

Ardrone Sim

Andrew Yeh Ching Nee, Soh Khim Ong

Advance Trends in Soft Computing Mo Jamshidi, Vladik Kreinovich, Janusz Kacprzyk, 2013-11-18 This book is the proceedings of the 3rd World Conference on Soft Computing (WCSC), which was held in San Antonio, TX, USA, on December 16-18, 2013. It presents start-of-the-art theory and applications of soft computing together with an in-depth discussion of current and future challenges in the field, providing readers with a 360 degree view on soft computing. Topics range from fuzzy sets, to fuzzy logic, fuzzy mathematics, neuro-fuzzy systems, fuzzy control, decision making in fuzzy environments, image processing and many more. The book is dedicated to Lotfi A. Zadeh, a renowned specialist in signal analysis and control systems research who proposed the idea of fuzzy sets, in which an element may have a partial membership, in the early 1960s, followed by the idea of fuzzy logic, in which a statement can be true only to a certain degree, with degrees described by numbers in the interval $[0,1]$. The performance of fuzzy systems can often be improved with the help of optimization techniques, e.g. evolutionary computation, and by endowing the corresponding system with the ability to learn, e.g. by combining fuzzy systems with neural networks. The resulting "consortium" of fuzzy, evolutionary, and neural techniques is known as soft computing and is the main focus of this book.

Intelligent Robotics Zhiwen Yu, Xinhong Hei, Duanling Li, Xianhua Song, Zeguang Lu, 2023-02-17 This book constitutes selected papers presented during the Third China Annual Intelligent Robotics Conference, CCF CIRAC 2022, held in Xi' an, China, in December 2022. The 35 papers presented were thoroughly reviewed and selected from the 120 qualified submissions. They are organized in the following topical sections: robot safety; intelligent robot sensing;

autonomous robot navigation; artificial intelligence and cloud robot; unmanned cluster collaboration; natural human-computer interaction; other robot-related technologies.

ITNG 2021 18th International Conference on Information Technology-New Generations Shahram Latifi, 2021-06-04 This volume represents the 18th International Conference on Information Technology - New Generations (ITNG), 2021. ITNG is an annual event focusing on state of the art technologies pertaining to digital information and communications. The applications of advanced information technology to such domains as astronomy, biology, education, geosciences, security, and health care are the among topics of relevance to ITNG. Visionary ideas, theoretical and experimental results, as well as prototypes, designs, and tools that help the information readily flow to the user are of special interest. Machine Learning, Robotics, High Performance Computing, and Innovative Methods of Computing are examples of related topics. The conference features keynote speakers, a best student award, poster award, service award, a technical open panel, and workshops/exhibits from industry, government and academia. This publication is unique as it captures modern trends in IT with a balance of theoretical and experimental work. Most other work focus either on theoretical or experimental, but not both. Accordingly, we do not know of any competitive literature.

The Book of the Chronicles of Keith, Grange, Ruthven, Cairney, and Botriphnie James Frederick Skinner Gordon, 1880

Robotics in Education Richard Balogh, David Obdržálek, Eftychios Christoforou, 2023-11-04 This book provides an overview of Educational Robotics and includes information that reflects the current status of the

field, research activity, experiences, and new tools. It compiles the contributions presented at the 14th International Conference on Robotics in Education (RiE2023). Beyond insights into theoretical aspects, practical projects and syllabus activities exemplify the concepts and provide implementation ideas, which span the whole educational system from kindergarten to the university level. The relevance to science, technology, engineering, and mathematics (STEM) education is highlighted by teaching the topics in a unified framework. The book constitutes a valuable resource for educators, researchers, scientists, and engineers interested in robotics. It covers topics including school teaching curricula, educational methodologies and pedagogy, projects, competitions, hardware, simulations, programming, machine learning, and artificial intelligence in education.

Proceedings of the 18th Asia Pacific Symposium on Intelligent and Evolutionary Systems – Volume 2 Hisashi Handa, Hisao Ishibuchi, Yew-Soon Ong, Kay-Chen Tan, 2014-11-04 This book contains a collection of the papers accepted in the 18th Asia Pacific Symposium on Intelligent and Evolutionary Systems (IES 2014), which was held in Singapore from 10-12th November 2014. The papers contained in this book demonstrate notable intelligent systems with good analytical and/or empirical results.

