

# Daisuke Sakamoto

Paula Kotzé, Gary Marsden, Gitte Lindgaard, Janet Wesson, Marco Winckler

*Geminoid Studies* Hiroshi Ishiguro, Fabio Dalla Libera, 2018-04-27 This book describes the teleoperated android Geminoid, which has a very humanlike appearance, movements, and perceptions, requiring unique developmental techniques. The book facilitates understanding of the framework of android science and how to use it in real human societies. Creating body parts of soft material by molding an existing person using a shape-memory form provides not only the humanlike texture of the body surface but also safe physical interaction, that is, humanlike interpersonal interaction between people and the android. The teleoperation also highlights novel effects in telecommunication. Operators of the Geminoid feel the robot's body as their own, and people encountering the teleoperated Geminoid perceive the robot's body as being possessed by the operator as well. Where does the feeling of human presence come from? Can we transfer or reproduce human presence by technology? Geminoid may help to answer these questions.

**Human-Robot Interaction in Social Robotics** Takayuki Kanda, Hiroshi Ishiguro, 2017-12-19 Human-Robot Interaction in Social Robotics explores important issues in designing a robot system that works with people in everyday environments. Edited by leading figures in the field of social robotics, it draws on contributions by researchers working on the Robovie project at the ATR Intelligent Robotics and Communication Laboratories, a world leader in humanoid interactive robotics. The book brings together, in one volume, technical and empirical research that was previously scattered throughout the literature. Taking a networked robot approach, the book examines how robots work in cooperation with ubiquitous sensors and people over telecommunication networks. It considers the use of social robots in daily life,

grounding the work in field studies conducted at a school, train station, shopping mall, and science museum. Critical in the development of network robots, these usability studies allow researchers to discover real issues that need to be solved and to understand what kinds of services are possible. The book tackles key areas where development is needed, namely, in sensor networks for tracking humans and robots, humanoids that can work in everyday environments, and functions for interacting with people. It introduces a sensor network developed by the authors and discusses innovations in the Robovie humanoid, including several interactive behaviors and design policies. Exploring how humans interact with robots in daily life settings, this book offers valuable insight into how robots may be used in the future. The combination of engineering, empirical, and field studies provides readers with rich information to guide in developing practical interactive robots.

Gaming, Simulations and Society International Simulation and Gaming Association. International Conference, R. Shiratori, K. Arai, F. Kato, 2005 Annotation This book presents a current research scope and perspective of Simulation and Gaming. Theoretical problems of Simulation and Gaming will be examined with a view to improving the social sciences through the introduction of the techniques and concepts of Simulation and Gaming. The fields of economics, political science, psychology and business management can all be radically improved by introducing such techniques of Simulation and Gaming as the Agent-Based Modelling. Other important topics are the analysis of philosophical foundations in Simulation and Gaming as an academic discipline. The ever growing and massive popularity of PC and arcade games cannot be ignored. Their potential as agents of education and their essentially violent nature raise many ethical and

moral problems that need to be addressed.

Graphics Interface 2014 Paul G. Kry, Andrea Bunt, 2020-11-25 This book is the proceedings of the 40th annual Graphics Interface conference-the oldest continuously scheduled conference in the field. The book includes high-quality papers on recent advances in interactive systems, human computer interaction, and graphics from around the world. It covers the following topics: shading and rendering, geometric modeling and meshing, image-based rendering, image synthesis and realism, computer animation, real-time rendering, non-photorealistic rendering, interaction techniques, human interface devices, augmented reality, data and information visualization, mobile computing, haptic and tangible interfaces, and perception.

Polymer Preprints, Japan ,2008

**Cognitive Robotics** Hooman Samani, 2015-10-16 The kimono-clad android robot that recently made its debut as the new greeter at the entrance of Tokyo's Mitsukoshi department store is just one example of the rapid advancements being made in the field of robotics. Cognitive robotics is an approach to creating artificial intelligence in robots by enabling them to learn from and respond to real-world situations, as opposed to pre-programming the robot with specific responses to every conceivable stimulus. Presenting the contributions of international experts from various disciplines within the field, Cognitive Robotics provides novel material and discusses advanced approaches in the field of intelligent robotics. It explains the various aspects of the topic to provide readers with a solid foundation on the subject. This edited collection presents theoretical research in cognitive robotics. It takes a multidisciplinary approach that considers the artificial intelligence, physical, chemical, philosophical, psychological, social, cultural, and ethical aspects of

this rapidly emerging field. The editor is a prominent researcher whose Lovotics research into emotional bonds with robots is widely recognized. Supplying an accessible introduction to cognitive robotics, the book considers computational intelligence for cognitive robotics based on informationally structured space. It examines how people respond to robots and what makes robots psychologically appealing to humans. The book contextualizes concepts in the history of studies on intelligence theories and includes case studies of different types of robots in action. Although ideal for robotics researchers and professionals, this book is also suitable for use as a supporting textbook in advanced robotics courses at both the undergraduate and graduate levels.

