

Ardrone Flight

Mo Jamshidi, Vladik Kreinovich, Janusz Kacprzyk

Entertainment Computing - ICEC 2014 Yusuf Pisan,Nikitas Marinos Sgouros,Tim Marsh,2014-09-24

This book constitutes the refereed proceedings of the 13th International Conference on Entertainment Computing, ICEC 2014, held in Sydney, Australia, in October 2013. The 20 full papers, 6 short papers and 8 posters presented were carefully reviewed and selected from 62 submissions. In addition to these papers, the program featured 3 demonstration papers, and 2 workshops. The papers cover various aspects of entertainment computing including authoring, development, use and evaluation of digital entertainment artefacts and processes.

Intelligent Technologies for Interactive Entertainment Dennis Reidsma,2014-06-20 This book constitutes the proceedings of the 6th International Conference on Intelligent Technologies for Interactive Entertainment, INTETAIN 2014. The 8 full papers presented together with 4 special session papers, 4 panels and 6 extended abstracts were carefully selected from 26 submissions. The papers present interdisciplinary research, covering topics such as creativity applied to technology, AI, cognition and models of engagement and play. The special session papers address the topic of humor in intelligent environments.

Robot Intelligence Technology and Applications 4 Jong-Hwan Kim,Fakhri Karray,Jun Jo,Peter Sincak,Hyun Myung,2016-07-08 This book covers all aspects of robot intelligence from perception at sensor level and reasoning at cognitive level to behavior planning at execution level for each low level segment of the machine. It also presents the technologies for cognitive reasoning, social interaction with humans, behavior generation, ability to cooperate with other robots, ambience awareness, and an artificial genome that can be passed on to other robots. These technologies are to materialize cognitive intelligence, social intelligence, behavioral intelligence, collective intelligence, ambient intelligence and genetic intelligence. The book aims at serving researchers and practitioners with a timely dissemination of the recent progress on robot intelligence technology and its applications, based on a collection of papers presented at the 4th International Conference on Robot Intelligence Technology and Applications (RiTA), held in Bucheon, Korea, December 14 - 16, 2015. For better readability, this edition has the total of 49 articles grouped into 3 chapters: Chapter I: Ambient, Behavioral, Cognitive, Collective, and Social Robot Intelligence, Chapter II: Computational Intelligence and Intelligent Design for Advanced Robotics, Chapter III: Applications of Robot Intelligence Technology .

ROBOT2013: First Iberian Robotics Conference Manuel A. Armada,Alberto Sanfeliu,Manuel Ferre,2013-11-12 The interest in robotics has remarkably augmented over recent years. Novel solutions for complex and very diverse application fields (exploration/intervention in severe environments, assistive, social, personal services, emergency rescue operations, transportation, entertainment, unmanned aerial vehicles, medical, etc.), has been anticipated by means of a large progress in this area of robotics. Moreover, the amalgamation of original ideas and related innovations, the search for new potential applications and the use of state of the art supporting technologies permit to foresee an important step forward and a significant socio-economic impact of advanced robot technology in the forthcoming years. In response to the technical challenges in the development of these sophisticated machines, a significant research and development effort has yet to be undertaken. It concerns embedded technologies (for power sources, actuators, sensors, information systems), new design methods, adapted control techniques for highly redundant systems, as well as operational and decisional autonomy and human/robot co-existence. This book contains the proceedings of the ROBOT 2013: FIRST IBERIAN ROBOTICS CONFERENCE and it can be said that included both state of the art and more practical presentations dealing with implementation problems,

support technologies and future applications. A growing interest in Assistive Robotics, Agricultural Robotics, Field Robotics, Grasping and Dexterous Manipulation, Humanoid Robots, Intelligent Systems and Robotics, Marine Robotics, has been demonstrated by the very relevant number of contributions. Moreover, ROBOT2013 incorporates a special session on Legal and Ethical Aspects in Robotics that is becoming a topic of key relevance. This Conference will be held in Madrid (28-29 November 2013), organised by the Sociedad Española para la Investigación y Desarrollo en Robótica (SEIDROB) and by the Centre for Automation and Robotics - CAR (Universidad Politécnica de Madrid (UPM) and Consejo Superior de Investigaciones Científicas (CSIC)), along with the co-operation of Grupo Temático de Robótica CEA-GTRob, Sociedade Portuguesa de Robotica (SPR), and Asociación Española de Promoción de la Investigación en Agentes Físicos (RedAF).