ROBOT 2017: Third Iberian Robotics Conference Anibal Ollero, Alberto Sanfeliu, Luis Montano, Nuno Lau, Carlos Cardeira, 2017-11-10 These volumes of Advances in Intelligent Systems and Computing highlight papers presented at the Third Iberian Robotics Conference (ROBOT 2017). Held from 22 to 24 November 2017 in Seville, Spain, the conference is a part of a series of conferences co-organized by SEIDROB (Spanish Society for Research and Development in Robotics) and SPR (Portuguese Society for Robotics). The

conference is focused on Robotics scientific and technological activities in the Iberian Peninsula, although open to research and delegates from other countries. Thus, it has more than 500 authors from 21 countries. The volumes present scientific advances but also robotic industrial applications, looking to promote new collaborations between industry and academia.

Advances in Autonomous Robotics Systems Michael Mistry, Aleš Leonardis, Mark Witkowski, Chris Melhuish, 2014-08-23 This book constitutes the refereed proceedings of the 15th Conference on Advances in Autonomous Robotics, TAROS 2014, held in Birmingham, UK, in September 2014. The 23 revised full papers presented together with 9 extended abstracts were carefully reviewed and selected from 48 submissions. The overall program covers various aspects of robotics, including navigation, planning, sensing and perception, flying and swarm robots, ethics, humanoid robotics, human-robot interaction, and social robotics.

Artificial Intelligence and Evolutionary Computations in Engineering Systems Subhransu Sekhar Dash, K. Vijayakumar, Bijaya Ketan Panigrahi, Swagatam Das, 2017-07-11 The volume is a collection of high-quality peer-reviewed research papers presented in the International Conference on Artificial Intelligence and Evolutionary Computation in Engineering Systems (ICAIECES 2016) held at SRM University, Chennai, Tamilnadu, India. This conference is an international forum for industry professionals and researchers to deliberate and state their research findings, discuss the latest advancements and explore the future directions in the emerging areas of engineering and technology. The book presents original work and novel ideas, information, techniques and applications in the field of communication, computing and power technologies.

Springer Handbook of Augmented Reality Andrew Yeh Ching Nee, Soh Khim Ong, 2023-01-01 The Springer Handbook of Augmented Reality presents a comprehensive and authoritative guide to augmented reality (AR) technology, its numerous applications, and its intersection with emerging technologies. This book traces the history of AR from its early development, discussing the fundamentals of AR and its associated science. The handbook begins by presenting the development of AR over the last few years, mentioning the key pioneers and important milestones. It then moves to the fundamentals and principles of AR, such as photogrammetry, optics, motion and objects tracking, and marker-based and marker-less registration. The book discusses both software toolkits and techniques and hardware related to AR, before presenting the applications of AR. This includes both end-user applications like education and cultural heritage, and professional applications within engineering fields, medicine and architecture, amongst others. The book concludes with the convergence of AR with other emerging technologies, such as Industrial Internet of Things and Digital Twins. The handbook presents a comprehensive reference on AR technology from an academic, industrial and commercial perspective, making it an invaluable resource for audiences from a variety of backgrounds.

From Animals to Animats 14 Elio Tuci, Alexandros Giagkos, Myra Wilson, John Hallam, 2016-08-09 This book constitutes the proceedings of the 14th International Conference on Simulation of Adaptive Behavior, SAB 2016, held in Aberystwyth, UK, in August 2016. The 31 papers presented in this volume were carefully reviewed and selected from 45 submissions. They cover the main areas in animat research, including the animat approach and methodology, perception and motor control, learning and adaptation, evolution, and

collective and social behavior.

Agent and Multi-Agent Systems: Technologies and Applications Gordan Jezic, Mario Kusek, Ignac Lovrek, Robert J. Howlett, Lakhmi C. Jain, 2014-05-16 Agents and multi-agent systems are related to a modern software paradigm which has long been recognized as a promising technology for constructing autonomous, complex and intelligent systems. The topics covered in this volume include agent-oriented software engineering, agent co-operation, co-ordination, negotiation, organization and communication, distributed problem solving, multi-agent communities, rational and clustering agents, learning paradigms, agent cognitive models, and heterogenous multi-agent environments. The volume highlights new trends and challenges in agent and multi-agent research and includes 30 papers classified in five specific topics: Modeling and logic agents, Knowledge based agent systems, Cognitive and cooperative multi-agent systems, Agent-based Modeling and Simulation, and Learning Paradigms and Applications: Agent-based Approach. The published papers have been presented at the 8th KES Conference on Agent and Multi-Agent Systems - Technologies and Applications (KES-AMSTA 2014) held in Chania on the island of Crete in Greece in June 2014. The presented results will be of value to the research community working in the fields of artificial intelligence, collective computational intelligence, robotics, dialogue systems and, in particular, agent and multi-agent systems, technologies and applications.

