Bluetooth Agent

Gunasekaran Manogaran,Nour Eldeen Mahmoud Khalifa,Mohamed Loey,Mohamed Hamed N. Taha

Semantic Agent Systems Atilla Elci, Mamadou Tadiou Koné, Mehmet A. Orgun, 2011-03-16 Semantic agent systems are about the integration of the semantic Web, software agents, and multi-agent systems technologies. Like in the past (e.g. biology and informatics yielding bioinformatics) a whole new perspective is emerging with semantic agent systems. In this context, the semantic Web is a Web of semantically linked data which aims to enable man and machine to execute tasks in tandem. Here, software agents in a multiagent system as delegates of humans are endowed with power to use semantically linked data. This edited book "Semantic Agent Systems: Foundations and Applications" proposes contributions on a wide range of topics on foundations and applications written by a selection of international experts. It first introduces in an accessible style the nature of semantic agent systems. Then it explores with numerous illustrations new frontiers in software agent technology. "Semantic Agent Systems: Foundations and Applications" is recommended for scientists, experts, researchers, and learners in the field of artificial intelligence, the semantic Web, software agents, and multi-agent systems technologies.

Intelligent Human Computer Interaction Hakimjon Zaynidinov, Madhusudan Singh, Uma Shanker Tiwary, Dhananjay Singh, 2023-04-10 This book constitutes the refereed proceedings of the 14th International Conference on Intelligent Human Computer Interaction, IHCI 2022, held in Tashkent, Uzbekistan, during October 20–22, 2022. The 47 full papers and 13 short papers included in this book were carefully reviewed and selected from 148 submissions. They were organized in topical sections as follows: Bio-inspired Computing; Cognitive computing; Human Centered AI; Intelligent Technology for Post-Covid and Web Frameworks.

Agents and Peer-to-Peer Computing Gianluca Moro, Sonia Bergamaschi, 2005-11-04 Peer-to-peer (P2P) computing is attracting enormous media attention, spurred by the popularity of file sharing systems such as Napster, Gnutella, and Morpheus. The peers are autonomous, or as some call them, first-class citizens. P2P networks are emerging as a new distributed computing paradigm for their potential to harness the computing power of the hosts composing the network and make their under-utilized resources available to others. Although researchers working on distributed computing, multiagent systems, databases and networks have been using similar concepts for a long time, it is only recently that papers motivated by the current P2P paradigm have started appearing in high-quality conferences and workshops. Research in agent systems in particular appears to be most relevant because, since their inception, multiagent systems have always been thought of as networks of peers. The multiagent paradigm can thus be superimposed on the P2P architecture, where agents embody the description of the task environments, the decision-support capabilities, the collective behavior, and the interaction protocols of each peer. The emphasis in this context on decentralization, user autonomy, ease and speed of growth that gives P2P its advantages also leads to significant potential problems. Most prominent among these problems are coordination, the ability of an agent to make decisions on its own actions in the context of activities of other agents, and scalability, the value of the P2P systems lies in how well they scale along several dimensions, including complexity, heterogeneity of peers, robustness, traffic redistribution, and so on. This volume presents the fully revised

papers presented at the Third International Workshop on Agents and Peer-to-Peer Computing, AP2PC 2004, held in New York City on July 19, 2004 in the context of the Third International Joint Conference on Autonomous Agents and Multi-Agent Systems (AAMAS 2004). The volume is organized in topical sections on P2P networks and search performance, emergent communities and social behaviours, semantic integration, mobile P2P systems, adaptive systems, agent-based resource discovery, as well as trust and reputation.

