Traffic Hybrid System

Cliff Jones,Ji Wang,Naijun Zhan

Mean_field Limit of a Hybrid System for Multi-lane Multi-class Traffic Xiaoqian Gong,Benedetto Piccoli,Giuseppe Visconti,2020

Symposium on Real-Time and Hybrid Systems Cliff Jones,Ji Wang,Naijun Zhan,2018-09-28 This volume is published in honor of Professor Chaochen Zhou's 80th birthday. The Festschrift contains 13 refereed papers by leading researchers who were among the participants of the celebratory conference in Changsha, China that took place in October 2017. The papers cover a broad spectrum of subjects related to Formal Methods for the development of computer systems. Topics include Probabilistic Programming, Concurrency, Quantum Computing, Domain Engineering, Real-time and Hybrid Systems, and Cloud Computing. Chaochen Zhou is internationally recognized for his own contributions and for the wide influence that he has had through his appointments in Oxford (UK) where he collaborated with Professor Tony Hoare, Lyngby (Denmark) where he worked with Professor Dines Bjørner, UNU-IIST (Macau) where he moved from being Principal Research Fellow to his appointed as Director of the Institute, as well as in Beijing. His book on the Duration Calculus (joint with Michael Hansen) made a seminal contribution to specifying and reasoning about real-time systems. Chaochen Zhou's contributions have been marked by his election as a member of the Chinese Academy of Sciences.

Cognitive mechanisms for safe road traffic systems Giovanni Vecchiato,Lewis L. Chuang,Christer Ahlström,2022-12-16

Hybrid Artificial Intelligent Systems Emilio Corchado,2011-05-16 The two LNAI volumes 6678 and 6679 constitute the proceedings of the 6th International Conference on Hybrid Artificial Intelligent Systems, HAIS 2011, held in Wroclaw, Poland, in May 2011. The 114 papers published in

these proceedings were carefully reviewed and selected from 241 submissions. They are organized in topical sessions on hybrid intelligence systems on logistics and intelligent optimization; metaheuristics for combinatorial optimization and modelling complex systems; hybrid systems for context-based information fusion; methods of classifier fusion; intelligent systems for data mining and applications; systems, man, and cybernetics; hybrid artificial intelligence systems in management of production systems; habrid artificial intelligent systems for medical applications; and hybrid intelligent approaches in cooperative multi-robot systems.

Electric and Hybrid Vehicles Gianfranco Pistoia,2010-07-27 Electric and Hybrid Vehicles: Power Sources, Models, Sustainability, Infrastructure and the Market reviews the performance, cost, safety, and sustainability of battery systems for hybrid electric vehicles (HEVs) and electric vehicles (EVs), including nickel-metal hydride batteries and Li-ion batteries. Throughout this book, especially in the first chapters, alternative vehicles with different power trains are compared in terms of lifetime cost, fuel consumption, and environmental impact. The emissions of greenhouse gases are particularly dealt with. The improvement of the battery, or fuel cell, performance and governmental incentives will play a fundamental role in determining how far and how substantial alternative vehicles will penetrate into the market. An adequate recharging infrastructure is of paramount importance for the diffusion of vehicles powered by batteries and fuel cells, as it may contribute to overcome the so-called range anxiety. Thus, proposed battery charging techniques are summarized and hydrogen refueling stations are described. The final chapter reviews the state of the art of the current models of

hybrid and electric vehicles along with the powertrain solutions adopted by the major automakers. Contributions from the worlds leading industry and research experts Executive summaries of specific case studies Information on basic research and application approaches

Hybrid Systems V Panos J. Antsaklis,Wolf Kohn,Michael Lemmon,Anil Nerode,Shankar Sastry,2003-07-31 This book constitutes the strictly refereed post-proceedings of the 5th International Hybrid Systems Workshop held in Notre Dame, Indiana, USA in September 1998. The 23 revised full papers presented in the book have gone through two rounds of thorough reviewing and revision. The volume presents state-of-the-art research results and particularly addresses such areas as program verification, concurrent and distributed processes, logic programming, logics of programs, discrete event simulation, calculus of variations, optimization, differential geometry, Lie algebras, automata theory, dynamical systems, etc.

Stochastic Hybrid Systems Henk A.P. Blom,John Lygeros,2009-09-02 This volume presents a number of fundamental theoretical advances in the area of stochastic hybrid systems, motivated primarily from applications to air traffic management. Air traffic is arguably the most challenging application area for stochastic hybrid systems, since it requires handling complex distributed systems, multiple human in the loop elements and hybrid dynamics. The editors have collected key contributions, which define the state-of-the-art, present novel directions, and highlight emerging application areas.

