

Orb Controller

Alexander Nebylov

Protocols for High-Speed Networks VI Joseph D. Touch, James P.G. Sterbenz, 2013-03-14 1 This year marks the 10th anniversary of the IFIP International Workshop on Protocols for High-Speed Networks (PfhSN). It began in May 1989, on a hillside overlooking Lake Zurich in Switzerland, and arrives now in Salem Massachusetts 6,000 kilometers away and 10 years later, in its sixth incarnation, but still with a waterfront view (the Atlantic Ocean). In between, it has visited some picturesque views of other lakes and bays of the world: Palo Alto (1990 - San Francisco Bay), Stockholm (1993 - Baltic Sea), Vancouver (1994- the Strait of Georgia and the Pacific Ocean), and Sophia Antipolis I Nice (1996- the Mediterranean Sea). PfhSN is a workshop providing an international forum for the exchange of information on high-speed networks. It is a relatively small workshop, limited to 80 participants or less, to encourage lively discussion and the active participation of all attendees. A significant component of the workshop is interactive in nature, with a long history of significant time reserved for discussions. This was enhanced in 1996 by Christophe Diot and Walid Dabbous with the institution of Working Sessions chaired by an animator, who is a distinguished researcher focusing on topical issues of the day. These sessions are an audience participation event, and are one of the things that makes PfhSN a true working conference.

Control and Measurement Applications for Smart Grid Sathans Suhag, Chitralekha Mahanta, Sukumar Mishra, 2022-02-01 The book contains select proceedings of the International Conference on Smart Grid Energy Systems and Control (SGESC 2021). The proceedings is divided into 03 volumes, and this volume focuses on adaptive control and intelligent sensors, wide-area measurements, and applications in the smart grid. This book includes papers on topics such as SMART sensors, vision sensors, sensor fusion, wireless sensors, and the internet of things, MEMS, Mechatronics, Remote sensing, telemetry, and its applications in automated vehicle control. This book is a unique collection of chapters from different areas with a common theme and will be immensely useful to academic researchers and practitioners in the industry.

Distributed Information Resources, 1999-07-26 Since its first volume in 1960, *Advances in Computers* has presented detailed coverage of innovations in hardware and software and in computer theory, design, and applications. It has also provided contributors with a medium in which they can examine their subjects in greater depth and breadth than that allowed by standard journal articles. As a result, many articles have become standard references that continue to be of significant, lasting value despite the rapid growth taking place in the field.

Advances in Computational Intelligence Ildar Batyrshin, María de Lourdes Martínez-Villaseñor, Hiram Eredín Ponce Espinosa, 2019-01-02 The two-volume set LNAI 11288 and 11289 constitutes the proceedings of the 17th Mexican International Conference on Artificial Intelligence, MICAI 2018, held in Guadalajara, Mexico, in October 2018. The total of 62 papers presented in these two volumes was carefully reviewed and selected from 149 submissions. The contributions are organized in topical as follows: Part I: evolutionary and nature-inspired intelligence; machine learning; fuzzy logic and uncertainty management. Part II: knowledge representation, reasoning, and optimization; natural language processing; and robotics and computer vision.

Robotics Research Raymond Austin Jarvis, Alex Zelinsky, 2003-03-12 At the dawn of the new millennium, robotics is undergoing a major transformation in scope and dimension. From a largely dominant industrial focus, robotics is rapidly expanding into the challenges of unstructured environments. Interacting with, assisting, serving, and exploring with humans, the emerging robots will increasingly touch people and their lives. The goal of this new series of Springer Tracts in Advanced Robotics is to bring, in a timely fashion, the latest advances and developments in robotics on the basis of their significance and quality. It is our hope that the greater dissemination of research developments will stimulate more exchanges and collaborations among the research community and contribute to further advancement of this rapidly growing field. As one of robotics pioneering symposia, ISRR, the International Symposium on Robotics Research, has established over the past two decades some of the field's most fundamental and lasting contributions. With the launching of STAR, this and other thematic symposia devoted to excellence in robotics and an important platform for closer links and

extended reach within the research community. The Tenth edition of Robotics Research edited by Raymond Jarvis and Alex Zelinsky offers a 11-part volume a collection of a broad range of topics in robotics. The content of these contributions provides a wide coverage of the current state of robotics research: the advances and challenges in its theoretical foundation and technology basis, and the developments in its traditional and new areas of applications.

