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Brian Hu

Robust Filtering for Uncertain Systems Huijun Gao, Xianwei Li, 2014-04-10 This monograph provides the reader with a systematic treatment of robust filter design, a key issue in systems, control and signal processing, because of the fact that the inevitable presence of uncertainty in system and signal models often degrades the filtering performance and may even cause instability. The methods described are therefore not subject to the rigorous assumptions of traditional Kalman filtering. The monograph is concerned with robust filtering for various dynamical systems with parametric uncertainties and focuses on parameter-dependent approaches to filter design. Classical filtering schemes, like H_2 filtering and H_∞ filtering, are addressed and emerging issues such as robust filtering with constraints on communication channels and signal frequency characteristics are discussed. The text features: · design approaches to robust filters arranged according to varying complexity level and emphasizing robust filtering in the parameter-dependent framework for the first time; · guidance on the use of special realistic phenomena or factors to describe problems more accurately and to improve filtering performance; · a unified linear matrix inequality formulation of design approaches for easy and effective filter design; · demonstration of the techniques of matrix decoupling technique, the generalized Kalman–Yakubovich–Popov lemma, the free weighting matrix technique and the delay modelling approach, in robust filtering; · numerous easy-to-follow simulation examples, graphical and tabular illustrations to help the reader understand the filter design approaches developed; and · an account of emerging issues on robust filtering for research to inspire future investigation. Robust Filtering for Uncertain Systems will be of interest to academic researchers specializing in linear, robust and optimal control and estimation and to practitioners working in tracking and network control or signal filtering, detection and estimation. Graduate students learning control and systems theory, signal processing or applied mathematics will also find the book to be a valuable resource.

Nonlinear Stochastic Systems with Network-Induced Phenomena Jun Hu, Zidong Wang, Huijun Gao, 2014-07-21 This monograph introduces methods for handling filtering and control problems in nonlinear stochastic systems arising from network-induced phenomena consequent on limited communication capacity. Such phenomena include communication delay, packet dropout, signal quantization or saturation, randomly occurring nonlinearities and randomly occurring uncertainties. The text is self-contained, beginning with an introduction to nonlinear stochastic systems, network-induced phenomena and filtering and control, moving through a collection of the latest research results which focuses on the three aspects of: · the state-of-the-art of nonlinear filtering and control; · recent advances in recursive filtering and sliding mode control; and · their potential for application in networked control systems, and concluding with some ideas for future research work. New concepts such as the randomly occurring uncertainty and the probability-constrained performance index are proposed to make the network models as realistic as possible. The power of combinations of such recent tools as the completing-the-square and sums-of-squares techniques, Hamilton–Jacobi–Isaacs matrix inequalities, difference linear matrix inequalities and parameter-dependent matrix inequalities is exploited in treating the mathematical and computational challenges arising from nonlinearity and stochasticity. Nonlinear Stochastic Systems with Network-Induced Phenomena establishes a unified framework of control and filtering which will be of value to academic researchers in bringing structure to problems associated with an important class of networked system and offering new means of solving them. The significance of the new concepts, models and methods presented for practical control engineering and signal processing will also make it a valuable reference for engineers dealing with nonlinear control and filtering problems.

Advanced Control for Vehicle Active Suspension Systems Weichao Sun, Huijun Gao, Peng Shi, 2019-03-13 This book focuses on most recent theoretical findings on control issues for active suspension systems. The authors first introduce the theoretical background of active suspension control, then present constrained H_∞ control approaches of active suspension systems in the entire frequency domain, focusing on the state feedback and dynamic output feedback controller in the finite frequency domain which people are most sensitive to. The book also contains nonlinear constrained

tracking control via terminal sliding-mode control and adaptive robust theory, presenting controller design of active suspensions as well as the reliability control of active suspension systems. The target audience primarily comprises research experts in control theory, but the book may also be beneficial for graduate students alike.