Flexible Query Answering Systems Henning Christiansen, Mohand-Said Hacid, Troels Andreasen, Henrik Legind Larsen, 2004-06-17 ThisvolumeconstitutestheproceedingsoftheSixthInternationalConferenceon Flexible Query Answering Systems, FQAS 2004, held in Lyon, France, on June 24–26, 2004. FQAS is the premier conference for researchers and practitioners concerned with the vital task of providing easy, ?exible, and intuitive access to information for every type of need. This multidisciplinary conference draws on several research areas, including databases, information retrieval, knowledge representation, soft computing, multimedia, and humancomputer interaction. With FQAS 2004, the FQAS conference series celebrated its tenth anniversary as it has been held every two years since 1994. The overall theme of the FQAS conferences is innovative query systems aimed at providing easy, ?exible, and intuitive access to information. Such systems are intended to facilitate retrieval from information repositories such as databases, libraries, and the Web. These repositories are typically equipped with standard query systems that are often inadequate for users. The focus of FQAS is the development of query systems that are more expressive, informative, cooperative, productive, and intuitive to use.

Raspberry Pi for Secret Agents Matthew Poole, 2016-07-27 Turn your Raspberry Pi into a secret agent toolbox with this set of exciting projects About This Book Turn your Raspberry Pi into a multi-purpose secret agent gadget for audio and video surveillance, Wi-Fi exploration, or playing pranks on your friends Detect an intruder on camera or with sensors and set off an alarm or receive messages to your phone Find out what the other computers on your network are up to and make yourself anonymous on the Internet This book has been updated for new additions to your toolkit featuring the tiny, recently released Raspberry Pi Zero board Who This Book Is For This book is for those who are new to the Raspberry Pi Zero , Raspberry Pi 2 or Raspberry Pi 3 and have some experience with the original Raspberry Pi models, and even for those budding secret agents who would like to use Pi Zero as a secret agent toolbox. No programming experience is assumed. Suitable for the novice and expert alike, each topic provides a fast and easy way to get started with exciting applications, with practical examples in every chapter. What You Will Learn Install and configure the Raspbian Jessie operating system for maximum mischief Detect an intruder with motion detection or a laser trip wire and set off an alarm Listen in to conversations from a distance over Bluetooth Distort your voice in weird and wonderful ways Track the Pi's whereabouts using GPS Connect your Pi to the mobile Internet using a 3G dongle and make yourself anonymous on the net Display secret messages and codes to fellow agents on a LED display In Detail This book is for all mischievous Raspberry Pi owners who'd like to see their computer transform into a neat spy gadget to be used in a series of practical pranks and projects. No previous skills are required to follow along, and if you're completely new to Linux, you'll pick up much of the basics for free. We'll

help you set up your Raspberry Pi Zero , Raspberry Pi 2 and Raspberry Pi 3 and guide you through a number of pranks and secret agent techniques that are so inconspicuous yet high on mischief. You'll learn how to configure your operating system for maximum mischief and start exploring audio, video, or Wi-Fi techniques. We'll show you how to record, listen, or talk to people from a distance and how to set up your own phone network. Then, you'll plug in your webcam and set up a motion detector with an alarm and find out what the other computers on your Wi-Fi network are up to. Once you've mastered the techniques, we'll combine them with a battery pack and GPS for the ultimate off-road spy kit. Style and Approach This easy-to-follow guide is for budding secret agents who want to create tools for mischief, stealth, and reconnaissance. It's full of fun, practical examples and easy-to-follow recipes, guaranteeing maximum mischief for all skill levels.