Middleware 2000 Joseph Sventek, Geoffrey Coulson, 2003-06-29 Middleware is everywhere. Ever since the advent of sockets and other virtual circuit abstractions, researchers have been looking for ways to incorporate high-value concepts into distributed systems platforms. Most distributed applications, especially Internet applications, are now programmed using such middleware platforms. Prior to 1998, there were several major conferences and workshops at which research into middleware was reported, including ICODP (International Conference on Open Distributed Processing), ICDP (International Conference on Distributed Platforms) and SDNE (Services in Distributed and Networked Environments). Middleware'98 was a synthesis of these three conferences. Middleware 2000 continued the excellent tradition of Middleware'98. It provided a single venue for reporting state-of-the-art results in the provision of distributed systems platforms. The focus of Middleware 2000 was the design, implementation, deployment, and evaluation of distributed systems platforms and architectures for future networked environments. Among the 70 initial submissions to Middleware 2000, 21 papers were selected for inclusion in the technical program of the conference. Every paper was reviewed by four members of the program committee. The papers were judged according to their originality, presentation quality, and relevance to the conference topics. The accepted papers cover various subjects such as caching, reflection, quality of service, and transactions.

Distributed Embedded Smart Cameras Christophe Bobda, Senem Velipasalar, 2014-06-04 This publication addresses distributed embedded smart cameras – cameras that perform on-board analysis and collaborate with other cameras. This book provides the material required to better understand the architectural design challenges of embedded smart camera systems, the hardware/software ecosystem, the design approach for and applications of distributed smart cameras together with the state-of-the-art algorithms. The authors concentrate on the architecture, hardware/software design, realization of smart camera networks from applications to architectures, in particular in the embedded and mobile domains.

Programming with VisiBroker Vijaykumar Natarajan, Stefan Reich, Bhaskar Vasudevan, 2001-05-29 The only book you need for programming VisiBroker using Java The most widely used commercial implementation of the CORBA standard, Inprise's VisiBroker, is used by hundreds of thousands of developers worldwide. Written by a team of Inprise insiders, this updated and expanded Second Edition of the #1 guide to programming VisiBroker helps Java developers quickly master the skills they need to develop more powerful and sophisticated distributed, object-oriented, client/server systems, from scratch or with existing components using VisiBroker 4. New topics covered in this edition include migrating VisiBroker 3 to version 4; the Portable Object Adaptor; implementing the Objects by Value feature; the VisiBroker Interface Repository; Dynamic Programming APIs for use with scripting; and more. CD-ROM contains VisiBroker for Java 4, VisiBroker Naming and Event Services, and complete code for all examples in the book.

Early Winter's Orb David Anthony, Charles David, 2005-04 When unnatural snow covers the land, Emily must find a way to save her people from endless winter.

Fundamental Approaches to Software Engineering Mauro Pezzè, 2003-07-01 This book constitutes the refereed proceedings of the 6th International Conference on Fundamental Approaches to Software Engineering, FASE 2003, held in Warsaw, Poland, in April 2003. The 20 revised full papers presented together with a keynote paper were carefully reviewed and selected from 89 submissions. The papers are organized in topical sections on software components, mobile computing, aspects and web applications, software measurements, formal verification, analysis and testing, and model integration and extension.

Technological Advancements in Aging and Neurological Conditions to Improve Physical Activity.

