

# Accelerometer Values

Frank A. Marcos

**Basic Sensors in IOS** Alasdair Allan,2011-07-29 Programming the accelerometer, gyroscope, camera, and magnetometer--Cover.

**Variability of the Lower Thermosphere Determined from Satellite Accelerometer Data** Frank A. Marcos,1978 An extensive atmospheric density data base has been developed using accelerometer results from four low altitude satellites. The altitude range of the data is from 250 km down to as low as 140 km, with latitude coverage from 90 N to 90 S and local time periods that cover several 24-hr cycles. The data were obtained over a wide range of geomagnetic activity conditions. Solar radiation, as indicated by the 10.7-cm flux, was generally very low. Hence the data base applies mainly to solar minimum conditions. A description of the satellites, the accelerometer experiment, and the data base is given. Density variability is statistically analyzed in relation to selected atmospheric models. Particular attention is given to deviations from a normal distribution. Frequency distribitons of the data are described in terms of the mean value and the second, third, and fourth moments about the mean. This provides a more accurate description of extreme variations. The statistical properties of atmospheric variability are analyzed as a function of geomagnetic activity, latitude, altitude, and local time to develop a quantitative knowledge of unmodeled density variations. The results show that these accelerometer data will permit significant improvement in understanding the variations in the lower thermospheric density.

**Pervasive Computing** Alois Ferscha,Friedemann Mattern,2004-04-07 nd Welcome to the proceedings of PERVASIVE 2004, the 2 International C- ference on Pervasive Computing and the premier forum for the presentation and appraisal of the most recent and most advanced research results in all - undational and applied areas of pervasive and ubiquitous computing. Consi- ring the half-life period of technologies and knowledge this community is facing, PERVASIVE is one of the most vibrant, dynamic, and evolutionary among the computer-science-related symposia and conferences. The research challenges, e?orts, and contributions in pervasive computing have experienced a breathtaking acceleration over the past couple of years, mostly due to technological progress, growth, and a shift of paradigms in c- puter science in general. As for technological advances, a vast manifold of tiny, embedded, and autonomous computing and communication systems have st- ted to create and populate a pervasive and ubiquitous computing landscape, characterized by paradigms like autonomy, context-awareness, spontaneous - teraction, seamless integration, self-organization, ad hoc networking, invisible services, smart artifacts, and everywhere interfaces. The maturing of wireless networking, miniaturized information-processing possibilities induced by novel microprocessor technologies, low-power storage systems, smart materials, and technologies for motors, controllers, sensors, and actuators envision a future computing scenario in which almost every object in our everyday environment will be equipped with embedded processors, wireless communication facilities, and embedded software to perceive, perform, and control a multitude of tasks and functions.

*A Global Thermospheric Density Model Based on Satellite Accelerometer Data* Frank A. Marcos,1982 Measurements from the accelerometer experiments on four low-altitude satellites (S3-1 and Atmosphere Explorer-C, -D, and -E) have been combined to produce an empirical model of the neutral mass density from 140 to 240 km. Data from over a 8000 orbits are analyzed using the least-squares method of multiple linear regression. The resulting model gives density as a function of solar flux (for flux values 60 to 130 units), geomagnetic activity, day of year, local time, latitude and altitude. It provides a more accurate fit to the measured data than other available atmospheric models. Three commonly used models are evaluated by comparison of their predicted density variations with those of this empirical model.

Lower-thermosphere Neutral Density Profiles Derived from Satellite Accelerometer Data F. A. Marcos,J. L. Mendillo,1976 The Cannon Ball II and SPADES satellites carried triaxial accelerometer systems for accurate measurement of neutral atmospheric density. Cannon Ball II was launched 6 August 1971 into a polar elliptic orbit in which the initial perigee was at the extremely low altitude of 132 km. SPADES was launched 11 July 1968 into a polar elliptic orbit in which the initial perigee was at 155 km. The data, analyzed to deduce an average density profile for each satellite for summer conditions in the northern hemisphere, are for the altitude region 135 to 250 km, where measurements have heretofore been extremely sparse. Comparisons were made with recent models and experimental data. These results are intended to be supplemented by those of lower-thermosphere studies now being carried out on accelerometer data from the Atmosphere Explorer satellites and a low-altitude Air Force satellite. Comprehensive analyses of accelerometer data low-altitude satellites will allow accurate modeling of the lower thermosphere. These models are required for improving calculation of the trajectories of Air Force systems vehicles and other spacecraft.