Getting Started with Python for the Internet of Things Tim Cox, Dr. Steven Lawrence Fernandes, Sai Yamanoor, Srihari Yamanoor, Prof. Diwakar Vaish, 2019-02-26 Build clever, collaborative, and powerful automation systems with the Raspberry Pi and Python. Key FeaturesCreate your own Pi-Rover or Pi-Hexipod robotsDevelop practical applications in Python using Raspberry PiBuild your own Jarvis, a highly advanced computerized AIBook Description This Learning Path takes you on a journey in the world of robotics and teaches you all that you can achieve with Raspberry Pi and Python. It teaches you to harness the power of Python with the Raspberry Pi 3 and the Raspberry Pi zero to build superlative automation systems that can transform your business. You will learn to create text classifiers, predict sentiment in words, and develop applications with the Tkinter library. Things will get more interesting when you build a human face detection and recognition system and a home automation system in Python, where different appliances are controlled using the Raspberry Pi. With such diverse robotics projects, you'll grasp the basics of robotics and its functions, and understand the integration of robotics with the IoT environment. By the end of this Learning Path, you will have covered everything from configuring a robotic controller, to creating a self-driven robotic vehicle using Python. Raspberry Pi 3 Cookbook for Python Programmers - Third Edition by Tim Cox, Dr. Steven Lawrence FernandesPython Programming with Raspberry Pi by Sai Yamanoor, Srihari YamanoorPython Robotics Projects by Prof. Diwakar VaishWhat you will learnBuild text classifiers and predict sentiment in words with the Tkinter libraryDevelop human face detection and recognition systemsCreate a neural network module for optical character recognitionBuild a mobile robot using the Raspberry Pi as a controllerUnderstand how to interface sensors, actuators, and LED displays workApply machine learning techniques to your modelsInterface your robots with BluetoothWho this book is for This Learning Path is specially designed for Python developers who want to take their skills to the next level by creating robots that can enhance people's lives. Familiarity with Python and electronics will aid understanding the concepts in this Learning Path.

Python Robotics Projects Prof. Diwakar Vaish,2018-05-30 Leverage the power of Python to build DIY robotic projects Key Features Design, build, and stimulate collaborative robots Build high-end robotics projects such as a customized personal Jarvis Leverage the power of Python and ROS for DIY robotic projects Book Description Robotics is a fast-growing industry. Multiple surveys state that investment in the field has increased tenfold in the last 6 years, and is set to become a \$100-billion sector by 2020. Robots are prevalent throughout all industries, and they are all set to be a part of our domestic lives. This book starts with the installation and basic steps in configuring a robotic controller. You'll then move on to setting up your environment to use Python with the robotic controller. You'll dive deep into building simple robotic projects, such as a pet-feeding robot, and more complicated projects, such as machine learning enabled home automation system (Jarvis), vision processing based robots and a self-driven robotic vehicle using Python. By the end of this book, you'll know how to build smart robots using Python. What you will learn Get to know the basics of robotics and its functions Walk through interface components with microcontrollers Integrate robotics with the IoT environment Build projects using machine learning Implement path planning and vision processing Interface your robots with Bluetooth Who this book is for If building robots is your dream, then this book is made for you. Prior knowledge of Python would be an added advantage.

Mobile Agents for Telecommunication Applications Eric Horlait, Thomas Magedanz, 2003-09-29 The aim of the MATA workshops series is to provide a unique opportunity for researchers from the IT, Internet, and telecommunications domain, as well as related software and application developers and service providers to discuss the advances in agent technologies and their applications in next generation mobile Internet and telecommunications. Since 1999 in Canada, MATA workshops have contributed to the creation of a research community around mobile agents and their use in telecommunication applications. The 2003 workshop focused on recent developments in agent technologies and particularly the use of agent technologies within the ?elds of network - nagement, dynamic service provisioning and management, nomadic and mobile computing, context aware services and environments, active and programmable networks, policybasedservicesandmanagement, adhocnetworking, peer-to-peer computing, ambient intelligence, Wireless Java, software de?ned radio, adaptive mobile end systems, virtual home environments, smart home, smart cars and navigation, e-learning, m-commerce, and other related 3Gb areas. October 2003 Eric HORLAIT VI Preface Scienti?c Program Committee T. Araragi, NTT, Japan P. Bellavista, Bologna, Italy F. Bellifemine, TILab, Italy R. Boutaba, Univ. of Waterloo, Canada P. Brezillon, LIP6, France B. Burg, HP Labs, USA J. Celestino Junior, 'FUC, Brazil J. Delgado, UPF Barcelona, Spain B. Dillenseger, France Teleco, France W. Enkelmann, Chrysler AG, Germany B. Falchuk, Telecordia, USA R. Glitho, Ericsson, Canada Y. Gourhant, FT R&D,

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Agent-Oriented Information Systems IV Manuel Kolp,2008-02-12 This book constitutes the thoroughly refereed post-proceedings of the 8th International Bi-Conference Workshop on Agent-Oriented Information Systems, AOIS 2005, held in Hakodate, Japan, May9, 2006 and Luxembourg, Luxembourg, June 6, 2006. The 13 revised full papers presented have gone through two rounds of reviewing and improvement and were carefully selected for inclusion in the book. The papers are organized in topical sections on Modelling, Methodologies, Agentoriented Software Engineering, and Applications.