*Service Engineering for Gastronomic Sciences* Takeshi Shimmura, Tomomi Nonaka, Satomi Kunieda, 2020-06-23 This pioneering book on food study pursues an interdisciplinary approach to service science and the service engineering field. Further, it highlights a range of experiments conducted at actual business sites to verify the effectiveness of the proposed methodologies and theories. In modern society, food study has become more complex, as it involves multiple fields of science. For instance, a long-lived society entails a number of problems for human beings. A balanced intake of nutrients is important for a healthy life, but in many cases, healthy food is not the most enjoyable. As such, it is important for the food industry to provide foods that are both tasty and wholesome, based on the sciences of gastronomy and nutrition. Conventional food study proceeds along the lines of a specific field such as nutrition, agriculture, or gastronomy, though it should be conducted in an interdisciplinary manner. This book covers multifaceted research on food study to respond to today's societal demands, based mainly on the natural and

social sciences. It addresses a wide range of topics, including: food production management using mathematical modeling, operations research, and production engineering; evaluation of food products based on big data analysis; psychological experiments and ethnography; food products based on consumer behavior; organoleptic assessment and health improvement; design of physical dining environments using virtual reality, pedestrian debt recognition (human indoor position measuring), and observation of behavior. Reporting on and assessing many studies conducted at actual business locations, the book offers a unique and highly practical resource.

**Human-Robot Interaction** Christoph Bartneck, Tony Belpaeme, Friederike Eyssel, Takayuki Kanda, Merel Keijsers, Selma Šabanović, 2020-05-07 This broad overview for graduate students introduces multidisciplinary topics from robotics to sociology which are needed to understand the area.

**Advances in Computer Entertainment** Dennis Reidsma, Katayose Haruhiro, Anton Nijholt, 2013-11-08 This book constitutes the refereed conference proceedings of the 10th International Conference on Advances in Computer Entertainment, ACE 2013, held in Boekelo, The Netherlands, in November 2013. The 19 full paper and 16 short papers presented together 42 extended abstracts were carefully reviewed and selected from a total of 133 submissions in all categories. The papers cover topics across a wide spectrum of disciplines including new devices; evaluation and user studies; games as interface to serious applications; creating immersion; interfaces; new experiences; procedural approaches and AI; and theory. Focusing on all areas related to interactive entertainment they aim at stimulating discussion in the development of new and compelling entertainment computing and interactive art concepts and applications.

*Algorithmic Foundations of Robotics IX* David Hsu, Volkan Isler, Jean-Claude Latombe, Ming C. Lin, 2010-11-18 Robotics is at the cusp of dramatic transformation. Increasingly complex robots with unprecedented autonomy are finding new applications, from medical surgery, to construction, to home services. Against this background, the algorithmic foundations of robotics are becoming more crucial than ever, in order to build robots that are fast, safe, reliable, and adaptive. Algorithms enable robots to perceive, plan, control, and learn. The design and analysis of robot algorithms raise new fundamental questions that span computer science, electrical engineering, mechanical engineering, and mathematics. These algorithms are also finding applications beyond robotics, for example, in modeling molecular motion and creating digital characters for video games and architectural simulation. The Workshop on Algorithmic Foundations of Robotics (WAFR) is a highly selective meeting of leading researchers in the field of robot algorithms. Since its creation in 1994, it has published some of the field's most important and lasting contributions. This book contains the proceedings of the 9th WAFR, held on December 13-15, 2010 at the National University of Singapore. The 24 papers included in this book span a wide variety of topics from new theoretical insights to novel applications.

**Advances in Computer Entertainment Technology** Adrian David Cheok, Masahiko Inami, Teresa Romão, 2018-03-02 This book constitutes the refereed conference proceedings of the 14th International Conference on Advances in Computer Entertainment Technology, ACE 2017, held in London, UK, in December 2017. The 59 full papers presented were selected from a total of 229 submissions. ACE is by nature a multi-disciplinary conference, therefore attracting people across a wide spectrum of interests and

disciplines including computer science, design, arts, sociology, anthropology, psychology, and marketing. The main goal is to stimulate discussion in the development of new and compelling entertainment computing and interactive art concepts and applications. The chapter 'eSport vs irlSport' is open access under a CC BY 4.0 license via [link.springer.com](http://link.springer.com).