The Future of Violence Benjamin Wittes, Gabriella Blum, 2015-03-10 The ability to inflict pain and suffering on large groups of people is no longer limited to the nation-state. New technologies are putting enormous power into the hands of individuals across the world—a shift that, for all its sunny possibilities, entails enormous risk for all of us, and may even challenge the principles on which the modern nation state is founded. In short, if our national governments can no longer protect us from harm, they will lose their legitimacy. Detailing the challenges that states face in this new world, legal scholars Benjamin Wittes and Gabriella Blum controversially argue in [Title TK] that national governments must expand their security efforts to protect the lives and liberty of their citizens. Wittes and Blum show how advances in cybertechnology, biotechnology, and robotics mean that more people than ever before have access to technologies—from drones to computer networks and biological data—that could possibly be used to extort or attack states and private citizens. Security, too, is no longer only under governmental purview, as private companies or organizations control many of these technologies: internet service providers in the case of cyber terrorism and digital crime, or academic institutions and individual researchers and publishers in the case of potentially harmful biotechnologies. As Wittes and Blum show, these changes could undermine the social contract that binds citizens to their governments. In this brave new world of dispersed threats, Wittes and Blum persuasively argue that the best means for safeguarding our liberty and privacy are strong governmental surveillance and security networks. Indeed, they show—through engaging looks at political thinkers from Thomas Hobbes to the Founders and beyond—that security and liberty are mutually supportive, rather than existing in a precarious balance in which the increase in one leads to a proportional decrease in the other. And not only must we bolster our domestic security efforts, but we must think internationally. Our best defense is increasingly a transnational one: more multinational forces and greater action to protect (and protect against) the territory of weaker states who do not yet have the capability to police themselves. [Title TK] is at once an exposé of our emerging world—one in which students can print guns with 3-D printers and scientists’ manipulations of viruses can be recreated and unleashed by ordinary people—and an authoritative blueprint for how government and individuals must adapt to it.

Parallel and Distributed Computing, Applications and Technologies Jong Hyuk Park, Hong Shen, Yunsick Sung, Hui Tian, 2019-02-07 This book constitutes the refereed proceedings of the 19th International Conference on CParallel and Distributed Computing, Applications and Technologies, PDCAT 2018, held in Jeju Island, South Korea, in August 2018. The 35 revised full papers presented along with the 14 short papers and were carefully reviewed and selected from 150 submissions. The papers of this volume are organized in topical sections on wired and wireless communication systems, high dimensional data representation and processing, networks and information security, computing techniques for efficient

networks design, electronic circuits for communication systems.

Ad-hoc Networks and Wireless Miguel Garcia Pineda, Jaime Lloret, Symeon Papavassiliou, Stefan Ruehrup, Carlos Becker Westphall, 2015-02-09 This book constitutes the refereed proceedings of six workshops collocated with the 13th International Conference on Ad-Hoc Networks and Wireless, ADHOC-NOW Workshops 2014, held in Benidorm, Spain, in June 2014. The 25 revised full papers presented were carefully reviewed and selected from 59 submissions. The papers address the following topics: emerging technologies for smart devices; marine sensors and systems; multimedia wireless ad hoc networks; security in ad hoc networks; smart sensor protocols and algorithms; wireless sensor, actuator and robot networks.