Stochastic Reachability Analysis of Hybrid Systems Luminita Manuela Bujorianu,2012-04-23 Stochastic reachability analysis (SRA) is a method of analyzing the behavior of control systems which mix discrete and continuous dynamics. For

probabilistic discrete systems it has been shown to be a practical verification method but for stochastic hybrid systems it can be rather more. As a verification technique SRA can assess the safety and performance of, for example, autonomous systems, robot and aircraft path planning and multi-agent coordination but it can also be used for the adaptive control of such systems. Stochastic Reachability Analysis of Hybrid Systems is a self-contained and accessible introduction to this novel topic in the analysis and development of stochastic hybrid systems. Beginning with the relevant aspects of Markov models and introducing stochastic hybrid systems, the book then moves on to coverage of reachability analysis for stochastic hybrid systems. Following this build up, the core of the text first formally defines the concept of reachability in the stochastic framework and then treats issues representing the different faces of SRA: • stochastic reachability based on Markov process theory; • martingale methods; • stochastic reachability as an optimal stopping problem; and • dynamic programming. The book is rounded off by an appendix providing mathematical underpinning on subjects such as ordinary differential equations, probabilistic measure theory and stochastic modeling, which will help the non-expert-mathematician to appreciate the text. Stochastic Reachability Analysis of Hybrid Systems characterizes a highly interdisciplinary area of research and is consequently of significant interest to academic researchers and graduate students from a variety of backgrounds in control engineering, applied mathematics and computer science. The Communications and Control Engineering series reports major technological advances which have potential for great impact in the fields of communication and control. It reflects research in industrial and academic institutions around the

world so that the readership can exploit new possibilities as they become available.

<u>Modelling, Analysis and Design of Hybrid Systems</u> S. Engell,G. Frehse,E. Schnieder,2003-07-01 In 1995, the Deutsche Forschungsgemeinschaft (DFG), the largest public research funding organization in Germany, decided to launch a priority program (Schw- punktprogramm in German) calledKondisk-Dynamics and Control of Systems with Mixed Continuous and Discrete Dynamics. Such a priority program is usually sponsored for six years and supports about twenty scientists at a time, in engineering andcomputersciencemostlyyoungresearchersworkingfor adoctoraldegree. There is a yearly competition across all disciplines of arts and sciences for the funding of such programs, and the group of proposers was the happy winner of a slot in that year. The program started in 1996 after an open call for proposals; the successful projects were presented and re-evaluated periodically, and new projects could be submitted simultaneously. During the course of the focused research program, 25 different projects were funded in 19 participating university institutes, some of the projects were collaborative efforts of two groups with different backgrounds, mostly one from engineering and one from computer science. There were two main motivations for establishingKondisk. The rst was the fact that technical systems nowadays are composed of physical components with (mostly) continuous dynamics and computerized control systems where the reaction to discrete events plays a major role, implemented in Programmable Logic Contr- lers (PLCs), Distributed Control Systems (DCSs) or real-time computer systems.

Road Traffic Modeling and Management Fouzi Harrou,Abdelhafid Zeroual,Mohamad Mazen Hittawe,Ying Sun,2021-10-05 Road Traffic Modeling and Management: Using Statistical Monitoring and

Deep Learning provides a framework for understanding and enhancing road traffic monitoring and management. The book examines commonly used traffic analysis methodologies as well the emerging methods that use deep learning methods. Other sections discuss how to understand statistical models and machine learning algorithms and how to apply them to traffic modeling, estimation, forecasting and traffic congestion monitoring. Providing both a theoretical framework along with practical technical solutions, this book is ideal for researchers and practitioners who want to improve the performance of intelligent transportation systems. Provides integrated, up-to-date and complete coverage of the key components for intelligent transportation systems: traffic modeling, forecasting, estimation and monitoring Uses methods based on video and time series data for traffic modeling and forecasting Includes case studies, key processes guidance and comparisons of different methodologies

Logical Analysis of Hybrid Systems André Platzer,2010-09-02 Hybrid systems are models for complex physical systems and have become a widely used concept for understanding their behavior. Many applications are safety-critical, including car, railway, and air traffic control, robotics, physical-chemical process control, and biomedical devices. Hybrid systems analysis studies how we can build computerized controllers for physical systems which are guaranteed to meet their design goals. The author gives a unique, logic-based perspective on hybrid systems analysis. It is the first book that leverages the power of logic for hybrid systems. The author develops a coherent logical approach for systematic hybrid systems analysis, covering its theory, practice, and applications. It is further shown how the developed verification techniques can be used to study air traffic and railway control systems.

