

WORLD ROBOTIC SYMPOSIUM 23


RAYMOND AUSTIN JARVIS, ALEX ZELINSKY


📖 **EXPERIMENTAL ROBOTICS** OUSSAMA KHATIB, VIJAY KUMAR, DANIELA RUS, 2008-02-26 THE INTERNATIONAL SYMPOSIUM ON EXPERIMENTAL ROBOTICS (ISER) IS A SERIES OF BI-ANNUAL MEETINGS WHICH ARE ORGANIZED IN A ROTATING FASHION AROUND NORTH AMERICA, EUROPE AND ASIA/OCEANIA. THE GOAL OF ISER IS TO PROVIDE A FORUM FOR RESEARCH IN ROBOTICS THAT FOCUSES ON THE NOVELTY OF THEORETICAL CONTRIBUTIONS VALIDATED BY EXPERIMENTAL RESULTS. THIS UNIQUE REFERENCE PRESENTS THE LATEST ADVANCES IN ROBOTICS, WITH IDEAS THAT ARE CONCEIVED CONCEPTUALLY AND HAVE BEEN EXPLORED EXPERIMENTALLY.


📖 **ROBOTICS RESEARCH** MASAYUKI INABA, PETER CORKE, 2016-04-22 THIS VOLUME PRESENTS A COLLECTION OF PAPERS PRESENTED AT THE 16TH INTERNATIONAL SYMPOSIUM OF ROBOTIC RESEARCH (ISRR). ISRR IS THE BIENNIAL MEETING OF THE INTERNATIONAL FOUNDATION OF ROBOTIC RESEARCH (IFRR) AND ITS 16TH EDITION TOOK PLACE IN SINGAPORE OVER THE PERIOD 16TH TO 19TH DECEMBER 2013. THE ISRR IS THE LONGEST RUNNING SERIES OF ROBOTICS RESEARCH MEETINGS AND DATES BACK TO THE VERY EARLIEST DAYS OF ROBOTICS AS A RESEARCH DISCIPLINE. THIS 16TH ISRR MEETING WAS HELD IN THE 30TH ANNIVERSARY YEAR OF THE VERY FIRST MEETING WHICH TOOK PLACE IN BRETTON WOODS (NEW HAMPSHIRE, USA) IN AUGUST 1983., AND REPRESENTS THIRTY YEARS AT THE FOREFRONT OF IDEAS IN ROBOTICS RESEARCH. AS FOR THE PREVIOUS SYMPOSIA, ISRR 2013 FOLLOWED UP ON THE SUCCESSFUL CONCEPT OF A MIXTURE OF INVITED CONTRIBUTIONS AND OPEN SUBMISSIONS. 16 OF THE CONTRIBUTIONS WERE INVITED CONTRIBUTIONS FROM OUTSTANDING RESEARCHERS SELECTED BY THE IFRR OFFICERS AND THE PROGRAM COMMITTEE, AND THE OTHER CONTRIBUTIONS WERE CHOSEN AMONG THE OPEN SUBMISSIONS AFTER PEER REVIEW. THIS SELECTION PROCESS RESULTED IN A TRULY EXCELLENT TECHNICAL PROGRAM WHICH FEATURED SOME OF THE VERY BEST OF ROBOTIC RESEARCH. THESE PAPERS WERE PRESENTED IN A SINGLE-TRACK INTERACTIVE FORMAT WHICH ENABLES REAL CONVERSATIONS BETWEEN SPEAKERS AND THE AUDIENCE. THE SYMPOSIUM CONTRIBUTIONS CONTAINED IN THIS VOLUME REPORT ON A VARIETY OF NEW ROBOTICS RESEARCH RESULTS COVERING A BROAD SPECTRUM ORGANIZED INTO TRADITIONAL ISRR CATEGORIES: CONTROL; DESIGN; INTELLIGENCE AND LEARNING; MANIPULATION; PERCEPTION; AND PLANNING.