Agent and Multi-Agent Systems: Technologies and Applications Geun Sik Jo,Lakhmi Jain,2008-03-14 Following from the very successful First KES

Symposium on Agent and Multi-Agent Systems - Technologies and Applications (KES-AMSTA 2007), held in Wroclaw, Poland, 31 May-1 June 2007, the second event in the KES-AMSTA symposium series (KES-AMSTA 2008) was held in Incheon, Korea, March 26-28, 2008. The symposium was organized by the School of Computer and Information Engineering, Inha University, KES International and the KES Focus Group on Agent and Mul- agent Systems. The KES-AMSTA Symposium Series is a sub-series of the KES Conference Series. The aim of the symposium was to provide an international forum for scientific research into the technologies and applications of agent and multi-agent systems. Agent and multi-agent systems are related to the modern software which has long been recognized as a promising technology for constructing autonomous, complex and intelligent systems. A key development in the field of agent and multi-agent systems has been the specification of agent communication languages and formalization of ontologies. Agent communication languages are intended to provide standard declarative mechanisms for agents to communicate knowledge and make requests of each other, whereas ontologies are intended for conceptualization of the knowledge domain. The symposium attracted a very large number of scientists and practitioners who submitted their papers for nine main tracks concerning the methodology and applications of agent and multi-agent systems, a doctoral track and two special sessions.

Agent and Multi-Agent Systems: Technologies and Applications Adam Grzech,2007-07-07 This book constitutes the refereed proceedings of the First International Symposium on Agent and Multi-Agent Systems: Technologies and Applications, KES-AMSTA 2007, held in Wroclaw, Poland in May/June 2007. Coverage includes agent-oriented Web applications, mobility aspects of agent systems, agents for network management, agent approaches to robotic systems, as well as intelligent and secure agents for digital content management.

On The Move to Meaningful Internet Systems 2003: CoopIS, DOA, and ODBASE Zahir Tari, Douglas C. Schmidt, 2003-10-25 missions in fact also treat an envisaged mutual impact among them. As for the 2002 edition in Irvine, the organizers wanted to stimulate this cross-pollination with a program of shared famous keynote speakers (this year we got Sycara, - ble, Soley and Mylopoulos!), and encouraged multiple attendance by providing authors with free access to another conference or workshop of their choice. We received an even larger number of submissions than last year for the three conferences (360 in total) and the workshops (170 in total). Not only can we therefore again claim a measurable success in attracting a representative volume of scienti?c papers, but such a harvest allowed the program committees of course to compose a high-guality cross-section of worldwide research in the areas covered. In spite of the increased number of submissions, the Program Chairs of the three main conferences decided to accept only approximately the same number of papers for presentation and publication as in 2002 (i. e. , around 1 paper out of every 4-5 submitted). For the workshops, the acceptance rate was about 1 in 2. Also for this reason, we decided to separate the proceedings into two volumes with their own titles, and we are grateful to Springer-Verlag for their collaboration in producing these two books. The reviewing process by the respective program committees was very professional and each paper in the main conferences was reviewed by at least three referees.