Intelligent Autonomous Systems 12 Sukhan Lee, Hyungsuck Cho, Kwang-Joon Yoon, Jangmyung Lee, 2012-11-02 Intelligent autonomous systems are emerged as a key enabler for the creation of a new paradigm of services to humankind, as seen by the recent advancement of autonomous cars licensed for driving in our streets, of unmanned aerial and underwater vehicles carrying out hazardous

tasks on-site, and of space robots engaged in scientific as well as operational missions, to list only a few. This book aims at serving the researchers and practitioners in related fields with a timely dissemination of the recent progress on intelligent autonomous systems, based on a collection of papers presented at the 12th International Conference on Intelligent Autonomous Systems, held in Jeju, Korea, June 26-29, 2012. With the theme of "Intelligence and Autonomy for the Service to Humankind, the conference has covered such diverse areas as autonomous ground, aerial, and underwater vehicles, intelligent transportation systems, personal/domestic service robots, professional service robots for surgery/rehabilitation, rescue/security and space applications, and intelligent autonomous systems for manufacturing and healthcare. This volume 1 includes contributions devoted to Autonomous Ground Vehicles and Mobile Manipulators, as well as Unmanned Aerial and Underwater Vehicles and Bio-inspired Robotics.

Towards Autonomous Robotic Systems Clare Dixon, Karl Tuyls, 2015-07-17 This book constitutes the refereed proceedings of the 16th Annual Conference on Towards Autonomous Robotics, TAROS 2015, held in Liverpool UK, in September 2015. The 16 revised full papers presented together with 18 short papers were carefully reviewed and selected from 59 submissions. The overall program covers various aspects of robotics, including navigation, planning, sensing and perception, flying and swarm robots, ethics, humanoid robotics, human-robot interaction, and social robotics.

UAV Inspection of Large Components. Adaptive Navigation at Runtime Michelle Bettendorf, 2022-02-03 Bachelor Thesis from the year 2019 in the subject Computer Science - Applied, grade: 1.0, University of Augsburg, language: English, abstract: In this thesis, two problems are covered. The first one is

to estimate the position of a drone out of two different given transformations, which don't have the same coordinate origin. Furthermore, measurement errors have to be outbalanced so that the position estimation is as accurate as possible. In order to solve this problem, a Kalman Filter was utilized. The second problem is to direct the drone to given goal positions while avoiding obstacles. For directing the drone to the desired location a vector flight control with temporary goals was created. The vector flight control is working online and is constantly using the current estimated position of the Kalman Filter in order to direct the drone correctly at each time. This thesis is covering the concept, the implementation and evaluation of these algorithms.

Robot Intelligence Technology and Applications 4 Jong-Hwan Kim, Fakhri Karray, Jun Jo, Peter Sincak, Hyun Myung, 2016-07-08 This book covers all aspects of robot intelligence from perception at sensor level and reasoning at cognitive level to behavior planning at execution level for each low level segment of the machine. It also presents the technologies for cognitive reasoning, social interaction with humans, behavior generation, ability to cooperate with other robots, ambience awareness, and an artificial genome that can be passed on to other robots. These technologies are to materialize cognitive intelligence, social intelligence, behavioral intelligence, collective intelligence, ambient intelligence and genetic intelligence. The book aims at serving researchers and practitioners with a timely dissemination of the recent progress on robot intelligence technology and its applications, based on a collection of papers presented at the 4th International Conference on Robot Intelligence Technology and Applications (RiTA), held in Bucheon, Korea, December 14 - 16, 2015. For better

readability, this edition has the total of 49 articles grouped into 3 chapters: Chapter I: Ambient, Behavioral, Cognitive, Collective, and Social Robot Intelligence, Chapter II: Computational Intelligence and Intelligent Design for Advanced Robotics, Chapter III: Applications of Robot Intelligence Technology .