Filtering, Control and Fault Detection with Randomly Occurring Incomplete Information Hongli Dong, Zidong Wang, Huijun Gao, 2013-06-13 In the context of systems and control, incomplete information refers to a dynamical system in which knowledge about the system states is limited due to the difficulties in modelling complexity in a quantitative way. The well-known types of incomplete information include parameter uncertainties and norm-bounded nonlinearities. Recently, in response to the development of network technologies, the phenomenon of randomly occurring incomplete information has become more and more prevalent. Filtering, Control and Fault Detection with Randomly Occurring Incomplete Information reflects the state-of-the-art of the research area for handling randomly occurring incomplete information from three interrelated aspects of control, filtering and fault detection. Recent advances in networked control systems and distributed filtering over sensor networks are covered, and application potential in mobile robotics is also considered. The reader will benefit from the introduction of new concepts, new models and new methodologies with practical significance in control engineering and signal processing. Key Features: Establishes a unified framework for filtering, control and fault detection problem for various discrete-time nonlinear stochastic systems with randomly occurring incomplete information Investigates several new concepts for randomly occurring phenomena and proposes a new system model to better describe network-induced problems Demonstrates how newly developed techniques can handle emerging mathematical and computational challenges Contains the latest research results Filtering, Control and Fault Detection with Randomly Occurring Incomplete Information provides a unified yet neat framework for control/filtering/fault-detection with randomly occurring incomplete information. It is a comprehensive textbook for graduate students and is also a useful practical research reference for engineers dealing with control, filtering and fault detection problems for networked systems.

Robust Environmental Perception and Reliability Control for Intelligent Vehicles Huihui Pan, Jue Wang, Xinghu Yu, Weichao Sun, Huijun Gao, 2023-11-25 This book presents the most recent state-of-the-art algorithms on robust environmental perception and reliability control for intelligent vehicle systems. By integrating object detection, semantic segmentation, trajectory prediction, multi-object tracking, multi-sensor fusion, and reliability control in a systematic way, this book is aimed at guaranteeing that intelligent vehicles can run safely in complex road traffic scenes. Adopts the multi-sensor data fusion-based neural networks to environmental perception fault tolerance algorithms, solving the problem of perception reliability when some sensors fail by using data redundancy. Presents the camera-based monocular approach to implement the robust perception tasks, which introduces sequential feature association and depth hint augmentation, and introduces seven adaptive methods. Proposes efficient and robust semantic segmentation of traffic scenes through real-time deep dual-resolution networks and representation separation of vision transformers. Focuses on trajectory prediction and proposes phased and progressive trajectory prediction methods that is more consistent with human psychological characteristics, which is able to take both social interactions and personal intentions into account. Puts forward methods based on conditional random field and multi-task segmentation learning to solve the robust multi-object tracking problem for environment perception in autonomous vehicle scenarios. Presents the novel reliability control strategies of intelligent vehicles to optimize the dynamic tracking performance and investigates the completely unknown autonomous vehicle tracking issues with actuator faults.

Robotic Micromanipulation of Zebrafish Larva Songlin Zhuang, Gefei Zhang, Dongxu Lei, Xinghu Yu, Mingsi Tong, Weiyang Lin, Yang Shi, Huijun Gao, 2023-07-22 This book offers readers a series of robotic methods for manipulating zebrafish larva, one of the most popular model vertebrates widely used in biomedical research and clinical applications. The authors leverage advanced control theories, image processing algorithms, and

artificial intelligence to establish a robot-assisted automated or semi-automated zebrafish larva-targeted micromanipulation system for different experimental purposes. The methods presented are generic and can be translated to manipulate other types of biological objects, such as embryos or cells. Coverage includes topics that span the procedures of manipulating zebrafish larva, such as in-plane positioning, three-dimensional orientation, deformation-controllable immobilization, organ-targeted microinjection, whole-organism imaging, and high-throughput trajectory tracking of zebrafish larvae group movement. *Robotic Micromanipulation of Zebrafish Larva* is written in a simple, clear, and easy-to-read style. It is an ideal reference for academic researchers and biomedical operators. It is also a valuable resource for students learning robotics, control and system theories, image processing, artificial intelligence, and biomedical engineering.

International Young Physicists' Tournament: Problems And Solutions 2015 Wenli Gao,Sihui Wang,2018-01-05 International Young Physicists' Tournament (IYPT), is one of the most prestigious international physics contests among high school students. This book is based on the solutions of 2015 IYPT problems. The authors are undergraduate students who participated the CUPT (Chinese Undergraduate Physics Tournament). It is intended as a college level solution to the challenging open-ended problems. It provides original, quantitative solutions in fulfilling seemingly impossible tasks. The young authors provide quantitative solutions to practical problems in everyday life.This is a good reference book for undergraduates, advanced high school students, physics educators and curious public interested in the intriguing phenomenon in daily life.