Cognitive Functions, and Postural Control Gill Barry,Eling D. de Bruin,Nina Skjæret-Maroni,Emma Stanmore,2022-06-29

Make: Volume 84 Dale Dougherty,2023-02-07 What's new in digital fabrication? So much! In *Make: Vol. 84* we show you how adding dedicated SBCs, like a Raspberry Pi, make 3D printers vastly smarter and up to five times faster. New laser engravers can cut metal for under \$2,000, and cheap workhorse diode lasers are everywhere. Pro-level 3D scanning is on your phone, and 3D design software has a flavor for every style of maker. Now's the time to level up! Plus, we dive into how makers can (ethically) use generative A.I. to create audio, images, text, code, and 3D models for your next project! Plus, 23 Projects & Skills, including: Build a \$30 Vertical Wind Turbine Create Wearable Soft Speakers Wow your friends with a DIY Ambient TV Backlight Sew decorative Light-Up Zodiac Embroidery Get involved with Amateur Radio and Software Defined Radio (SDR) And much more!

Guide to Cloud Computing for Business and Technology Managers Vivek Kale,2014-12-17 *Guide to Cloud Computing for Business and Technology Managers: From Distributed Computing to Cloudware Applications* unravels the mystery of cloud computing and explains how it can transform the operating contexts of business enterprises. It provides a clear understanding of what cloud computing really means, what it can do, and when it is practical to use. Addressing the primary management and operation concerns of cloudware, including performance, measurement, monitoring, and security, this pragmatic book: Introduces the enterprise applications integration (EAI) solutions that were a first step toward enabling an integrated enterprise Details service-oriented architecture (SOA) and related technologies that paved the road for cloudware applications Covers delivery models like IaaS, PaaS, and SaaS, and deployment models like public, private, and hybrid clouds Describes Amazon, Google, and Microsoft cloudware solutions and services, as well as those of several other players Demonstrates how cloud computing can reduce costs, achieve business flexibility, and sharpen strategic focus Unlike customary discussions of cloud computing, *Guide to Cloud Computing for Business and Technology Managers: From Distributed Computing to Cloudware Applications* emphasizes the key differentiator—that cloud computing is able to treat enterprise-level services not merely as discrete stand-alone services, but as Internet-locatable, composable, and repackagable building blocks for generating dynamic real-world enterprise business processes.

Proceedings ,1995

Time-Triggered Communication Roman Obermaisser,2011-10-19 *Time-Triggered Communication* helps readers build an understanding of the conceptual foundation, operation, and application of time-triggered communication, which is widely used for embedded systems in a diverse range of industries. This book assembles contributions from experts that examine the differences and commonalities of the most significant protocols including: TTP, FlexRay, TTEthernet, SAFEBus, TTCAN, and LIN. Covering the spectrum, from low-cost time-triggered fieldbus networks to ultra-reliable time-triggered networks used for safety-critical applications, the authors illustrate the inherent benefits of time-triggered communication in terms of predictability, complexity management, fault-tolerance, and analytical dependability modeling, which are key aspects of safety-critical systems. Examples covered include FlexRay in cars, TTP in railway and avionic systems, and TTEthernet in aerospace applications. Illustrating key concepts based on real-world industrial applications, this book: Details the underlying concepts and principles of time-triggered communication Explores the properties of a time-triggered communication system, contrasting its strengths and weaknesses Focuses on the core algorithms applied in many systems, including those used for clock synchronization, startup, membership, and fault isolation Describes the protocols that incorporate presented algorithms Covers tooling requirements and solutions for system integration, including scheduling The information in this book is extremely useful to industry leaders who design and manufacture products with distributed embedded systems based on time-triggered communication. It also benefits suppliers of embedded components or development tools used in this area. As an educational tool, this material can be used to teach students and working professionals

in areas including embedded systems, computer networks, system architectures, dependability, real-time systems, and automotive, avionics, and industrial control systems.