Advance Trends in Soft Computing Mo Jamshidi, Vladik Kreinovich, Janusz Kacprzyk, 2013-11-18 This book is the proceedings of the 3rd World Conference on Soft Computing (WCSC), which was held in San Antonio, TX, USA, on December 16-18, 2013. It presents start-of-the-art theory and applications of soft computing together with an in-depth discussion of current and future challenges in the field, providing readers with a 360 degree view on soft computing. Topics range from fuzzy sets, to fuzzy logic, fuzzy mathematics, neuro-fuzzy systems, fuzzy control, decision making in fuzzy environments, image processing and many more. The book is dedicated to Lotfi A. Zadeh, a renowned specialist in signal analysis and control systems research who proposed the idea of fuzzy sets, in which an element may have a partial membership, in the early 1960s, followed by the idea of fuzzy logic, in which a statement can be true only to a certain degree, with degrees described by numbers in the interval $[0,1]$. The performance of fuzzy systems can often be improved with the help of optimization techniques, e.g. evolutionary computation, and by endowing the corresponding system with the ability to learn, e.g. by combining fuzzy systems with neural networks. The resulting “consortium” of fuzzy, evolutionary, and neural techniques is known as soft computing and is the main focus of this book.

Smart Graphics Yaxi Chen, Marc Christie, Wenrong Tan, 2017-03-24 This book constitutes the proceedings of the 13th International Symposium on Smart Graphics, SG 2015, held in Chengdu, China, in August 2015. The 17 full and 3 short papers presented in this volume were carefully reviewed and selected from 35 submissions. They are organized in topical sections named: graphics, sketching and visualization, automation and evaluation, image processing, and posters and demo session.

Robot Operating System (ROS) Anis Koubaa, 2017-05-25 This second volume is a continuation of the successful first volume of this Springer book, and as well as addressing broader topics it puts a particular focus on unmanned aerial vehicles (UAVs) with Robot Operating System (ROS). Consisting of three types of chapters: tutorials, cases studies, and research papers, it provides comprehensive additional material on ROS and the aspects of developing robotics systems, algorithms, frameworks, and applications with ROS. ROS is being increasingly integrated in almost all kinds of robots and is becoming the de-facto standard for developing applications and systems for robotics. Although the research community is actively developing applications with ROS and extending its features, amount of literature references is not representative of the huge amount of work being done. The book includes 19 chapters organized into six parts: Part 1 presents the control of UAVs with ROS, while in Part 2, three chapters deal with control of mobile robots. Part 3 provides recent work toward integrating ROS with Internet, cloud and distributed systems. Part 4 offers five case studies of service robots and field experiments. Part 5 presents signal-processing tools for perception and sensing, and lastly, Part 6 introduces advanced simulation frameworks. The diversity of topics in the book makes it a unique and valuable reference resource for ROS users, researchers, learners and developers.

Artificial Intelligence Research and Development A. Nebot, X. Binefa, R. López de Mántaras, 2016-09-21

The Catalan Association for Artificial Intelligence (ACIA) was formed in 1994 with the aim of promoting cooperation between researchers in artificial intelligence within the Catalan speaking community. This objective has been achieved and widened since the association held their first conference in 1998, and the annual conference of the association has become an international event presenting and discussing the latest research in AI, which attracts AI researchers from around the world. This book presents the proceedings of the 19th International Conference of the Catalan Association for Artificial Intelligence (CCIA 2016), held in Barcelona, Spain, on 19-21 October. From a total of 50 original contributions, 16 long papers and 22 short papers were accepted for presentation at the conference on the basis of their relevance, originality and technical validity. The book is divided into 7 sections: Invited Talks (synopsis only); Vision and Robotics; Logic, Constraint Satisfaction and Qualitative Theory; Classification and Clustering; Modelling; Planning and Recommender Systems; Lexical Knowledge Representation and Natural Language Processing. Providing an overview of the latest developments in the field, this book will be of interest to all those whose work involves research into, and the application of, artificial intelligence.