Cyber-Physical Systems for Industrial Transformation Gunasekaran Manogaran,Nour Eldeen Mahmoud Khalifa,Mohamed Loey,Mohamed Hamed N. Taha,2023-04-05 This book investigates the fundaments, standards, and protocols of Cyber-Physical Systems (CPS) in the industrial transformation environment. It facilitates a fusion of both technologies in the creation of reliable and robust applications. Cyber-Physical Systems for Industrial Transformation: Fundamentals, Standards, and Protocols explores emerging technologies such as artificial intelligence, data science, blockchain, robotic process automation, virtual reality, edge computing, and 5G technology to highlight current and future opportunities to transition CPS to become more robust and reliable. The book showcases the real-time sensing, processing, and actuation software and discusses fault-tolerant and cybersecurity as well. This book brings together undergraduates, postgraduates, academics, researchers, and industry individuals that are interested in exploring new ideas, techniques, and tools related to CPS and Industry 4.0.

Beginning Samsung ARTIK Cliff Wootton, 2016-05-18 Discover which ARTIK modules to use for various applications, and how to produce code for them. This book goes beyond the information previously available online, efficiently guiding developers from initial setup of their development environment to product development and prototyping in no time. Beginners will find helpful background insights into foundation technology and useful reference information is included for more advanced developers. Samsung's announcement of the new ARTIK modules for IoT has generated tremendous interest in the developer market for wearable and other consumer or industrial devices. This book provides the perfect tutorial-based introduction to the ARTIK family of "Systems on Modules," which integrate powerful microprocessors, memory, wireless connectivity, and enhanced security on to very small form factor boards. With Beginning Samsung ARTIK as your guide, take the next steps to creating great solutions with an ARTIK. What You'll Learn Use terminal emulators to access the command line and talk to the device Establish Wi-Fi connectivity with a wireless network Upgrade the operating system and install additional software Bring up Eclipse IDE and create a cross-compiler toolchain on Mac OS X Cross-compile for the ARM processors in the ARTIK modules using Arduino IDE with libArduino to C Use C to access the ARTIK hardware via a file based API Use Node.js and Python inside the ARTIK module Integrate applications with the Samsung SAMI data aggregation hub Use Temboo to generate IoT software solutions that can be downloaded and compiled natively inside the ARTIK Debug applications with software and hardware probes Who This Book Is For Moderately experienced developers wanting to understand ARTIK and how to interact with it from within their own apps or web services.

Ontologies for Agents: Theory and Experiences Valentina Tamma, Stephen Cranefield, Timothy W. Finin, Steven Willmott, 2006-03-30 The volume aims at providing a comprehensive review of the diverse efforts covering the gap existing between the two main perspectives on the topic of ontologies for multi-agent systems, namely: How ontologies should be modelled and represented in order to be effectively used in agent systems, and on the other hand, what kind of capabilities should be exhibited by an agent in order to make use of ontological knowledge and to perform efficient reasoning with it. The volume collects the most significant papers of the AAMAS 2002 and AAMAS 2003 workshop on ontologies for agent systems, and the EKAW 2002 workshop on ontologies for multi-agent systems. **Ubiquitous Intelligence and Computing** Jadwiga Indulska,Laurence T. Yang,Theo Ungerer,Jiannong Cao,2007-08-15 A fascinating bird's eye view on a hugely relevant topic. This book constitutes the refereed proceedings of the 4th International Conference on Ubiquitous Intelligence and Computing held in Hong Kong, China in 2007, co-located with ATC 2007, the 4th International Conference on Autonomic and Trusted Computing. The 119 revised full papers presented together with 1 keynote paper and 1 invited paper were carefully reviewed and selected from 463 submissions. The papers are organized in topical sections.

Ubiquitous Intelligence and Computing Hai Jin,Laurence T. Yang,Jeffrey J.-P. Tsai,2006-08-29 This book is the refereed proceedings of the Third International Conference on Ubiquitous Intelligence and Computing, UIC 2006, held in Wuhan, China. The book presents 117 revised full papers together with a keynote paper were carefully reviewed and selected from 382 submissions. The papers are organized in topical sections on smart objects and embedded systems; smart spaces, environments, and platforms; ad-hoc and intelligent networks; sensor networks, and more.