📖 **ROBOTICS RESEARCH** JOHN M. HOLLERBACH, DANIEL E. KODITSCHKE, 2012-12-06 THIS BOOK IS THE PROCEEDINGS OF THE 9TH INTERNATIONAL SYMPOSIUM OF ROBOTICS RESEARCH, ONE OF THE OLDEST AND MOST PRESTIGIOUS CONFERENCES IN ROBOTICS. THE GOAL OF THE SYMPOSIUM WAS TO BRING TOGETHER ACTIVE, LEADING ROBOTICS RESEARCHERS FROM ACADEMIA, GOVERNMENT AND INDUSTRY, TO DEFINE THE STATE OF THE ART OF ROBOTICS AND ITS FUTURE DIRECTION. THE BROAD SPECTRUM OF ROBOTICS RESEARCH IS COVERED,


WITH AN EYE ON WHAT WILL BE IMPORTANT IN ROBOTICS IN THE NEXT MILLENNIUM.

 **ROBOTICS RESEARCH** Cédric Pradalier, Roland Siegwart, Gerhard Hirzinger, 2011-05-02 This volume presents a collection of papers presented at the 14th International Symposium of Robotic Research (ISRR). ISRR is the biennial meeting of the International Foundation of Robotic Research (IFRR) and its 14th edition took place in Lucerne, Switzerland, from August 31st to September 3rd, 2009. As for the previous symposia, ISRR 2009 followed up on the successful concept of a mixture of invited contributions and open submissions. Half of the 48 presentations were therefore invited contributions from outstanding researchers selected by the IFRR officers, and half were chosen among the 66 submissions after peer review. This selection process resulted in a truly excellent technical program which, we believe, featured some of the very best of robotic research. Out of the 48 presentations, the 42 papers which were finally submitted for publication are organized in 8 sections that encompass the major research orientations in robotics: navigation, control & planning, human-robot interaction, manipulation and humanoids, learning, mapping, multi-robot systems, and micro-robotics. They represent an excellent snapshot of cutting-edge research in robotics and outline future directions.

 **ROBOTICS RESEARCH** Nancy M. Amato, Greg Hager, Shawna Thomas, Miguel Torres-Torriti, 2019-11-28 ISRR, the International Symposium on Robotics Research, is one of robotics pioneering symposia, which has established over the past two decades some of the field's most fundamental and lasting contributions. This book presents the results of the eighteenth edition of Robotics Research ISRR 17, offering a collection of a broad range of topics in robotics. This symposium took place in Puerto Varas, Chile from December 11th to December 14th, 2017. The content of the contributions provides a wide coverage of the current state of robotics research, the advances and challenges in its theoretical foundation and technology basis, and the developments in its traditional and new emerging areas of applications. The diversity, novelty, and span of the work unfolding in these areas reveal the field's increased maturity and expanded scope and define the state of the art of robotics and its future direction.

 **ROBOTICS RESEARCH** Raymond Austin Jarvis, Alex Zelinsky, 2003-09-05 At the dawn of the new millennium, robotics is undergoing a major transformation in scope and dimension. From a largely dominant industrial focus, robotics is rapidly expanding into the challenges of unstructured environments. Interacting with, assisting, serving, and exploring with