Digital Culture & Society (DCS) Tim Hector,David Waldecker,Niklas Strüver,Tanja Aal,2023-09-30 Modern mundane life is brimming with a variety of data-driven technologies that are supposed to augment the practices they are involved in. As humans bring these technologies into their lives in a process of domestication, they tame them and are simultaneously influenced by their presence. In combining domestication research and an empirical analysis of current, digital, and interconnected media, this issue examines the process of taming with an emphasis on practices. The contributions in this issue explore the use of digitally connected media such as vacuum robots, smart speakers, drones, and kitchen appliances with reference to the domestication paradigm from interdisciplinary perspectives including media studies, sociology, anthropology, and human-computer interaction.

Towards Autonomous Robotic Systems Clare Dixon,Karl Tuyls,2015-07-17 This book constitutes the refereed proceedings of the 16th Annual Conference on Towards Autonomous Robotics, TAROS 2015, held in Liverpool UK, in September 2015. The 16 revised full papers presented together with 18 short papers were carefully reviewed and selected from 59 submissions. The overall program covers various aspects of robotics, including navigation, planning, sensing and perception, flying and swarm robots, ethics, humanoid robotics, human-robot interaction, and social robotics.

The Greys Are Among Us Anthony Irvin,2017-03-17 Alex is a fourth grader who loves going to his Missouri elementary school, watching cartoons about heroes, gazing at the stars outside his window, and dreaming of what it would be like to live on another planet. As he begins to nurture a fascination with space and aliens, Alex has no idea of the adventure that lies ahead for him. One day after Alex's classmates discuss the possibility of ghosts, aliens, and unidentified flying objects, he decides to embark on a quest with his friend, Carlton, to prove that UFOs are real. A few nights into their hunt, Alex sees something strange flickering in the sky. Now on a mission to tell the world of his discovery, Alex makes a speech after winning the spelling bee that shocks everyone. When the gifted Alex advances to middle school before all his friends, he makes a great effort to attain his goal of teaching others about extraterrestrials. But little does he know that something is about to happen that even he could have never predicted. In this exciting science fiction tale, a Midwestern boy sets out on a determined mission to prove that aliens really do exist.

Frontiers of Intelligent Autonomous Systems Sukhan Lee,Kwang-Joon Yoon,Jangmyung Lee,2012-12-15 This carefully edited volume aims at providing readers with the most recent progress on intelligent autonomous systems, with its particular emphasis on intelligent autonomous ground, aerial and underwater vehicles as well as service robots for home and healthcare under the context of the

mentioned convergence. “Frontiers of Intelligent Autonomous Systems” includes thoroughly revised and extended papers selected from the 12th International Conference on Intelligent Autonomous Systems (IAS-12), held in Jeju, Korea, June 26-29, 2012. The editors chose 35 papers out of the 202 papers presented at IAS-12 which are organized into three chapters: Chapter 1 is dedicated to autonomous navigation and mobile manipulation, Chapter 2 to unmanned aerial and underwater vehicles and Chapter 3 to service robots for home and healthcare. To help the readers to easily access this volume, each chapter starts with a chapter summary introduced by one of the editors: Chapter 1 by Sukhan Lee, Chapter 2 by Kwang Joon Yoon and Chapter 3 by Jangmyung Lee.

Multi-robot Exploration for Environmental Monitoring Kshitij Tiwari, Nak Young Chong, 2019-11-29 Multi-robot Exploration for Environmental Monitoring: The Resource Constrained Perspective provides readers with the necessary robotics and mathematical tools required to realize the correct architecture. The architecture discussed in the book is not confined to environment monitoring, but can also be extended to search-and-rescue, border patrolling, crowd management and related applications. Several law enforcement agencies have already started to deploy UAVs, but instead of using teleoperated UAVs this book proposes methods to fully automate surveillance missions. Similarly, several government agencies like the US-EPA can benefit from this book by automating the process. Several challenges when deploying such models in real missions are addressed and solved, thus laying stepping stones towards realizing the architecture proposed. This book will be a great resource for graduate students in Computer Science, Computer Engineering, Robotics, Machine Learning and Mechatronics. Analyzes the constant conflict between machine learning models and robot resources Presents a novel range estimation framework tested on real robots (custom built and commercially available)