**Human-Computer Interaction -- INTERACT 2013** Paula Kotzé,Gary Marsden,Gitte Lindgaard,Janet Wesson,Marco Winckler,2013-07-30 The four-volume set LNCS 8117-8120 constitutes the refereed proceedings of the 14th IFIP TC13 International Conference on Human-Computer Interaction, INTERACT 2013, held in Cape Town, South Africa, in September 2013. The 57 papers included in the first volume are organized in topical sections on 3D navigation, 3D technologies - 3D object manipulation, augmented reality, cognitive workload, cognitive workload and decision support, creating effective 3D displays, cross-cultural, intercultural and social issues, data entry mechanisms and devices, design and evaluation, design and evaluation of prototypes, design to support creativity, designing for inclusiveness, designing with and for people with special needs, display manipulations, and diversity / ICT in social development.

An Introduction to Ethics in Robotics and AI Christoph Bartneck,Christoph Lütge,Alan Wagner,Sean Welsh,2020-08-11 This open access book introduces the reader to the foundations of AI and ethics. It discusses issues of trust, responsibility, liability, privacy and risk. It focuses on the interaction between people and the AI systems and Robotics they use. Designed to be accessible for a broad audience, reading this book does not require prerequisite technical, legal or philosophical expertise. Throughout, the authors use examples to illustrate the issues at hand and conclude the book with a discussion on the application areas



of AI and Robotics, in particular autonomous vehicles, automatic weapon systems and biased algorithms. A list of questions and further readings is also included for students willing to explore the topic further.

**Serviceology for Services** Yoshinori Hara,Dimitris Karagiannis,2017-06-30 This book constitutes the refereed proceedings of the 5th International Conference on Serviceology for Services, held in Vienna, Austria, in July 2017. The 21 full papers and one tutorial paper presented in this volume were carefully reviewed and selected from 75 submissions. The papers are organized around the following topics: human-centered service; customer satisfaction; service innovation and marketing; service design.

*SPSJ ... Annual Meeting* Kōbunshi Gakkai (Japan),Kōbunshi Gakkai (Japan),.2007

*Energy Research and Power Engineering* W.Y. Fan,2013-07-31 Collection of selected, peer reviewed papers from the 2013 International Conference on Energy Research and Power Engineering (ERPE 2013), May 24-25, 2013, Zhengzhou, Henan, China. The 303 papers are grouped as follows: Chapter 1: Advanced Technologies and Researches in Materials Science; Chapter 2: Advances in Mechanical Engineering; Chapter 3: Mechatronics, Control, Measurement and Monitoring. Technologies and Solutions; Chapter 4: Energy Industry. Engineering Researches and Management; Chapter 5: Materials and Technologies in Construction.

*Intelligent Autonomous Systems 8* Frans Groen,2004 Intelligent Autonomous systems are beginning to enter our daily life in ambient intelligence applications. These systems can directly sense and act in their own environment without demanding detailed supervision form humans. Many new challenges are emerging to create systems that can operate and interact in human inhabited environments. The goal of

IAS 8 is to exchange and stimulate research ideas about how to bring active, intelligent systems into our daily lives. This publications contains an excellent selection of papers that shows the research of autonomous systems today. Subjects discussed are the designing of autonomous agents, Artificial Emotional Creatures and Multi-Robot Coordination in Highly Dynamic Environments.

Index of Patents Issued from the United States Patent and Trademark Office ,1993

**Cognitive Robotics** Angelo Cangelosi, Minoru Asada, 2022-05-17 The current state of the art in cognitive robotics, covering the challenges of building AI-powered intelligent robots inspired by natural cognitive systems. A novel approach to building AI-powered intelligent robots takes inspiration from the way natural cognitive systems—in humans, animals, and biological systems—develop intelligence by exploiting the full power of interactions between body and brain, the physical and social environment in which they live, and phylogenetic, developmental, and learning dynamics. This volume reports on the current state of the art in cognitive robotics, offering the first comprehensive coverage of building robots inspired by natural cognitive systems. Contributors first provide a systematic definition of cognitive robotics and a history of developments in the field. They describe in detail five main approaches: developmental, neuro, evolutionary, swarm, and soft robotics. They go on to consider methodologies and concepts, treating topics that include commonly used cognitive robotics platforms and robot simulators, biomimetic skin as an example of a hardware-based approach, machine-learning methods, and cognitive architecture. Finally, they cover the behavioral and cognitive capabilities of a variety of models, experiments, and applications, looking at issues that range from intrinsic motivation and perception to robot consciousness. Cognitive

Robotics is aimed at an interdisciplinary audience, balancing technical details and examples for the computational reader with theoretical and experimental findings for the empirical scientist.

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