A Global Thermospheric Density Model Based on Satellite Accelerometer Data Frank A. Marcos,1982

The High Resolution Accelerometer Package (HiRAP) Flight Experiment Summary for the First 10 Flights Robert C. Blanchard,1992

Satellite Density Measurements with the Rotatable Calibration Accelerometer (ROCA) Frank A. Marcos,K. S. W. Champion,1979 Satellite accelerometer measurements of atmospheric density have provided significant improvement in our understanding of the structure and dynamics of the lower thermosphere. Derivation of accurate data with this technique requires removal of instrument bias from the total sensor output. The ROCA (Rotatable Calibration Accelerometer) experiment was flown to provide and orbital calibration capability on the three-axis stabilized S3-4 satellite. The ROCA sensitive axis could be operated in either of two orientations selectable by ground command. For density measurement (normal operating mode) the sensitive axis was aligned with the satellite velocity vector. For direct measurement of bias, the sensitive axis was aligned perpendicular to the velocity vector. Utilization of the inflight calibration technique showed a dependence of the bias upon the instrument operating temperature. Removal of the bias-temperature component from the total acceleration signal obtained in the normal operating mode permits derivation of accurate density data. Measurements of atmospheric density were obtained during approximately 600 orbits over a five month period. The resulting ROCA data will be utilized for improved satellite ephemeris computations and for detailed studies of the lower thermosphere, particularly those related to energy inputs at high latitudes. (Author).

Professional Android Sensor Programming Greg Milette,Adam Stroud,2012-05-18 Learn to build human-interactive Android apps, starting with device sensors This book shows Android developers how to exploit the rich set of device sensors—locational, physical (temperature, pressure, light, acceleration, etc.), cameras, microphones, and speech recognition—in order to build fully human-interactive Android applications. Whether providing hands-free directions or checking your blood pressure, Professional Android Sensor Programming shows how to turn possibility into reality. The authors provide techniques that bridge the gap between accessing sensors and putting them to meaningful use in real-world situations. They not only show you how to use the sensor related APIs effectively, they also describe how to use supporting Android OS components to build complete systems. Along the way, they provide solutions to problems that commonly occur when using Android's sensors, with tested, real-world examples. Ultimately, this invaluable resource provides in-depth, runnable code examples that you can then adapt for your own applications. Shows experienced Android developers how to exploit the rich set of Android smartphone sensors to build human-interactive Android apps Explores Android locational and physical sensors (including temperature, pressure, light, acceleration, etc.), as well as cameras, microphones, and speech recognition Helps programmers use the Android sensor APIs, use Android OS components to build complete systems, and solve common problems Includes detailed, functional code that you can adapt and use for your own applications Shows you how to successfully implement real-world solutions using each class of sensors for determining location, interpreting physical sensors, handling images and audio, and recognizing and acting on speech Learn how to write programs for this fascinating aspect of mobile app development with Professional Android Sensor Programming.

**Professional C# 5.0 and .NET 4.5.1** Christian Nagel,Jay Glynn,Morgan Skinner,2014-02-19 Comprehensive, advanced coverage of C# 5.0 and .NET 4.5.1 Whether you're a C# guru or transitioning from C/C++, staying up to date is critical to your success. Professional C# 5.0 and .NET 4.5.1 is your go-to guide for navigating the programming environment for the Windows platform. After a quick refresher of the C# basics, the

team of expert authors dives in to C# 5.0 and updates for NET 4.5.1. Includes: Different behaviors for .NET 4.5.1 and the changes to Visual Studio 2013 Changes to ASP.NET Core, Web Forms, MVC, and Web API Updated Windows 8 deployments and localization, event logs, and data flow Shuffling of ADO.NET Entity Framework Additions to Windows Workflow Foundation New Windows Runtime 2.0 updates