Consensus Over Switching Network Topology: Characterizing System Parameters and Joint Connectivity Jiahu Qin,Qichao Ma,Huijun Gao,Wei Xing Zheng,Yu Kang,2021-10-27 This book aims to extend existing works on consensus of multi-agent systems systematically. The agents to be considered range from double integrators to generic linear systems. The primary goal is to explicitly characterize how agent parameters, which reflect both self-dynamics and inner coupling of each agent, and switching network topologies jointly influence the collective behaviors. A series of necessary and/or sufficient conditions for exponential consensus are derived. The contents of this book are as follows. Chapter 1 provides the background and briefly reviews the advances of consensus of multi-agent systems. Chapter 2 addresses the consensus problem of double integrators over directed switching network topologies. It is proven that exponential consensus can be secured under very mild conditions incorporating the damping gain and network topology. Chapter 3 considers generic linear systems with undirected switching network topologies. Necessary and sufficient conditions on agent parameters and connectivity of the communication graph for exponential consensus are provided. Chapter 4 furthers the study of consensus for multiple generic linear systems by considering directed switching network topologies. How agent parameters and joint connectivity work together for reaching consensus is characterized from an algebraic and geometric view. Chapter 5 extends the design and analysis methodology to containment control problem, where there exist multiple leaders. A novel analysis framework from the perspective of state transition matrix is developed. This framework relates containment to consensus and overcomes the difficulty of construction of a containment error. This book serves as a reference to the main research issues and results on consensus of multi-agent systems. Some prerequisites for reading this book include linear system theory, matrix theory, mathematics, and so on.

Permanent Missions to the United Nations, No.308 United Nations,2019-06-05 This book serves as a directory of the Permanent Missions to the United Nations in New York, as well as a listing of their diplomatic personnel. It also includes information on Observer Offices, Specialized Agencies, and other UN organs and bodies.

Permanent Missions to the United Nations, No.307 United Nations DGACM,2019-02-22 This book serves as a directory of the Permanent Missions to the United Nations in New York, as well as a listing of their diplomatic personnel. It also includes information on Observer Offices, Specialized Agencies, and other UN organs and bodies.

Robust Environmental Perception and Reliability Control for Intelligent Vehicles Huihui Pan (Of Haerbin gong ye da xue),Jue Wang,Xinghu Yu,Weichao Sun,Huijun Gao,2024 This book presents the most recent state-of-the-art algorithms on robust environmental perception and reliability control for intelligent vehicle systems. By integrating object detection, semantic segmentation, trajectory prediction, multi-object tracking, multi-sensor fusion, and reliability control in a systematic way, this book is aimed at guaranteeing that intelligent vehicles can run safely in complex road traffic scenes. Adopts the multi-sensor data fusion-based neural networks to environmental perception fault tolerance algorithms, solving the problem of perception reliability when some sensors fail by using data redundancy. Presents the camera-based monocular approach to implement the robust perception tasks, which introduces sequential feature association and depth hint augmentation, and introduces seven adaptive methods. Proposes efficient and robust semantic segmentation of traffic scenes through real-time deep dual-resolution networks and representation separation of vision transformers. Focuses on trajectory prediction and proposes phased and progressive trajectory prediction methods that is more consistent with human psychological characteristics, which is able to take both social interactions and personal intentions into account. Puts forward methods based on conditional random field and multi-task segmentation learning to solve the robust multi-object tracking problem for environment perception in autonomous vehicle scenarios. Presents the novel reliability control strategies of intelligent vehicles to optimize the dynamic tracking performance and investigates the completely unknown autonomous vehicle tracking issues with actuator faults.--

Advances in Machine Learning and Cybernetics Daniel S. Yeung,Zhi-Qiang Liu,Xi-Zhao Wang,Hong Yan,2006-05-05 This book constitutes the thoroughly refereed post-proceedings of the 4th International Conference on Machine Learning and Cybernetics, ICMLC 2005, held in Guangzhou, China in August 2005. The 114 revised full papers of this volume are organized in topical sections on agents and distributed artificial intelligence, control, data mining and knowledge discovery, fuzzy information processing, learning and reasoning, machine learning applications, neural networks and statistical learning methods, pattern recognition, vision and image processing.

The 2nd International Workshop on Learning Technology for Education in Cloud Lorna Uden,Yu-Hui Tao,Hsin-Chang Yang,I-Hsien Ting,2013-08-24 Proceedings from the 2013 LTEC conference in Kaohsiung, Taiwan. The papers examine diverse aspects of Learning Technology for Education in Cloud environments, including social, technical and infrastructure implications. Also addressed is the question of how cloud computing can be used to design applications to support real time on demand learning using technologies. The workshop proceedings provide opportunities for delegates to discuss the latest research in TEL (Technology Enhanced Learning) and its impacts for learners and institutions, using cloud technologies.