This book is intended for researchers, postgraduates, and professionals who are interested in hybrid systems analysis, cyberphysical or embedded systems design, logic and theorem proving, or transportation and automation.

Intelligent Robotics and Applications Ming Xie,Youlun Xiong,Caihua Xiong,Zhencheng Hu,2009-12-16 The market demands for skills, knowledge and personalities have positioned robotics as an important field in both engineering and science. To meet these challenging – mands, robotics has already seen its success in automating many industrial tasks in factories. And, a new era will come for us to see a greater success of robotics in n– industrial environments. In anticipating a wider deployment of intelligent and auto– mous robots for tasks such as manufacturing, eldercare, homecare, edutainment, search and rescue, de-mining, surveillance, exploration, and security missions, it is necessary for us to push the frontier of robotics into a new dimension, in which motion and intelligence play equally important roles. After the success of the inaugural conference, the purpose of the Second Inter– tional Conference on Intelligent Robotics and Applications was to provide a venue where researchers, scientists, engineers and practitioners throughout the world could come together to present and discuss the latest achievement, future challenges and exciting applications of intelligent and autonomous robots. In particular, the emphasis of this year's conference was on "robot intelligence for achieving digital manufact– ing and intelligent automations. " This volume of Springer's Lecture Notes in Artificial Intelligence and Lecture Notes in Computer Science contains accepted papers presented at ICIRA 2009, held in Singapore, December 16-18, 2009. On the basis of the reviews

and recommendations by the international Program Committee members, we decided to accept 128 papers having technical novelty, out of 173 submissions received from different parts of the world.

Analysis and Design of Hybrid Systems 2003 (ADHS 03) Sebastian Engell,Herve Gueguen,Janan Zaytoon,J. Zaytoon,2003-12-19 Before the Riders came to their remote valley the Yendri led a tranquil pastoral life. When the Riders conquered and enslaved them, only a few escaped to the forests. Rebellion wasn't the Yendri way; they hid, or passively resisted, taking consolation in the prophecies of their spiritual leader. Only one possessed the necessary rage to fight back: Gard the foundling, half-demon, who began a one-man guerrilla war against the Riders. His struggle ended in the loss of the family he loved, and condemnation from his own people. Exiled, he was taken as a slave by powerful mages ruling an underground kingdom. Bitterer and wiser, he found more subtle ways to earn his freedom. This is the story of his rise to power, his vengeance, his unlikely redemption and his maturation into a loving father--as well as a lord and commander of demon armies. Kage Baker, author of the popular and witty fantasy, The Anvil of the World, returns to that magical world for another story of love, adventure, and a fair bit of ironic humor. At the publisher's request, this title is being sold without Digital Rights Management software (DRM) applied.

Stochastic Hybrid Systems Christos G. Cassandras,John Lygeros,2018-10-03 Because they incorporate both time- and event-driven dynamics, stochastic hybrid systems (SHS) have become ubiquitous in a variety of fields, from mathematical finance to biological processes to communication networks to engineering. Comprehensively integrating numerous cutting-edge studies, Stochastic Hybrid Systems presents a

captivating treatment of some of the most ambitious types of dynamic systems. Cohesively edited by leading experts in the field, the book introduces the theoretical basics, computational methods, and applications of SHS. It first discusses the underlying principles behind SHS and the main design limitations of SHS. Building on these fundamentals, the authoritative contributors present methods for computer calculations that apply SHS analysis and synthesis techniques in practice. The book concludes with examples of systems encountered in a wide range of application areas, including molecular biology, communication networks, and air traffic management. It also explains how to resolve practical problems associated with these systems. Stochastic Hybrid Systems achieves an ideal balance between a theoretical treatment of SHS and practical considerations. The book skillfully explores the interaction of physical processes with computerized equipment in an uncertain environment, enabling a better understanding of sophisticated as well as everyday devices and processes.