HUMANS, THE EMERGING ROBOTS WILL INCREASINGLY TOUCH PEOPLE AND THEIR LIVES. THE GOAL OF THIS NEW SERIES OF SPRINGER TRACTS IN ADVANCED ROBOTICS IS TO BRING, IN A TIMELY FASHION, THE LATEST ADVANCES AND DEVELOPMENTS IN ROBOTICS ON THE BASIS OF THEIR SIGNIFICANCE AND QUALITY. IT IS OUR HOPETHAT THE GREATER DISSEMINATION OF RESEARCH DEVELOPMENTS WILL STIMULATE MORE EXCHANGES AND COLLABORATIONS AMONG THE RESEARCH COMMUNITY AND CONTRIBUTE TO FURTHER ADVANCEMENT OF THIS RAPIDLY GROWING FIELD. AS ONE OF ROBOTICS PIONEERING SYMPOSIA, ISRR, THE INTERNATIONAL SYMPOSIUM ON ROBOTICS RESEARCH, HAS ESTABLISHED OVER THE PAST TWO DECADES SOME OF THE FIELD'S MOST FUNDAMENTAL AND LASTING CONTRIBUTIONS. WITH THE LAUNCHING OF STAR, THIS AND OTHER THEMATIC SYMPOSIA DEVOTED TO EXCELLENCE IN ROBOTICS AND AN IMPORTANT PLATFORM FOR CLOSER LINKS AND EXTENDED REACH WITHIN THE RESEARCH COMMUNITY. THE TENTH EDITION OF ROBOTICS RESEARCH EDITED BY RAYMOND JARVIS AND ALEX ZELINSKY OFFERS IN ITS 11-PART VOLUME A COLLECTION OF A BROAD RANGE OF TOPICS IN ROBOTICS. THE CONTENT OF THESE CONTRIBUTIONS PROVIDES A WIDE COVERAGE OF THE CURRENT STATE OF ROBOTICS RESEARCH: THE ADVANCES AND CHALLENGES IN ITS THEORETICAL FOUNDATION AND TECHNOLOGY BASIS, AND THE DEVELOPMENTS IN ITS TRADITIONAL AND NEW AREAS OF APPLICATIONS.

 *EXPERIMENTAL ROBOTICS* OUSSAMA KHATIB, VIJAY KUMAR, GEORGE PAPPAS, 2009-08-29 BY THE DAWN OF THE NEW MILLENNIUM, ROBOTICS HAS UNDERGONE A MAJOR TRANSFORMATION IN SCOPE AND DIMENSIONS. THIS EXPANSION HAS BEEN BROUGHT ABOUT BY THE MATURITY OF THE FIELD AND THE ADVANCES IN ITS RELATED TECHNOLOGIES. FROM A LARGELY DOMINANT INDUSTRIAL FOCUS, ROBOTICS HAS BEEN RAPIDLY EXPANDING INTO THE CHALLENGES OF THE HUMAN WORLD. THE NEW GENERATION OF ROBOTS IS EXPECTED TO SAFELY AND DEPENDABLY CO-HABITAT WITH HUMANS IN HOMES, WORKPLACES, AND COMMUNITIES, PROVIDING SUPPORT IN SERVICES, ENTERTAINMENT, EDUCATION, HEALTHCARE, MANUFACTURING, AND ASSISTANCE. BEYOND ITS IMPACT ON PHYSICAL ROBOTS, THE BODY OF KNOWLEDGE ROBOTICS HAS PRODUCED IS REVEALING A MUCH WIDER RANGE OF APPLICATIONS REACHING ACROSS DIVERSE RESEARCH AREAS AND SCIENTIFIC DISCIPLINES, SUCH AS: BIOMECHANICS, HAPTICS, NEUROSCENCES, VIRTUAL SIMULATION, ANIMATION, SURGERY, AND SENSOR NETWORKS AMONG OTHERS. IN RETURN, THE CHALLENGES OF THE NEW EMERGING AREAS ARE PROVING AN ABUNDANT SOURCE OF STIMULATION AND INSIGHTS FOR THE FIELD OF ROBOTICS. IT IS INDEED AT THE INTERSECTION OF DISCIPLINES THAT THE MOST STRIKING ADVANCES HAPPEN. THE GOAL OF THE SERIES OF SPRINGER TRACTS IN ADVANCED ROBOTICS (STAR) IS TO BRING, IN A TIMELY FASHION, THE LATEST ADVANCES AND

DEVELOPMENTS IN ROBOTICS ON THE BASIS OF THEIR SIGNIFICANCE AND QUALITY. IT IS OUR HOPE THAT THE WIDER DISSEMINATION OF RESEARCH DEVELOPMENTS WILL STIMULATE MORE EXCHANGES AND COLLABORATIONS AMONG THE RESEARCH COMMUNITY AND CONTRIBUTE TO FURTHER ADVANCEMENT OF THIS RAPIDLY GROWING FIELD.