Chemical Sensors Dnyandeo Karbhari Pawar,2023-12-01 Chemical sensors contain two basic functions: recognition and transduction, and provide real-time information about substances rather than physical quantities. Such devices are extensively utilized for various applications in diverse fields. The book focuses on the physical, chemical, optical, and electrical working mechanisms of different types of sensors integrated with various smart nanomaterials and composites. The mesmerizing properties of numerous materials and their fruitful applications for detecting numerous chemical parameters are discussed here. The book provides recent progress in the chemical sensors field and connects materials, physics, chemistry, and engineering, and therefore, is suitable for engineers, industrial, and academic researchers.

Recent Advances in Sliding Modes: From Control to Intelligent Mechatronics Xinghuo Yu,Mehmet Önder Efe,2015-04-10 This volume is dedicated to Professor Okyay Kaynak to commemorate his life time impactful research and scholarly achievements and outstanding services to profession. The 21 invited chapters have been written by leading researchers who, in the past, have had association with Professor Kaynak as either his students and associates or colleagues and collaborators. The focal theme of the volume is the Sliding Modes covering a broad scope of topics from theoretical investigations to their significant applications from Control to Intelligent Mechatronics.

Shipping in China Tae-Woo Lee, Mingnan Shen, 2017-03-02 The Chinese shipping industry is a particularly prominent industry and has rapidly expanded over the last decade. Amazingly, literature on the subject is scarce and this is the first book to focus on it specifically. Bringing together a team of well-known shipping, logistics, economics and political science scholars from the Far East, Europe and the Americas, the volume provides an up-to-date overview of the Chinese shipping industry and its place in international shipping. The contributors analyze and discuss all the relevant major business issues, including marketing, finance, the politics of its development and its organizational structures. The volume will be of critical interest to both academics and professionals in the fields of shipping and transport, transport economics, and business planning and strategy.

Index to Proceedings of the General Assembly 2018/2019, Part II - Index to Speeches Department of Global Communications, 2020-06-17 The Index to Proceedings of the General Assembly is a bibliographic guide to the proceedings and documentation of the General Assembly. This issue covers the seventy-third session of the Assembly including its Main and ad hoc committees. The Index is prepared by the Dag Hammarskjöld Library, Department of Global Communications, as one of the products of the United Nations Bibliographic Information System.

Educating Students with Autism Spectrum Disorder in China and Finland Xiaoyi Hu, Eija Kärnä, 2019-10-17 This book addresses the difficult challenges that children with autism present educators. By comprehensively examining the scientific knowledge underlying educational practices, programs and strategies in China and Finland, it provides valuable information for parents, administrators, researchers, and policy makers. This book examines the following fundamental issues related to the education of children with autism: •How children's specific diagnoses should affect educational assessment and planning •How we can support the families of children with autism •Features of effective instructional and comprehensive programs and strategies •How we can better prepare teachers, school staff, professionals and parents when it comes to educating children with autism •What policies at the national and local levels will best ensure appropriate education, examining strategies and resources needed to address the rights of children with autism to appropriate education

Industrial Engineering and Applications L.-C. Tang, 2023-08-09 The field of industrial engineering (IE) has a very wide scope, from production processes and automation to supply chain management, but the scope of IE techniques has expanded beyond the traditional domains of application, and is now relevant to areas that matter most to society at large. This book presents the proceedings of ICIEA 2023, the 10th International Conference on Industrial Engineering and Applications, held in Phuket, Thailand, from 4 to 6 April 2023. The conference was conducted in hybrid mode, with close to 100 delegates attending in person and about 50 participants attending online. A total of 272 submissions were received for the conference, of which 120 were accepted for presentation with 83 of those published here as full papers. These papers cover a wide range of topics within the scope of industrial and systems engineering, including but not limited to: supply chain and logistics; quality and reliability; advanced manufacturing; and production scheduling to ergonomics and man-machine systems interfaces. In particular, a significant number of papers are devoted to machine learning techniques and applications beyond the traditional manufacturing sector, to include healthcare, sustainability assessment, and other social issues. Offering an overview of recent research and novel applications, the book will be of interest to all those whose work involves the application of industrial engineering techniques.

Worldly Desires Brian Hu, 2018-09-26 Explores how internet use empowers Arab citizens.

Uncover the mysteries within Explore with is enigmatic creation, **GAOHUIJUAN** . This downloadable ebook, shrouded in suspense, is available in a PDF format (Download in PDF: *). Dive into a world of uncertainty and anticipation. Download now to unravel the secrets hidden within the pages.

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