Deep Learning for Unmanned Systems Anis Koubaa,Ahmad Taher Azar,2021-10-01
This book is used at the graduate or advanced undergraduate level and many others. Manned and unmanned ground, aerial and marine vehicles enable many promising and revolutionary civilian and military applications that will change our life in the near future. These applications include, but are not limited to, surveillance, search and rescue, environment monitoring, infrastructure monitoring, self-driving cars, contactless last-mile delivery vehicles, autonomous ships, precision agriculture and transmission line inspection to name just a few. These vehicles will benefit from advances of deep learning as a subfield of machine learning able to endow these vehicles with different capability such as perception, situation awareness, planning and intelligent control. Deep learning models also have the ability to generate actionable insights into the complex structures of large data sets. In recent years, deep learning research has received an increasing amount of attention from researchers in academia, government laboratories and industry. These research activities have borne some fruit in tackling some of the challenging problems of manned and unmanned ground, aerial and marine vehicles that are still open. Moreover, deep learning methods have been recently actively developed in other areas of machine learning, including reinforcement training and transfer/meta-learning, whereas standard, deep learning methods such as recent neural network (RNN) and coevolutionary

neural networks (CNN). The book is primarily meant for researchers from academia and industry, who are working on in the research areas such as engineering, control engineering, robotics, mechatronics, biomedical engineering, mechanical engineering and computer science. The book chapters deal with the recent research problems in the areas of reinforcement learning-based control of UAVs and deep learning for unmanned aerial systems (UAS) The book chapters present various techniques of deep learning for robotic applications. The book chapters contain a good literature survey with a long list of references. The book chapters are well written with a good exposition of the research problem, methodology, block diagrams and mathematical techniques. The book chapters are lucidly illustrated with numerical examples and simulations. The book chapters discuss details of applications and future research areas.

Advances in Visual Computing George Bebis, Richard Boyle, Bahram Parvin, Darko Koracin, Ryan McMahan, Jason Jerald, Hui Zhang, Steven Drucker, Kambhamettu Chandra, El Choubassi Maha, Zhigang Deng, Mark Carlson, 2014-12-02 The two volume set LNCS 8887 and 8888 constitutes the refereed proceedings of the 10th International Symposium on Visual Computing, ISVC 2014, held in Las Vegas, NV, USA. The 74 revised full papers and 55 poster papers presented together with 39 special track papers were carefully reviewed and selected from more than 280 submissions. The papers are organized in topical sections: Part I (LNCS 8887) comprises computational bioimaging, computer graphics; motion, tracking, feature extraction and matching, segmentation, visualization, mapping, modeling and surface reconstruction, unmanned autonomous systems, medical imaging, tracking for human activity monitoring, intelligent transportation systems, visual perception and robotic systems. Part II (LNCS

8888) comprises topics such as computational bioimaging , recognition, computer vision, applications, face processing and recognition, virtual reality, and the poster sessions.

Neural Information Processing Tom Gedeon,Kok Wai Wong,Minho Lee,2019-12-12
The three-volume set of LNCS 11953, 11954, and 11955 constitutes the proceedings of the 26th International Conference on Neural Information Processing, ICONIP 2019, held in Sydney, Australia, in December 2019. The 173 full papers presented were carefully reviewed and selected from 645 submissions. The papers address the emerging topics of theoretical research, empirical studies, and applications of neural information processing techniques across different domains. The first volume, LNCS 11953, is organized in topical sections on adversarial networks and learning; convolutional neural networks; deep neural networks; feature learning and representation; human centred computing; human centred computing and medicine; hybrid models; and artificial intelligence and cybersecurity.

Advanced Computing and Intelligent Technologies Monica Bianchini,Vincenzo Piuri,Sanjoy Das,Rabindra Nath Shaw,2021-07-21 This book gathers selected high-quality research papers presented at International Conference on Advanced Computing and Intelligent Technologies (ICACIT 2021) held at NCR New Delhi, India, during March 20-21, 2021, jointly organized by Galgotias University, India, and Department of Information Engineering and Mathematics Università Di Siena, Italy. It discusses emerging topics pertaining to advanced computing, intelligent technologies, and networks including AI and machine learning, data mining, big data analytics, high-performance computing network performance analysis, Internet of things networks, wireless sensor networks, and others. The book offers a valuable asset for researchers from

both academia and industries involved in advanced studies.

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