📖 **ROBOTICS RESEARCH** SEBASTIAN THRUN, RODNEY A. BROOKS, HUGH DURRANT-WHYTE, 2007-05-16 THIS VOLUME CONTAINS 50 PAPERS PRESENTED AT THE 12TH INTERNATIONAL SYMPOSIUM OF ROBOTICS RESEARCH, WHICH TOOK PLACE OCTOBER 2005 IN SAN FRANCISCO, CA. COVERAGE INCLUDES: PHYSICAL HUMAN-ROBOT INTERACTION, HUMANIDS, MECHANISMS AND DESIGN, SIMULTANEOUS LOCALIZATION AND MAPPING, FIELD ROBOTS, ROBOTIC VISION, ROBOT DESIGN AND CONTROL, UNDERWATER ROBOTICS, LEARNING AND ADAPTIVE BEHAVIOR, NETWORKED ROBOTICS, AND INTERFACES AND INTERACTION.

📖 **EXPERIMENTAL ROBOTICS IX** MARCELO H. ANG, OUSSAMA KHATIB, 2006-03-09 THE INTERNATIONAL SYMPOSIUM ON EXPERIMENTAL ROBOTICS (ISER) IS A SERIES OF BI-ANNUAL MEETINGS WHICH ARE ORGANIZED IN A ROTATING FASHION AROUND NORTH AMERICA, EUROPE AND ASIA/OCEANIA. THE GOAL OF ISER IS TO PROVIDE A FORUM FOR RESEARCH IN ROBOTICS THAT FOCUSES ON NOVELTY OF THEORETICAL CONTRIBUTIONS VALIDATED BY EXPERIMENTAL RESULTS. THE MEETINGS ARE CONCEIVED TO BRING TOGETHER, IN A SMALL GROUP SETTING, RESEARCHERS FROM AROUND THE WORLD WHO ARE IN THE FOREFRONT OF EXPERIMENTAL ROBOTICS RESEARCH. THIS UNIQUE REFERENCE PRESENTS THE LATEST ADVANCES ACROSS THE VARIOUS FIELDS OF ROBOTICS, WITH IDEAS THAT ARE NOT ONLY CONCEIVED CONCEPTUALLY BUT ALSO VERIFIED EXPERIMENTALLY. IT COLLECTS CONTRIBUTIONS ON THE CURRENT DEVELOPMENTS AND NEW DIRECTIONS IN THE FIELD OF EXPERIMENTAL ROBOTICS, WHICH ARE BASED ON THE PAPERS PRESENTED AT THE NINTH ISER HELD IN SINGAPORE.

📖 **EXPERIMENTAL ROBOTICS** OUSSAMA KHATIB, VIJAY KUMAR, GAURAV SUKHATME, 2013-08-20 INCORPORATING PAPERS FROM THE 12TH INTERNATIONAL SYMPOSIUM ON EXPERIMENTAL ROBOTICS (ISER), DECEMBER 2010, THIS BOOK EXAMINES THE LATEST ADVANCES ACROSS THE VARIOUS FIELDS OF ROBOTICS. OFFERS INSIGHTS ON BOTH THEORETICAL CONCEPTS AND EXPERIMENTAL RESULTS.

📖 **DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS** M. ANI HSIEH, GREGORY CHIRIKJIAN, 2014-06-07 DISTRIBUTED ROBOTICS IS A RAPIDLY GROWING AND MATURING INTERDISCIPLINARY RESEARCH AREA LYING AT THE INTERSECTION OF COMPUTER SCIENCE, NETWORK SCIENCE, CONTROL THEORY, AND ELECTRICAL AND MECHANICAL ENGINEERING. THE GOAL OF THE SYMPOSIUM ON DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS (DARS) IS TO EXCHANGE AND STIMULATE RESEARCH IDEAS TO REALIZE ADVANCED DISTRIBUTED ROBOTIC SYSTEMS. THIS

