space; Robotic Machining of Complex Components; Clinically Oriented Design in Robotic Surgery and Rehabilitation; Visual and Visual-Tactile Perception for Robotics. Part VII: Visual and Visual-Tactile Perception for Robotics; Perception, Interaction, and Control of Wearable Robots; Marine Robotics and Applications; Multi-Robot Systems for Real World Applications; Physical and Neurological Human-Robot Interaction. Part VIII: Physical and Neurological Human-Robot Interaction; Advanced Motion Control Technologies for Mobile Robots; Intelligent Inspection Robotics; Robotics in Sustainable Manufacturing for Carbon Neutrality; Innovative Design and Performance Evaluation of Robot Mechanisms. Part IX: Innovative Design and Performance Evaluation of Robot Mechanisms; Cutting-Edge Research in Robotics.

Mobile Learning Applications in Early Childhood Education Papadakis, Stamatios, Kalogiannakis, Michail, 2019-11-29 Mobile technologies combined with an interdisciplinary approach to knowledge and organization of learning experiences that are meaningful to children could create a creative and interactive learning environment different from that of traditional teaching. Making good use of mobile learning with appropriate devices will increase the learning motivations of the students and help them bring about positive performance. *Mobile Learning Applications in Early Childhood Education* is a collection of innovative research on the methods and applications of mobile learning techniques and strategies within diversified teaching settings. While highlighting topics including computational thinking, ubiquitous learning, and social development, this book is ideally designed for researchers, teachers, parents, curriculum developers, instructional designers, academicians, students, and practitioners seeking current research on the application of mobile technology within child education.

Computer Science and its Applications James J. (Jong Hyuk) Park, Ivan Stojmenovic, Hwa Young Jeong, Gangman Yi, 2014-11-29 The 6th FTIR International Conference on Computer Science and its Applications (CSA-14) will be held in Guam, USA, Dec. 17 - 19, 2014. CSA-14 presents a comprehensive conference focused on the various aspects of advances in engineering systems in computer science, and applications, including ubiquitous computing, U-Health care system, Big Data, UI/UX for human-centric computing, Computing Service, Bioinformatics and Bio-Inspired Computing and will show recent advances on various aspects of computing technology, Ubiquitous Computing Services and its application.

The Microscope: Its History, Construction, and Applications ... Jabez Hogg, 1854

Applications of the Isotopic Effect in Solids Vladimir G. Plekhanov, 2013-04-17 Readers intent on mastering the basics should start by reading the first few overview chapters and then delve into the descriptions of specific current applications to see how they actually work. Important future applications are also outlined, including information storage, materials for computer memories, quantum computers, isotopic fibers, isotopic optoelectronics, and quantum electronics.

Data Processing Techniques and Applications for Cyber-Physical Systems (DPTA 2019) Chuanchao Huang, Yu-Wei Chan, Neil Yen, 2020-02-03 This book covers cutting-edge and advanced research on data processing techniques and applications for Cyber-Physical Systems. Gathering the proceedings of the International Conference on Data Processing Techniques and Applications for Cyber-Physical Systems (DPTA 2019), held in Shanghai, China on November 15–16, 2019, it examines a wide range of topics, including: distributed processing for sensor data in CPS networks; approximate reasoning and pattern recognition for CPS networks; data platforms for efficient integration with CPS networks; and data security and privacy in CPS networks. Outlining promising future research directions, the book offers a valuable resource for students, researchers and professionals alike, while also providing a useful reference guide for newcomers to the field.

Extensions of the Critical Path Method Through the Application of Integer Programming W. L. Meyer, Louis Richard Shaffer, 1963

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