

Twheels

Matthew Syed

Design and Simulation of Rail Vehicles Maksym Spiryagin,Colin Cole,Yan Quan Sun,Mitchell McClanachan,Valentyn Spiryagin,Tim McSweeney,2014-05-13 Keep Up with Advancements in the Field of Rail Vehicle Design A thorough understanding of the issues that affect dynamic performance, as well as more inventive methods for controlling rail vehicle dynamics, is needed to meet the demands for safer rail vehicles with higher speed and loads. Design and Simulation of Rail Vehicles examines the field of rail vehicle design, maintenance, and modification, as well as performance issues related to these types of vehicles. This text analyzes rail vehicle design issues and dynamic responses, describes the design and features of rail vehicles, and introduces methods that address the operational conditions of this complex system. Progresses from Basic Concepts and Terminology to Detailed Explanations and Techniques Focused on both non-powered and powered rail vehicles—freight and passenger rolling stock, locomotives, and self-powered vehicles used for public transport—this book introduces the problems involved in designing and modeling all types of rail vehicles. It explores the applications of vehicle dynamics, train operations, and track infrastructure maintenance. It introduces the fundamentals of locomotive design, multibody dynamics, and longitudinal train dynamics, and discusses co-simulation techniques. It also highlights recent advances in rail vehicle design, and contains applicable standards and acceptance tests from around the world. • Includes multidisciplinary simulation approaches • Contains an understanding of rail vehicle design and simulation techniques • Establishes the connection between theory and many simulation examples • Presents simple to advanced rail vehicle design and simulation methodologies Design and Simulation of Rail Vehicles serves as an introductory text for graduate or senior undergraduate students, and as a reference for practicing engineers and researchers investigating performance issues related to these types of vehicles.

Design and Simulation of Heavy Haul Locomotives and Trains Maksym Spiryagin,Peter Wolfs,Colin Cole,Valentyn Spiryagin,Yan Quan Sun,Tim McSweeney,2016-10-03 With the increasing demands for safer freight trains operating with higher speed and higher loads, it is necessary to implement methods for controlling longer, heavier trains. This requires a full understanding of the factors that affect their dynamic performance. Simulation techniques allow proposed innovations to be optimised before introducing them into the operational railway environment. Coverage is given to the various types of locomotives used with heavy haul freight trains, along with the various possible configurations of those trains. This book serves as an introductory text for college students, and as a reference for engineers practicing in heavy haul rail network design,

Farm Machinery and Equipment ,1920

Vehicle Dynamics and Control Rajesh Rajamani,2011-12-21 Vehicle Dynamics and Control provides a comprehensive coverage of vehicle control systems and the dynamic models used in the development of these control systems. The control system applications covered in the book include cruise control, adaptive cruise control, ABS, automated lane keeping, automated highway systems, yaw stability control, engine control, passive, active and semi-active suspensions, tire-road friction coefficient estimation, rollover prevention, and hybrid electric vehicles. In developing the dynamic model for each application, an effort is made to both keep the model simple enough for control system design but at the same time rich enough to capture the essential features of the dynamics. A special effort has been made to explain the several different tire models commonly used in literature and to interpret them physically. In the second edition of the book, chapters on roll dynamics, rollover prevention and hybrid electric vehicles have been added, and the chapter on electronic stability control has been enhanced. The use of feedback control systems on automobiles is growing rapidly. This book is intended to serve as a useful resource to researchers who work on the development of such control systems, both in the automotive industry and at universities. The book can also serve as a textbook for a graduate level course on Vehicle Dynamics and Control.

Chilton Tractor & Equipment Journal ,1920

Chilton Tractor & Implement Journal ,1920

Farm Implement News ,1898

The Country Gentleman ,1919

4th ESA International Conference on Spacecraft Guidance, Navigation and Control Systems and Tutorial on Modern and Robust Control: Theory, Tools and Applications B. Schürmann,European Space Agency,2000

Implement & Tractor Trade Journal ,1919 Jan. 31, 1967– lists Nebraska tractor tests.

Artificial Intelligence in Design '96 John S. Gero,Fay Sudweeks,2012-12-06 Change is one of the most significant parameters in our society. Designers are amongst the primary change agents for any society. As a consequence design is an important research topic in engineering and architecture and related disciplines, since design is not only a means of change but is also one of the keystones to economic competitiveness and the fundamental precursor to manufacturing. The development of computational models founded on the artificial intelligence paradigm has provided an impetus for much of current design research –both computational and cognitive. These forms of design research have only been carried out in the last decade or so and in the temporal sense they are still immature. Notwithstanding this immaturity, noticeable advances have been made both in extending our understanding of design and in developing tools based on that understanding. Whilst many researchers in the field of artificial intelligence in design utilise ideas about how humans design as one source of concepts there is normally no attempt to model human designers. Rather the results of the research presented in this volume demonstrate approaches to increasing our understanding of design as a process.

Agents and Artificial Intelligence Jaap van den Herik,Ana Paula Rocha,2018-12-30 This book contains the revised and extended versions of selected papers from the 10th International Conference, ICAART 2018, held in Funchal, Madeira, Portugal, in January 2018. The 45 full papers together with 42 short papers and 26 Posters were carefully reviewed and selected from 161 initial submissions. The papers are organized in topics such as Agents, Artificial Intelligence, Semantic Web, Multi-Agent Systems, Distributed Problem Solving, Agent Communication and much more.