VOLUME OF PROCEEDINGS INCLUDES 31 ORIGINAL CONTRIBUTIONS PRESENTED AT THE 2012 INTERNATIONAL SYMPOSIUM ON DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS (DARS 2012) HELD IN NOVEMBER 2012 AT THE JOHNS HOPKINS UNIVERSITY IN BALTIMORE, MD USA. THE SELECTED PAPERS IN THIS VOLUME ARE AUTHORED BY LEADING RESEARCHERS FROM ASIA, EUROPA, AND THE AMERICAS, THEREBY PROVIDING A BROAD COVERAGE AND PERSPECTIVE OF THE STATE-OF-THE-ART TECHNOLOGIES, ALGORITHMS, SYSTEM ARCHITECTURES, AND APPLICATIONS IN DISTRIBUTED ROBOTIC SYSTEMS. THE BOOK IS ORGANIZED INTO FIVE PARTS, REPRESENTATIVE OF CRITICAL LONG-TERM AND EMERGING RESEARCH THRUSTS IN THE MULTI-ROBOT COMMUNITY: COORDINATION FOR PERCEPTION, COVERAGE, AND TRACKING; TASK ALLOCATION AND COORDINATION STRATEGIES; MODULAR ROBOTS AND NOVEL MECHANISMS AND SENSORS; FORMATION CONTROL AND PLANNING FOR ROBOT TEAMS; AND LEARNING, ADAPTATION, AND COGNITION FOR ROBOT TEAMS.

📄 ROBOTICS RESEARCH GEORGES GIRALT, GERHARD HIRZINGER, 2012-12-06
THIS PUBLICATION COVERS ALL THE TOPICS WHICH ARE RELEVANT TO ADVANCED ROBOTICS TODAY, RANGING FROM SYSTEMS DESIGN TO REASONING AND PLANNING. IT IS BASED ON THE SEVENTH INTERNATIONAL SYMPOSIUM ON ROBOTICS RESEARCH HELD IN GERMANY ON OCTOBER, 21 - 24TH, 1995. THE PAPERS WERE WRITTEN BY SPECIALISTS IN THE FIELD FROM THE UNITED STATES, EUROPE, JAPAN, AUSTRALIA AND CANADA. THE EDITORS, WHO ALSO CHAIRED THIS SYMPOSIUM, PRESENT THE LATEST RESEARCH RESULTS AS WELL AS NEW APPROACHES TO LONG STANDING PROBLEMS. ROBOTICS RESEARCH IS A CONTRIBUTION TO THE EMERGING CONCEPTS, METHODS AND TOOLS THAT SHAPE ROBOTICS. THE PAPERS RANGE FROM PURE RESEARCH REPORTS TO APPLICATION-ORIENTED STUDIES. THE TOPICS COVERED INCLUDE: MANIPULATION, CONTROL, VIRTUAL REALITY, MOTION PLANNING, 3D VISION AND INDUSTRIAL SYSTEMS' ISSUES.

📄 DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS ALCHERIO MARTINOLI, FRANCESCO MONDADA, NIKOLAUS CORRELL, GR📄 GORY MERMOUD, MAGNUS EGERSTEDT, M. ANI HSIEH, LYNNE E. PARKER, KASPER ST📄 Y, 2012-09-05 DISTRIBUTED ROBOTICS IS A RAPIDLY GROWING, INTERDISCIPLINARY RESEARCH AREA LYING AT THE INTERSECTION OF COMPUTER SCIENCE, COMMUNICATION AND CONTROL SYSTEMS, AND ELECTRICAL AND MECHANICAL ENGINEERING. THE GOAL OF THE SYMPOSIUM ON DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS (DARS) IS TO EXCHANGE AND STIMULATE RESEARCH IDEAS TO REALIZE ADVANCED DISTRIBUTED ROBOTIC SYSTEMS. THIS VOLUME OF PROCEEDINGS INCLUDES 43 ORIGINAL CONTRIBUTIONS PRESENTED AT THE TENTH INTERNATIONAL SYMPOSIUM ON DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS (DARS 2010), WHICH WAS HELD IN NOVEMBER 2010 AT THE 📄 COLE POLYTECHNIQUE F📄 D📄 RALE DE LAUSANNE (EPFL), SWITZERLAND. THE SELECTED