Exploring Raspberry Pi Derek Molloy, 2016-06-13 Expand Raspberry Pi capabilities with fundamental engineering principles Exploring Raspberry Pi is the innovators guide to bringing Raspberry Pi to life. This book favors engineering principles over a 'recipe' approach to give you the skills you need to design and build your own projects. You'll understand the fundamental principles in a way that transfers to any type of electronics, electronic modules, or external peripherals, using a learning by doing approach that caters to both beginners and experts. The book begins with basic Linux and programming skills, and helps you stock your inventory with common parts and supplies. Next, you'll learn how to make parts work together to achieve the goals of your project, no matter what type of components you use. The companion website provides a full repository that structures all of the code and scripts, along with links to video tutorials and supplementary content that takes you deeper into your project. The Raspberry Pi's most famous feature is its adaptability. It can be used for thousands of electronic applications, and using the Linux OS expands the functionality even more. This book helps you get the most from your Raspberry Pi, but it also gives you the fundamental engineering skills you need to incorporate any electronics into any project. Develop the Linux and programming skills you need to build basic applications Build your inventory of parts so you can always make it work Understand interfacing, controlling, and communicating with almost any component Explore advanced applications with video, audio, real-world interactions, and more Be free to adapt and create with Exploring Raspberry Pi.

Emerging Trends in Technological Innovation Luis M. Camarinha-Matos,Pedro Pereira,Luis Ribeiro,2010-02-26 Identifying Emerging Trends in Technological Innovation Doctoral programs in science and engineering are important sources of innovative ideas and techniques that might lead to new products and technological innovation. Certainly most PhD students are not experienced researchers and are in the process of learning how to do research. Nevertheless, a number of empiric studies also show that a high number of technological innovation ideas are produced in the early careers of researchers. The combination of the eagerness to try new approaches and directions of young doctoral students with the experience and broad knowledge of their supervisors is likely to result in an important pool of innovation potential. The DoCEIS doctoral conference on Computing, Electrical and Industrial En- neering aims at creating a space for sharing and discussing ideas and results from doctoral research in these inter-related areas of engineering. Innovative ideas and hypotheses can be better enhanced when presented and discussed in an encouraging and open environment. DoCEIS aims to provide such an environment, releasing PhD students from the pressure of presenting their propositions in more formal contexts.

Hands-On Robotics Programming with C++ Dinesh Tavasalkar, 2019-03-30 Enhance your programming skills to build exciting robotic projects Key FeaturesBuild an intelligent robot that can detect and avoid obstacles and respond to voice commandsDetect and track objects and faces using OpenCVControl your robot with a GUI button designed using Qt5Book Description C++ is one of the most popular legacy programming languages for robotics, and a combination of C++ and robotics hardware is used in many leading industries. This book will bridge the gap between Raspberry Pi and C/C++ programming and enable you to develop applications for Raspberry Pi. To follow along with the projects covered in the book, you can implement C programs in Raspberry Pi with the wiringPi library. With this book, you'll develop a fully functional car robot and write programs to move it in different directions. You'll then create an obstacle - avoiding robot using an ultrasonic sensor. Furthermore, you'll find out how to control the robot wirelessly using your PC/Mac. This book will also help you work with object detection and tracking using OpenCV, and guide you through exploring face detection techniques. Finally, you will create an Android app and control the robot wirelessly with an Android smartphone. By the end of this book, you will have gained experience in developing a robot using Raspberry Pi and C/C++ programming. What you will learnInstall software in Raspberry Pi compatible with C++ programmingProgram the Raspberry Pi in C++ to run a motorControl RPi-powered robot wirelessly with your laptop or PCProgram an RPi camera using OpenCV Control a Raspberry Pi robot with voice commandsImplement face and object detection with Raspberry PiWho this book is for This book is for developers, programmers. and robotics enthusiasts interested in leveraging C++ to build exciting robotics applications. Prior knowledge of C++ is necessary to understand the projects covered in this book.

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Bluetooth Agent Introduction

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