**Event Data Recorder (EDR) Interpretation** Christopher D Armstrong, 2018-11-02 Collision Reconstruction Methodologies - Volume 7A - The last ten years have seen explosive growth in the technology available to the collision analyst, changing the way reconstruction is practiced in fundamental ways. The greatest technological advances for the crash reconstruction community have come in the realms of photogrammetry and digital media analysis. The widespread use of scanning technology has facilitated the implementation of powerful new tools to digitize forensic data, create 3D models and visualize and analyze crash vehicles and environments. The introduction of unmanned aerial systems and standardization of crash data recorders to the crash reconstruction community have enhanced the ability of a crash analyst to visualize and model the components of a crash reconstruction. Because of the technological changes occurring in the industry, many SAE papers have been written to address the validation and use of new tools for collision reconstruction. Collision Reconstruction Methodologies Volumes 1-12 bring together seminal SAE technical papers surrounding advancements in the crash reconstruction field. Topics featured in the series include: • Night Vision Study and Photogrammetry • Vehicle Event Data Recorders • Motorcycle, Heavy Vehicle, Bicycle and Pedestrian Accident Reconstruction The goal is to provide the latest technologies and methodologies being introduced into collision reconstruction - appealing to crash analysts, consultants and safety engineers alike.

*Intelligent Environments 2016* P. Novais, S. Konomi, 2016-10-12 The term Intelligent Environments (IEs) refers to physical spaces in which IT and other pervasive computing technologies are combined and used to achieve specific goals for the user, the environment, or both. The ultimate objective of IEs is to enrich user experience, improve management of the environment in question and increase user awareness. This book presents the proceedings of the following workshops, which formed part of the 12th International Conference on Intelligent Environments (IE16), held in London, UK, in September 2016: the 5th International Workshop on Smart Offices and Other Workplaces (SOOW'16); the 5th International Workshop on the Reliability of Intelligent Environments (WoRIE'16); the 1st International Workshop on Legal Issues in Intelligent Environments (LIIE'2016); the 2nd International Symposium on Future Intelligent Educational Environments and Learning (SOFIEE'16); the 2nd International Workshop on Future Internet and Smart Networks (FI&SN'2016); the International Workshop on Intelligent Environments Supporting Healthcare and Well-being (WISHWell'2016); the International Workshop on Computation Sustainability, Technologies and Applications (CoSTA'2016); the Creative Science 2016 (CS'16) and Cloud-of-Things 2016 (CoT'16); the Workshop on Wireless Body Area Networks for Personal Monitoring in Intelligent Environments (WBAN-PMIE); and the Physical Computing Workshop. The workshops focused on the development of advanced intelligent environments, as well as newly emerging and rapidly evolving topics, emphasizing the multi-disciplinary and transversal aspects of IEs, as well as cutting-edge topics. The book will be of interest to all those whose work involves them in the use of intelligent environments.

**Atmospheric Density Results Derived from the SPADES Satellite Accelerometer Data** Frank A. Marcos, 1972 The report describes density results obtained from the ultrasensitive triaxial accelerometer system flown on the Air Force low-altitude density research satellite OV 1-15 (SPADES). A description of the spacecraft operation, the accelerometers, and the data reduction procedure is also given. The accelerometers measured the satellite deceleration induced by aerodynamic drag. Profiles of the neutral atmospheric density were derived directly from the drag data. Measurements were made from an altitude of 250 km down to perigee, nominally 160 km. Density profiles acquired from 14 July 1968 to 28 September 1968 are presented as Appendix A. Comparison of the density results to the appropriate Jacchia 1971 model atmosphere is given in Appendix B. (Author Modified Abstract).

**NASA Technical Paper**, 1987

**Apache Cordova API Cookbook** John M. Wargo, 2015 Provides experienced mobile developers with details about how each Cordova API works and how to use the APIs in their own applications. Original.