PAPERS IN THIS VOLUME ARE AUTHORED BY LEADING RESEARCHERS FROM ASIA, EUROPA, AND THE AMERICAS, THEREBY PROVIDING A BROAD COVERAGE AND PERSPECTIVE OF THE STATE-OF-THE-ART TECHNOLOGIES, ALGORITHMS, SYSTEM ARCHITECTURES, AND APPLICATIONS IN DISTRIBUTED ROBOTIC SYSTEMS. THE BOOK IS ORGANIZED INTO FOUR PARTS, EACH REPRESENTING ONE CRITICAL AND LONG-TERM RESEARCH THRUST IN THE MULTI-ROBOT COMMUNITY: DISTRIBUTED SENSING (PART I); LOCALIZATION, NAVIGATION, AND FORMATIONS (PART II); COORDINATION ALGORITHMS AND FORMAL METHODS (PART III); MODULARITY, DISTRIBUTED MANIPULATION, AND PLATFORMS (PART IV).

📖 ROBOTICS RESEARCH TAMIM ASFOUR, EIICHI YOSHIDA, JAEHEUNG PARK, HENRIK CHRISTENSEN, OUSSAMA KHATIB, 2022-02-17 THIS BOOK CONTAINS THE PAPERS THAT WERE PRESENTED AT THE 17TH INTERNATIONAL SYMPOSIUM OF ROBOTICS RESEARCH (ISRR). THE ISRR PROMOTES THE DEVELOPMENT AND DISSEMINATION OF GROUNDBREAKING RESEARCH AND TECHNOLOGICAL INNOVATION IN ROBOTICS USEFUL TO SOCIETY BY PROVIDING A LIVELY, INTIMATE, FORWARD-LOOKING FORUM FOR DISCUSSION AND DEBATE ABOUT THE CURRENT STATUS AND FUTURE TRENDS OF ROBOTICS WITH GREAT EMPHASIS ON ITS POTENTIAL ROLE TO BENEFIT HUMANKIND. THE SYMPOSIUM CONTRIBUTIONS CONTAINED IN THIS BOOK REPORT ON A VARIETY OF NEW ROBOTICS RESEARCH RESULTS COVERING A BROAD SPECTRUM ORGANIZED INTO THE CATEGORIES: DESIGN, CONTROL; GRASPING AND MANIPULATION, PLANNING, ROBOT VISION, AND ROBOT LEARNING.

📖 DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS FUMITOSHI MATSUNO, SHUN-ICHI AZUMA, MASAHITO YAMAMOTO, 2022-01-03 THIS BOOK PRESENTS THE STATE OF THE ART IN DISTRIBUTED AUTONOMOUS SYSTEMS COMPOSED OF MULTIPLE ROBOTS, ROBOTIC MODULES, OR ROBOTIC AGENTS. SWARMS IN NATURE CAN NOT ONLY ADAPT TO THEIR ENVIRONMENTS, BUT CAN ALSO CONSTRUCT SUITABLE HABITATS TO THEIR OWN ADVANTAGE. DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS CAN DO MANY THINGS THAT ITS INDIVIDUALS CANNOT DO ALONE. AS THE GLOBAL PANDEMIC WAS STILL ONGOING, THE 15TH INTERNATIONAL SYMPOSIUM ON DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS (DARS2021) WAS HELD ON JUNE 1-4, 2021, AS AN ONLINE MEETING. THE SCOPE OF DARS2021 WAS TO CREATE A BRIDGE BETWEEN BIOLOGISTS AND ENGINEERS INTERESTED IN THE DISTRIBUTED INTELLIGENCE OF LIVING THINGS AND TO ESTABLISH A NEW ACADEMIC FIELD BY INTEGRATING KNOWLEDGE FROM BOTH DISCIPLINES. TOPICS OF DARS2021 WERE SWARM INTELLIGENCE, SWARM ROBOTICS, MULTI-AGENT SYSTEM, MODULAR ROBOTICS, DECENTRALIZED CONTROL, DISTRIBUTED SYSTEM, ETC. THE PAPERS IN THIS BOOK PROVIDE A VERY GOOD OVERVIEW OF THE STATE OF THE ART IN DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS (DARS). THEY REFLECT CURRENT RESEARCH THEMES IN DARS WITH IMPORTANT CONTRIBUTIONS. WE HOPE THAT THIS BOOK HELPS TO SUSTAIN THE INTEREST IN DARS AND TRIGGERS NEW