Business Process Management Systems James F. Chang, 2016-04-19 With a focus on strategy and implementation, James Chang discusses business management practices and the technology that enables them. He analyzes the history of process management practices and demonstrates that BPM practices are a synthesis of radical change and continuous change practices. The book is relevant to both business and IT professionals who are presented with an integrated view on how various management practices merge into BPM. This volume describes the many technologies that converge to form a Business Process Management System (BPMS), illustrating its standards and service-oriented architecture. About the Author James Chang is the founder and president of Ivy Consultants, Inc. He has extensive experience implementing Enterprise Resource Planning (ERP)-enabled business solutions and process-centric integration solutions for Fortune 500 companies. Mr. Chang has written several articles on BPM and EAI. He graduated cum laude with a Bachelor of Science degree in operations research and industrial engineering from Cornell University.

Business Process Management Naresh Verma, 2009-12 This book explores at the various component-based integration technologies that are relevant for Business Process management Systems (BPMS). It discusses object-based technologies and discusses the work flow. Management System (WFMS) in detail. Further it elaborates various types of process integration systems, discusses the ideal BPMS, and attempts to elucidate the various standards, competitors to the standards described here, to support BPMS. It also discusses various integration technologies and look into the Business Process Management System (PMS) components and tools based on the previous integration technologies.

Evaluation and Comparison of CORBA (Object Request Broker) Implementations Roland Gelbmann, 2002-07-11 Inhaltsangabe: Abstract: Common Object Request Broker Architecture (CORBA), a standard from the Object Management Group (OMG), defines a vendor-independent architecture and infrastructure for distributed systems. Further CORBA species a client-server platform as well as an object-oriented programming model for distributed computing. The Object Request Broker (ORB) implements the part of CORBA which manages communication and data exchange between objects. CORBA-based applications often have to communicate with ORBs from different vendors. Therefore testing the interoperability is one important point in this work. Six actually available ORB implementations are shown and compared at given features. If a problem has to be solved with CORBA, it is necessary to choose the best ORB implementation for that purpose, because they differ often at significant points. Important details for decision are Standard Conformity, Robustness, Functionality as well as Functional Range or Interoperability. Exactly these properties are to be examined in this work. The investigation is performed on six, at the web available ORBs indeed Jacorb 1.4 beta 2, Orbacus 4.1.0, Orbix E2A 2.0, OpenORB 1.2.0, J2SE ORB 1.4.0 as well as TAO 1.2.1 all in their most actual released version. Additionally to these properties the correct implementation of the most important CORBA Services is checked. They are Event Service, Notification Service, Name Service and Transaction Service. The ORBs are compared at this given properties. It shows that the ORBs differ very much from each other and that the CORBA Services are often implemented incorrectly. Further a high costly implementation is no guarantee for best quality at all points. The evaluation shows that a freely available ORB can be as good as or better than a commercial one. Inhaltsverzeichnis: Table of Contents: 1. Introduction 1.1 Motivation 1.2 Project Objectives 1.3 Related Work 1.4 Content of the following Sections 2. CORBA Basics 2.1 Overview 2.2 Major Parts of an ORB 2.2.1 Core Components 2.2.2 Object Adaptors 2.3 CORBA Services 2.4 OMG Interface Definition Language 2.5 BOA to POA Migration 3. ORB Evaluation and Comparison 3.1 Chosen ORBs 3.1.1 Jacorb 1.4 beta 2 3.1.2 Orbacus 4.1.0 3.1.3 Orbix E2A 2.0 3.1.4 OpenORB 1.2.0 3.1.5 J2SE ORB 1.4.0 3.1.6 TAO The Ace ORB 1.2.1 3.2 Evaluation-Environment 3.3 Installation 3.4 Standard Conformity 3.4.1 Interface Definition Language 3.4.2 Basic Remote [...]

Automatic Control in Space 1985 J. P. Chretien,2014-06-28 Presents an authoritative overview of the recent developments and technical advances in the applications of automated control to space technology. Topics covered include: geostationary satellites, scientific satellites, flexible systems, low earth orbit satellites, orbit and trajectory control, component technology, platforms, rendez-vous and docking (RVD) and manipulators. Contains 39 research and review papers.

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