Drones For Dummies Mark LaFay, 2015-07-07 The fast and easy way to pick out, set up, and learn to fly your drone Ready to soar into the world of unmanned aircraft? Drones For Dummies introduces you to the fascinating world of UAVs. Written in plain English and brimming with friendly instruction, Drones For Dummies provides you with the information you need to find and purchase the right drone for your needs, examples of ways to use a drone, and even drone etiquette and the laws and regulations governing consumer drone usage. Plus, you'll discover the basics of flight, including how to use a drone to capture photos and video. Originally designed to assist in military and special operations applications, the use of drones has expanded into the public service sector and the consumer market for people looking to have a good time flying an aircraft remotely. Drones For Dummies covers everything you need to know to have fun with your UAV, and is packed with cool ways to expand your drone's use beyond simply flying. Pick the perfect drone to suit your needs Properly set up and fly a drone Use a drone to capture images and footage with a camera Tips for maintaining your drone If you're interested in the exciting new technology of unmanned aircraft vehicles, Drones For Dummies helps you take flight.

Robotics and Mechatronics Saïd Zeghloul, Med Amine Laribi, Jean-Pierre Gazeau, 2015-09-21 This volume contains papers that have been selected after review for oral presentation at ISRM 2015, the Fourth IFToMM International Symposium on Robotics and Mechatronics held in Poitiers, France 23-24 June 2015. These papers provide a vision of the evolution of the disciplines of robotics and mechatronics, including but not limited to: mechanism design; modeling and simulation; kinematics and dynamics of multibody systems; control methods; navigation and motion planning; sensors and actuators; bio-robotics; micro/nano-robotics; complex robotic systems; walking machines, humanoids-parallel kinematic structures: analysis and synthesis; smart devices; new design; application and prototypes. The book can be used by researchers and engineers in the relevant areas of robotics and mechatronics.

Indoor Navigation Strategies for Aerial Autonomous Systems Pedro Castillo-Garcia, Laura Elena Munoz Hernandez, Pedro Garcia Gil, 2016-11-10 Indoor Navigation Strategies for Aerial Autonomous Systems presents the necessary and sufficient theoretical basis for those interested in working in unmanned aerial vehicles, providing three different approaches to mathematically represent the dynamics of an aerial vehicle. The book contains detailed information on fusion inertial measurements for orientation stabilization and its validation in flight tests, also proposing substantial theoretical and practical validation for improving the dropped or noised signals. In addition, the book contains different strategies to control and navigate aerial systems. The comprehensive information will be of interest to both researchers and practitioners working in automatic control, mechatronics, robotics, and UAVs, helping them improve research and motivating them to build a test-bed for future projects. Provides substantial information on nonlinear control approaches and their validation in flight tests Details in observer-delay schemes that can be applied in real-time Teaches how an IMU is built and how they can improve the performance of their system when applying observers or predictors Improves prototypes with tactics for proposed nonlinear schemes

Security and the Networked Society Mark A. Gregory, David Glance, 2014-07-08 This book examines technological and social events during 2011 and 2012, a period that saw the rise of the hacktivist, the move to mobile platforms, and the ubiquity of social networks. It covers key technological issues such as hacking, cyber-crime, cyber-security and cyber-warfare, the internet, smart phones, electronic security, and information privacy. This book traces the rise into prominence of these issues while also exploring the resulting cultural reaction. The authors' analysis forms the basis of a discussion on future technological directions and their potential impact on society. The book includes forewords by Professor Margaret Gardner AO, Vice-Chancellor and President of RMIT University, and by Professor Robyn Owens, Deputy Vice-Chancellor (Research) at the University of Western Australia. Security and the Networked Society provides a reference for professionals and industry analysts studying digital technologies. Advanced-level students in computer science and electrical engineering will also find this book useful as a thought-provoking resource.

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