RESEARCH.

📖 **DISTRIBUTED AUTONOMOUS ROBOTIC SYSTEMS** Roderich Gro📖, Andreas Kolling, Spring Berman, Emilio Frazzoli, Alcherio Martinoli, Fumitoshi Matsuno, Melvin Gauci, 2018-03-13 Distributed robotics is an interdisciplinary and rapidly growing area, combining research in computer science, communication and control systems, and electrical and mechanical engineering. Distributed robotic systems can autonomously solve complex problems while operating in highly unstructured real-world environments. They are expected to play a major role in addressing future societal needs, for example, by improving environmental impact assessment, food supply, transportation, manufacturing, security, and emergency and rescue services. The goal of the International Symposium on Distributed Autonomous Robotic Systems (DARS) is to provide a forum for scientific advances in the theory and practice of distributed autonomous robotic systems. This volume of proceedings include 47 original contributions presented at the 13th International Symposium on Distributed Autonomous Robotic Systems (DARS 2016), which was held at the Natural History Museum in London, UK, from November 7th to 9th, 2016. The selected papers in this volume are authored by leading researchers from around the world, thereby providing a broad coverage and perspective of the state-of-the-art technologies, algorithms, system architectures, and applications in distributed robotic systems. The book is organized into seven parts, representative of critical long-term and emerging research thrusts in the multi-robot community: Distributed Coverage and Exploration; Multi-Robot Control; Multi-Robot Estimation; Multi-Robot Planning; Modular Robots and Smart Materials; Swarm Robotics; and Multi-Robot Systems in Applications.

📖 **EXPERIMENTAL ROBOTICS** Oussama Khatib, Vijay Kumar, Daniela Rus, 2009-09-03 The International Symposium on Experimental Robotics (ISER) is a series of bi-annual meetings which are organized in a rotating fashion around North America, Europe and Asia/Oceania. The goal of ISER is to provide a forum for research in robotics that focuses on the novelty of theoretical contributions validated by experimental results. This unique reference presents the latest advances in robotics, with ideas that are conceived conceptually and have been explored experimentally.

📖 **EUROPEAN ROBOTICS SYMPOSIUM 2008** Herman Bruyninckx, Libor Preucil, Miroslav Kulich, 2008-02-12 At the dawn of the new millennium, robotics is undergoing a major transformation in scope and dimension. From a largely dominant industrial focus, robotics is rapidly expanding into the challenges of unstructured environments. Interacting with, assi-

ING, SERVING, AND EXPLORING WITH HUMANS, THE EMERGING ROBOTS WILL INCREASINGLY TOUCH PEOPLE AND THEIR LIVES. THE GOAL OF THE SPRINGER TRACTS IN ADVANCED ROBOTICS (STAR) SERIES IS TO BRING, IN A TIMELY FASHION, THE LATEST ADVANCES AND DEVELOPMENTS IN ROBOTICS ON THE BASIS OF THEIR SIGNIFICANCE AND QUALITY. IT IS OUR HOPE THAT THE WIDER DISSEMINATION OF RESEARCH - VELOPMENTS WILL STIMULATE MORE EXCHANGES AND COLLABORATIONS AMONG THE RESEARCH COMMUNITY AND CONTRIBUTE TO FURTHER ADVANCEMENT OF THIS RAPIDLY GROWING FIELD. THE EUROPEAN ROBOTICS SYMPOSIUM (EUROS) WAS LAUNCHED IN 2006 AS AN INTER- TIONAL SCIENTIFIC SINGLE-TRACK EVENT PROMOTED BY EURON, THE EUROPEAN ROBOTICS NETWORK LINKING MOST OF THE EUROPEAN RESEARCH TEAMS SINCE ITS INCEPTION IN 2000. SINCE THEN, EUROS HAS FOUND ITS PARENTAL HOME UNDER STAR, TOGETHER WITH THE OTHER THEMATIC SYMPOSIA DEVOTED TO EXCELLENCE IN ROBOTICS RESEARCH: FSR, ISER, ISRR, WAFR.