  A Self-Learning Short-Term Traffic Forecasting System Through Dynamic Hybrid Approach Jiasong Zhu,朱嘉松,2017-01-27 This dissertation, A Self-learning Short-term Traffic Forecasting System Through Dynamic Hybrid Approach by Jiasong, Zhu, 朱嘉松, was obtained from The University of Hong Kong (Pokfulam, Hong Kong) and is being sold pursuant to Creative Commons: Attribution 3.0 Hong Kong License. The content of this dissertation has not been altered in any way. We have altered the formatting in order to facilitate the ease of printing and reading of the dissertation. All rights not granted by the above license are retained by the author. Abstract: Abstract of thesis entitled A Self-learning Short-term Traffic Forecasting System through Dynamic Hybrid Approach

Submitted by Zhu, Jiasong for the degree of Doctor
of Philosophy at The University of Hong Kong in
October 2007 A reliable and accurate short-term
traffic forecasting system is crucial for the
successful deployment of any Intelligent
Transportation System in that most of its
important functions are based on the traffic
conditions in the near future. A lot of
forecasting models have been developed during
recent years but none of them could consistently
outperform the others. Some models are applicable
only for specific traffic conditions or network
topologies. However, traffic forecasting
conditions in real-world applications are very
complicated which can be affected by a lot of
factors. Some of these factors can lead to long-
term traffic pattern changes. The impacts of such
changes to short-term traffic forecasting are
profound and can easily make existingly used
forecasting system outdated. Therefore, it is
desirable for forecasting systems to have self-
learning ability to detect long-term traffic
pattern changes and update it automatically
accordingly. This study aims at enhancing the
self-learning ability of short-term traffic
forecasting systems. There is a general lack of
self-learning ability of short-term traffic
forecasting systems. To design an effective
forecasting system for real-world applications,
this study analyzes the forecasting problem from
two sides: one is from the viewpoint of traffic
systems and the other is from forecasting models.
The main factors that cause itraffic pattern
changes and their impacts to practical performance
of forecasting models are analyzed. A dynamic
hybrid approach and a new self-learning mechanism
are developed. A layered strategy is taken to
break complicated traffic conditions into simpler
traffic modes. Kohonen Self-Organizing Map (KSOM)
is used as the clustering tool to implement the

layered strategy. A competitive mechanism is incorporated in the proposed forecasting system to dynamically find the optimal hybrid scheme among candidate forecasting models for different traffic modes. Although the system structure becomes more complicated, it is more flexible and operationally more efficient than conventional models. In addition, the methodology it takes is an open-ending one, which means any new promising model can be easily incorporated. A detailed system design framework is then presented to illustrate how the proposed approach can be implemented. Case studies are carried out using real-time traffic data from two test sites in the traffic network of Twin Cities Metro area, Minneapolis. Based on the presented system design framework, two prototype systems are implemented. Details of how the prototype systems make real-time forecasting, detect and handle long-term traffic pattern changes took place at these two test sites are introduced. To further test the performance of prototype systems against other mainstream models, comparative studies are carried out. The obtained results demonstrated the superiorities of the prototype systems to other forecasting methods and showed that the proposed approach can effectively improve the self-learning ability of short-term traffic forecasting systems. ii DOI: 10.5353/th_b3963451 Subjects: Traffic estima

  Hybrid Systems III Rajeev Alur,Thomas A. Henzinger,Eduardo D. Sontag,1996-04-24 This reference book documents the scientific outcome of the DIMACS/SYCON Workshop on Verification and Control of Hybrid Systems, held at Rutgers University in New Brunswick, NJ, in October 1995. A hybrid system consists of digital devices that interact with analog environments. Computer science contributes expertise on the analog aspects of this emerging field of interdisciplinary research and design. The 48

revised full papers included were strictly refereed; they present the state of the art in this dynamic field with contributions by leading experts. Also available are the predecessor volumes published in the same series as LNCS 999 and LNCS 736.

  Algebraic Calculi for Hybrid Systems Peter Höfner,2009

  Developing Future Traffic Management Systems Using Hybrid Twins ,2022

  Advances in Future Computer and Control Systems David Jin,Sally Lin,2012-04-13 FCCS2012 is an integrated conference concentrating its focus on Future Computer and Control Systems. "Advances in Future Computer and Control Systems" presents the proceedings of the 2012 International Conference on Future Computer and Control Systems(FCCS2012) held April 21-22,2012, in Changsha, China including recent research results on Future Computer and Control Systems of researchers from all around the world.

  Hybrid Systems: Computation and Control Rajeev Alur,2004-03-12 This book constitutes the refereed proceedings of the 7th International Workshop on Hybrid Systems: Computation and Control, HSCC 2004, held in Philadelphia, PA, USA, in March 2004. The 43 revised full papers presented together with an invited article were carefully reviewed and selected from 117 submissions. The papers address all current issues in hybrid systems such as tools for analysis and verification, control and optimization, modeling and engineering applications, and emerging topics in programming language support and implementation; a special focus is on the interplay between biomolecular networks, systems biology, formal methods, and control of hybrid systems.

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