Logic Programming and Nonmonotonic Reasoning Vladimir Lifschitz,Ilkka Niemelä,2003-11-20 This book constitutes the refereed proceedings of the 7th International Conference on Logic Programming and Nonmonotonic Reasoning, LPNMR 2004, held in Fort Lauderdale, Florida, USA in January 2004. The 24 revised full papers presented together with 8 system descriptions were carefully reviewed and selected for presentation. Among the topics addressed are declarative logic programming, nonmonotonic reasoning, knowledge representation, combinatorial search, answer set programming, constraint programming, deduction in ontologies, and planning.

Votes & Proceedings New South Wales. Parliament. Legislative Council,1887

Rebel Ideas Matthew Syed,2021-05-11 Ideas are everywhere, but those with the greatest problem-solving, business-transforming, and life-changing potential are often hard to identify. Even when we recognize good ideas, applying them to everyday obstacles—whether in the workplace, our homes, or our civic institutions—can seem insurmountable. According to Matthew Syed, it doesn't have to be this way. In *Rebel Ideas*, Syed argues that our brainpower as individuals isn't enough. To tackle problems from climate change to economic decline, we'll need to employ the power of cognitive diversity. Drawing on psychology, genetics, and beyond, Syed uses real-world scenarios including the failings of the CIA before 9/11 and a communication disaster at the peak of Mount Everest to introduce us to the true power of thinking

differently. Rebel Ideas will strengthen any kind of team, while including advice on how, as individuals, we can embrace the potential of an outsider mind-set as our greatest asset. Matthew Syed is the Sunday Times bestselling author of Black Box Thinking, Bounce, and The Greatest. He writes an award-winning newspaper column in The Times and is the host of the hugely successful BBC podcast Flintoff, Savage and the Ping Pong Guy.

Oil Field Engineering ,1916

Biomedical Aspects of Manual Wheelchair Propulsion L. H. V. van der Woude,Maria T. E. Hopman,Cathelijne H. Kemenade,1999 Mobility is fundamental to health, social integration and individual well-being of the human being. Henceforth, mobility must be viewed as being essential to the outcome of the rehabilitation process of wheelchair dependent persons and to the successful (re-)integration into society and to a productive and active life. Many lower limb disabled subjects depend upon a wheelchair for their mobility. Estimated numbers for the Netherlands, Europe and USA are respectively 80.000, 2,5 million and 1,25 million wheelchair dependent individuals. Groups large enough to allow a special research focus and conference activity. Both the quality of the wheelchair, the individual work capacity, the functionality of the wheelchair/user combination, and the effectiveness of the rehabilitation programme do indeed determine the freedom of mobility. Their optimization is highly dependent upon a continuous and high quality research effort, in combination with regular discussion and dissemination with practitioners. The book intends to give a state of the art view on the current fundamental, clinical and applied research findings and their consequences upon wheelchair propulsion, arm work, wheelchair training and possible consequences of a wheelchair confined life style. Also its implications for rehabilitation, as well as alternative modes of ambulation and activity in the wheelchair confined population, such as functional electrical stimulation and its possible future developments, are dealt with.

Gas Engine ,1916

Introduction to the Mechanics of Space Robots Giancarlo Genta,2011-10-27 Based on lecture notes on a space robotics course, this book offers a pedagogical introduction to the mechanics of space robots. After presenting an overview of the environments and conditions space robots have to work in, the author discusses a variety of manipulatory devices robots may use to perform their tasks. This is followed by a discussion of robot mobility in these environments and the various technical approaches. The last two chapters are dedicated to actuators, sensors and power systems used in space robots. This book fills a gap in the space technology literature and will be useful for students and for those who have an interest in the broad and highly interdisciplinary field of space robotics, and in particular in its mechanical aspects.

Smart Charging and Anti-Idling Systems Yanjun Huang,Soheil Mohagheghi Fard,Milad Khazraee,Hong Wang,Amir Khajepour,2022-05-31 As public attention on energy conservation and emission reduction has increased in recent years, engine idling has become a growing concern due to its low efficiency and high emissions. Service vehicles equipped with auxiliary systems, such as refrigeration, air conditioning, PCs, and electronics, usually have to idle to power them. The number of service vehicles (e.g. public-school-tour buses, delivery-refrigerator trucks, police cars, ambulances, armed vehicles, firefighter vehicles) is increasing significantly with tremendous social development. Therefore, introducing new anti-idling solutions is inevitably vital for controlling energy unsustainability and poor air quality. There are a few books about the idling disadvantages and anti-idling solutions. Most of them are more concerned with different anti-idling technologies and their effects on the society rather than elaborating an anti-idling system design considering different applications and limitations. There is still much room to improve existing anti-idling technologies and products. In this book, we took a service vehicle, refrigerator truck, as an example to demonstrate the whole process of designing, optimizing, controlling, and developing a smart charging system for the anti-idling purpose. The proposed system cannot only electrify the auxiliary systems to achieve anti-idling, but also utilize the concepts of regenerative braking and optimal charging strategy to arrive at an optimum solution. Necessary tools, algorithms, and methods are illustrated and the benefits of the optimal anti-idling solution are evaluated.

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