ROBOTICS RESEARCH MAKOTO KANEKO, YOSHIHIKO NAKAMURA, 2010-11-07
THE INTERNATIONAL SYMPOSIUM OF ROBOTICS RESEARCH (ISRR) CONTINUES TO BE THE PREMIERE MEETING OF THE INTERNATIONAL FOUNDATION OF ROBOTICS RESEARCH (IFRR). THE 13TH INTERNATIONAL SYMPOSIUM OF ROBOTICS RESEARCH TOOK PLACE NOVEMB3R 26-29, 2007, IN HIROSHIMA, JAPAN, AND WAS ORGANIZED BY THE TWO EDITORS OF THIS BOOK. THIS VOLUME BRINGS A COLLECTION OF A BROAD RANGE OF TOPICS IN ROBOTICS. THE CONTENT OF THESE CONTRIBUTIONS PROVIDES A WIDE COVERAGE OF THE CURRENT STATE OF ROBOTICS RESEARCH: THE ADVANCES AND CHALLENGES IN ITS THEORETICAL FOUNDATION AND TECHNOLOGY BASIS, AND THE DEVELOPMENTS IN ITS TRADITIONAL AND NOVEL AREAS OF APPLICATIONS. HISTORICALLY, THE PROCEEDINGS OF THE ISRR HAVE FEATURED GROUND-BREAKING WORK OF THE HIGHEST CALIBER, WHICH INFLUENCED GENERATIONS TO COME. THE PRESENT VOLUME PROMISES TO BE NO EXCEPTION. THE COLLECTION OF SCIENTIFIC ARTICLES IN THIS VOLUME PROVIDES NEW INSIGHTS TO IMPORTANT PROBLEMS IN ROBOTICS, WRITTEN BY SOME OF THE LEADERS IN THE FIELD.

ROMANSY 21 - ROBOT DESIGN, DYNAMICS AND CONTROL VINCENZO PARENTI-CASTELLI, WERNER SCHIEHLEN, 2016-06-29
THIS PROCEEDINGS VOLUME CONTAINS PAPERS THAT HAVE BEEN SELECTED AFTER REVIEW FOR ORAL PRESENTATION AT ROMANSY 2016, THE 21TH CISM-IFTOMM SYMPOSIUM ON THEORY AND PRACTICE OF ROBOTS AND MANIPULATORS. THESE PAPERS COVER ADVANCES ON SEVERAL ASPECTS OF THE WIDE FIELD OF ROBOTICS AS CONCERNING THEORY AND PRACTICE OF ROBOTS AND MANIPULATORS. ROMANSY 2016 IS THE 21ST EVENT IN A SERIES THAT STARTED IN 1973 AS ONE OF THE FIRST CONFERENCE ACTIVITIES IN THE WORLD ON ROBOTICS. THE FIRST EVENT WAS HELD AT CISM (INTERNATIONAL CENTRE FOR MECHANICAL SCIENCE) IN UDINE, ITALY ON

5-8 SEPTEMBER 1973. IT WAS ALSO THE FIRST TOPIC CONFERENCE OF IFTOMM (INTERNATIONAL FEDERATION FOR THE PROMOTION OF MECHANISM AND MACHINE SCIENCE) AND IT WAS DIRECTED NOT ONLY TO THE IFTOMM COMMUNITY.

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WORLD ROBOTIC SYMPOSIUM 23 INTRODUCTION

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