*Application of the Satellite Triaxial Accelerometer Experiment to Atmospheric Density and Wind Studies* Frank A. Marcos, 1982 A new satellite triaxial accelerometer system has been developed. This instrument has been flight-tested on three-axis stabilized satellites and has demonstrated the capability to accurately measure accelerations in the satellite's in-track, cross-track, and radial directions. The in-track data provide direct determination of atmospheric density. These data, obtained during a period of high solar flux, supplement the extensive set of measurements obtained by other accelerometer experiments during low solar flux conditions. The cross-track and radial results permit, for the first time, large-scale measurements of the zonal and, possibly, radial components of neutral atmospheric winds. These simultaneous wind and density data provide an extremely valuable input for the understanding of dynamic processes in the atmosphere and for the improvement of atmospheric models.

*Human-Computer Interaction and Knowledge Discovery in Complex, Unstructured, Big Data* Andreas Holzinger, Gabriella Pasi, 2013-06-26 This book constitutes the refereed proceedings of the Third Workshop on Human-Computer Interaction and Knowledge Discovery, HCI-KDD 2013, held in Maribor, Slovenia, in July 2013, at SouthCHI 2013. The 20 revised papers presented were carefully reviewed and selected from 68 submissions. The papers are organized in topical sections on human-computer interaction and knowledge discovery, knowledge discovery and smart homes, smart learning environments, and visualization data analytics.

**Advanced In-Flight Measurement Techniques** Fritz Boden, Nicholas Lawson, Henk W. Jentink, Jürgen Kompenhans, 2013-02-13 The book presents a synopsis of the main results achieved during the 3 year EU-project Advanced Inflight Measurement Techniques (AIM) which applied advanced image based measurement techniques to industrial flight testing. The book is intended to be not only an overview on the AIM activities but also a guide on the application of advanced optical measurement techniques for future flight testing. Furthermore it is a useful guide for engineers in the field of experimental methods and flight testing who face the challenge of a future requirement for the development of highly accurate non-intrusive in-flight measurement techniques.

*Computer Security - ESORICS 2017* Simon N. Foley, Dieter Gollmann, Einar Snekkenes, 2017-09-01 The two-volume set, LNCS 10492 and LNCS 10493 constitutes the refereed proceedings of the 22nd European Symposium on Research in Computer Security, ESORICS 2017, held in Oslo, Norway, in September 2017. The 54 revised full papers presented were carefully reviewed and selected from 338 submissions. The papers address issues such as data protection; security protocols; systems; web and network security; privacy; threat modeling and detection; information flow; and security in emerging applications such as cryptocurrencies, the Internet of Things and automotive.

*Orbital Bias Determination for Accelerometers on Atmosphere Explorer Satellites* Frank A. Marcos, Robert W. Fioretti, 1977 An extensive amount of neutral density data has been obtained from the highly successful accelerometer experiments on the Atmosphere Explorer -C, -D, and -E satellites. The accelerometer is electrostatically suspended and force rebalanced. Ground calibration requires sufficient suspension force to operate in the earth's 1g field. An important characteristic of the instrument is its null bias which is proportional to the suspension voltage. Null bias error is reduced when the instrument is in orbit by reducing the suspension force. For despun orbit data, accelerations due to bias must be separated from those due to drag for accurate density computation. In the elliptical orbit phase of the AE missions, bias values have been deduced from the sensor output obtained at altitudes where aerodynamic drag is negligible. Bias measurements obtained from all three satellites are summarized. A bias temperature coefficient is also calculated. Results in this report show that orbital values differ from a simple extrapolation of the ground calibration data. This difference must be known to obtain accurate density data above about 200 km. The orbital bias results are applied to improve the accuracy of despun orbit measurements made during both the elliptical and circular orbit phases of the AE mission. Methods of extending bias determination to circular orbit data are discussed. (Author).

In a world defined by information and interconnectivity, the enchanting power of words has acquired unparalleled significance. Their ability to kindle emotions, provoke contemplation, and ignite transformative change is really awe-inspiring. Enter the realm of "Accelerometer Values," a mesmerizing literary masterpiece penned by way of a distinguished author, guiding readers on a profound journey to unravel the secrets and potential hidden within every word. In this critique, we shall delve into the book is central themes, examine its distinctive writing style, and assess its profound effect on the souls of its readers.

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Accelerometer Values Introduction

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